# Tree-graded spaces and asymptotic cones of groups ${ }^{\omega}$ 

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#### Abstract

We introduce a concept of tree-graded metric space and we use it to show quasi-isometry invariance of certain classes of relatively hyperbolic groups, to obtain a characterization of relatively hyperbolic groups in terms of their asymptotic cones, to find geometric properties of Cayley graphs of relatively hyperbolic groups, and to construct the first example of a finitely generated group with a continuum of non- $\pi_{1}$-equivalent asymptotic cones. Note that by a result of Kramer, Shelah, Tent and Thomas, continuum is the maximal possible number of different asymptotic cones of a finitely generated group, provided that the Continuum Hypothesis is true.


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## 1. Introduction

An asymptotic cone of a metric space is, roughly speaking, what one sees when one looks at the space from infinitely far away. More precisely, any asymptotic cone of a metric space ( $X$, dist) corresponds to an ultrafilter $\omega$, a sequence of observation points $e=\left(e_{n}\right)_{n \in \mathbb{N}}$ from $X$ and a sequence of scaling constants $d=\left(d_{n}\right)_{n \in \mathbb{N}}$ diverging to $\infty$. The cone $\operatorname{Con}(X ; e, d)$ corresponding to $e$ and $d$ is the $\omega$-limit of the sequence of spaces with basepoints ( $X, \operatorname{dist} / d_{n}, e_{n}$ ) (see Section 3 for precise definitions).

In particular, if $X$ is the Cayley graph of a group $G$ with a word metric then the asymptotic cones of $X$ are called asymptotic cones of $G$.

The concept of asymptotic cone was essentially used by Gromov in [28] and then formally introduced by van den Dries and Wilkie [54].

Asymptotic cones have been used to characterize important classes of groups:

- A finitely generated group is virtually Abelian if and only if its asymptotic cones are isometric to the Euclidean space $\mathbb{R}^{n}[28,44]$.
- A finitely generated group is virtually nilpotent if and only if its asymptotic cones are locally compact [28,54,25].
- A finitely generated group is hyperbolic if and only if its asymptotic cones are $\mathbb{R}$-trees [30].

In [20] it is shown moreover that asymptotic cones of non-elementary hyperbolic groups are all isometric to the complete homogeneous $\mathbb{R}$-tree of valence continuum. The asymptotic cones of elementary groups are isometric to either a line $\mathbb{R}$ (if the group is infinite) or to a point. In particular, every hyperbolic group has only one asymptotic cone up to isometry.

Asymptotic cones of quasi-isometric spaces are bi-Lipschitz equivalent. Thus the topology of an asymptotic cone of a finitely generated group does not depend on the choice of the generating set. This was used in [33,34] to prove rigidity results for fundamental groups of Haken manifolds, in [37] to prove rigidity for cocompact lattices in higher rank semisimple groups, and in [23] to provide an alternative proof of the rigidity for non-cocompact lattices in higher rank semisimple groups. For a survey of results on quasi-isometry invariants and their relations to asymptotic cones see [25].

The power of asymptotic cones stems from the fact that they capture both geometric and logical properties of the group, since a large subgroup of the ultrapower $G^{\omega}$ of the group $G$ acts transitively by isometries on the asymptotic cone $\operatorname{Con}^{\omega}(G ; e, d)$. Logical aspects of asymptotic cones are studied and used in the recent papers by Kramer et al. [38,39].

One of the main properties of asymptotic cones of a metric space $X$ is that geometry of finite configurations of points in the asymptotic cone reflects the "coarse" geometry of similar finite configurations in $X$. This is the spirit of Gromov-Delzant's approximation statement [19] and of the applications of $\mathbb{R}$-trees to Rips-Sela theory of equations in hyperbolic groups and homomorphisms of hyperbolic groups [48]. This was also used in Druţu's proof of hyperbolicity of groups with sub-quadratic isoperimetric inequality [24].

By a result of Gromov [30] if all asymptotic cones of a finitely presented group are simply connected then the group has polynomial isoperimetric function and linear isodiametric function. Papasoglu proved in [45] that groups having quadratic isoperimetric functions have simply connected asymptotic cones. In general, asymptotic cones of groups are not necessarily simply connected [53]. In fact, if a group $G$ is not finitely presented then its asymptotic cones cannot all be simply connected [30,25]. A higher-dimensional version of this result is obtained by Riley [47]. Examples of finitely presented groups with non-simply connected asymptotic cones can be found in [10,49].

Although asymptotic cones can be completely described in some cases, the general perception is nevertheless that asymptotic cones are usually large and "undescribable". This might be the reason of uncharacteristically "mild" questions by Gromov [30]:

Problem 1.1. Which groups can appear as subgroups in fundamental groups of asymptotic cones of finitely generated groups?

Problem 1.2. Is it true that the fundamental group of an asymptotic cone of a group is either trivial or uncountable?

In [30], Gromov also asked the following question.
Problem 1.3. How many non-isometric asymptotic cones can a finitely generated group have?
A solution of Problem 1.1 was given by Erschler and Osin [26]. They proved that every metric space satisfying some weak properties can be $\pi_{1}$ - and isometrically embedded into the asymptotic cone of a finitely generated group. This implies that every countable group is a subgroup of the fundamental group of an asymptotic cone of a finitely generated group.

Notice that since asymptotic cones tend to have fundamental groups of order continuum, this result does not give information about the structure of the whole fundamental group of an asymptotic cone, or about how large the class of different asymptotic cones is: there exist groups of cardinality continuum (for example, the group of all permutations of a countable set) that contain all countable groups as subgroups. One of the goals of this paper is to get more precise information about fundamental groups of asymptotic cones, and about the whole set of different asymptotic cones of a finitely generated group.

Problem 1.3 turned out to be related to the Continuum Hypothesis (i.e. the question of whether there exists a set of cardinality strictly between $\aleph_{0}$ and $2^{\aleph_{0}}$ ). Namely, in [38], it is proved that if the Continuum Hypothesis is not true then any uniform lattice in $\mathrm{SL}_{n}(\mathbb{R})$ has $2^{2^{\aleph_{0}}}$ non-isometric asymptotic cones, but if the Continuum Hypothesis is true then any uniform lattice in $\mathrm{SL}_{n}(\mathbb{R})$ has exactly one asymptotic cone up to isometry; moreover the maximal theoretically possible number of non-isometric asymptotic cones of a finitely generated group is continuum. Recall that the Continuum Hypothesis is independent of the usual axioms of set theory (ZFC).

It is known, however, that even if the Continuum Hypothesis is true, there exist groups with more than one non-homeomorphic asymptotic cone [52]. Nevertheless, it was not known whether there exists a group with the maximal theoretically possible number of non-isometric asymptotic cones (continuum).

In [29], Gromov introduced a useful generalization of hyperbolic groups, namely the relatively hyperbolic groups. ${ }^{1}$ This class includes:
(1) geometrically finite Kleinian groups; these groups are hyperbolic relative to their cusp subgroups;
(2) fundamental groups of hyperbolic manifolds of finite volume (that is, non-uniform lattices in rank one semisimple groups with trivial center); these are hyperbolic relative to their cusp subgroups;
(3) hyperbolic groups; these are hyperbolic relative to the trivial subgroup or more generally to collections of quasi-convex subgroups satisfying some extra conditions;
(4) free products of groups; these are hyperbolic relative to their factors;
(5) fundamental groups of non-geometric Haken manifolds with at least one hyperbolic component; these are hyperbolic relative to the fundamental groups of the maximal graph-manifold components and to the fundamental groups of the tori and Klein bottles not contained in graph-manifold components [8];
(6) $\omega$-residually free groups (limit groups in another terminology); these are hyperbolic relative to the collection of maximal Abelian non-cyclic subgroups [16].

[^1]There exist several characterizations of relatively hyperbolic groups which are in a sense parallel to the well-known characterizations of hyperbolic groups (see [5,27,43,17,56] and references therein). But there was no characterization in terms of asymptotic cones. Also, it was not known whether being relatively hyperbolic with respect to any kind of subgroups is a quasi-isometry invariant, except for hyperbolic groups when quasi-isometry invariance is true.

The following theorems are the main results of the paper (we formulate these results not in the most general form).

The first theorem gives more information about the possible structure of fundamental groups of asymptotic cones.

Theorem 1.4 (Theorem 7.33 and Corollary 7.32). (1) For every countable group C, the free product of continuously many copies of $C$ is the fundamental group of an asymptotic cone of a 2-generated group.
(2) There exists a 2-generated group $\Gamma$ such that for every finitely presented group $G$, the free product of continuously many copies of $G$ is the fundamental group of an asymptotic cone of $\Gamma$.

The second theorem answers the question about the number of asymptotic cones of a finitely generated group.

Theorem 1.5 (Theorem 7.37). Regardless of whether the Continuum Hypothesis is true or not, there exists a finitely generated group $G$ with continuously many pairwise non- $\pi_{1}$-equivalent asymptotic cones.

The third theorem shows that large classes of relatively hyperbolic groups are closed under quasiisometry. We call a finitely generated group $H$ unconstricted if one of its asymptotic cones has no global cut-points.

Theorem 1.6 (Corollary 5.22). Let $G$ be a finitely generated group that is hyperbolic relative to unconstricted subgroups $H_{1}, \ldots, H_{m}$.

Let $G^{\prime}$ be a group that is quasi-isometric to $G$. Then $G^{\prime}$ is hyperbolic relative to subgroups $H_{1}^{\prime}, \ldots, H_{n}^{\prime}$, each of which is quasi-isometric to one of $H_{1}, \ldots, H_{m}$.

The number $m$ of "parabolic" subgroups $\left\{H_{i}\right\}_{i \in I}$ in Theorem 1.6 is not a quasi-isometry invariant. This can be seen for instance for the fundamental groups of a finite-volume hyperbolic manifold and of a finite covering of it.

There are previous results showing that some special classes of relatively hyperbolic groups are closed under quasi-isometry: the class of fundamental groups of non-geometric Haken manifolds with at least one hyperbolic component $[33,34]$ and the class of non-uniform lattices of isometries of a rank one symmetric space [50]. The class of free products of groups with finite amalgamated subgroups is closed under quasi-isometry by Stallings' Ends Theorem (see [46] for more general results about graphs of groups with finite edge groups).

The main ingredient in the proof of Theorem 1.6 is the following result, interesting by itself.
Theorem 1.7 (Corollary 5.8). Let $G$ be a finitely generated group that is hyperbolic relative to subgroups $H_{1}, \ldots, H_{m}$, and let $G^{\prime}$ be an unconstricted group. Then the image of $G^{\prime}$ under any ( $L, C$ )-quasi-isometry $G^{\prime} \rightarrow G$ is in an $M$-tubular neighborhood of a coset $g H_{i}, g \in G, i=1, \ldots, m$, where $M$ depends on $L, C, G$ and $S$ only.

Note that the hypothesis of Theorem 1.7 that the group $G$ is unconstricted clearly cannot be removed. For example, a relatively hyperbolic group itself is not in a bounded neighborhood of a coset of any of its "parabolic" subgroups $H_{i}$ provided $H_{i}$ are proper subgroups.

Theorem 1.7 does not apply in this case because relatively hyperbolic groups are usually constricted, i.e. they have global cut-points in every asymptotic cone (see Theorem 1.11).

A result similar to Theorem 1.7 is obtained in [46, Section 3] for $G$ a fundamental group of a graph of groups with finite edge groups and $S$ a one-ended group. We should note here that unconstricted groups are 1 -ended by Stallings' Ends Theorem. The converse statement is most likely not true because the asymptotic cones of any hyperbolic group are $\mathbb{R}$-trees.

Theorem 1.7 in particular gives information about which unconstricted subgroups can appear as undistorted subgroups in a relatively hyperbolic group (see Remark 8.30(1)). The following theorem clarifies even more the question of the structure of undistorted subgroups in relatively hyperbolic groups.

Theorem 1.8 (Theorem 8.29). Let $G=\langle S\rangle$ be a finitely generated group that is hyperbolic relative to subgroups $H_{1}, \ldots, H_{n}$. Let $G^{\prime}$ be an undistorted finitely generated subgroup of $G$. Then $G^{\prime}$ is relatively hyperbolic with respect to subgroups $H_{1}^{\prime}, \ldots, H_{m}^{\prime}$, where each $H_{i}^{\prime}$ is one of the intersections $G^{\prime} \cap g H_{j} g^{-1}$, $g \in G, j \in\{1,2, \ldots, n\}$.

We also obtain information about the automorphism group of a relatively hyperbolic group.
Theorem 1.9 (Corollary 8.31). Let $G$ be a finitely generated group that is relatively hyperbolic with respect to a unconstricted subgroup $H$. Let $\operatorname{Fix}(H)$ be the subgroup of the automorphism group of $G$ consisting of the automorphisms that fix $H$ as a set. Then:
(1) $\operatorname{Inn}(G) \operatorname{Fix}(H)=\operatorname{Aut}(G)$.
(2) $\operatorname{Inn}(G) \cap \operatorname{Fix}(H)=\operatorname{Inn}_{H}(G)$, where $\operatorname{Inn}_{H}(G)$ is by definition $\left\{i_{h} \in \operatorname{Inn}(G) \mid h \in H\right\}$.
(3) There exists a natural homomorphism from $\operatorname{Out}(G)$ to $\operatorname{Out}(H)$ given by $\left.\phi \mapsto i_{g_{\phi}} \phi\right|_{H}$, where $g_{\phi}$ is an element of $G$ such that $i_{g_{\phi}} \phi \in \operatorname{Fix}(H)$, and $\left.\psi\right|_{H}$ denotes the restriction of an automorphism $\psi \in \operatorname{Fix}(H)$ to $H$.

We call a finitely generated group wide if none of its asymptotic cones has a global cut-point. Wide groups are certainly unconstricted (the converse statement is most likely not true).

Here are examples of wide groups:

- Non-virtually cyclic groups satisfying a law (see Corollary 6.13). Recall that a law is a word $w$ in $n$ letters $x_{1}, \ldots, x_{n}$ and a group satisfying the law $w$ is a group $G$ such that $w=1$ in $G$ whenever $x_{1}, \ldots, x_{n}$ are replaced by an arbitrary set of $n$ elements in $G$. For instance Abelian groups are groups with the law $w=x_{1} x_{2} x_{1}^{-1} x_{2}^{-1}$. More generally, solvable groups are groups with a law, and so are Burnside groups. Also, uniformly amenable groups are groups satisfying a law (see Corollary 6.16). While for nilpotent groups the results of Theorems 1.6 and 1.7 are not surprising and were already known in some particular cases of relatively hyperbolic groups [50], for solvable non-nilpotent groups and for Burnside groups the situation is different. For instance the group Sol has asymptotic cones composed of continuously many Hawaiian earrings [13], so it is a priori not clear why such a group should have a rigid behavior with respect to quasi-isometric embeddings into relatively hyperbolic groups. Burnside groups display a similar picture.

In the case of non-virtually cyclic groups with a law, the constant $M$ in Theorem 1.7 depends only on the law and not on the group $S$ (Corollary 6.14).

- Non-virtually cyclic groups with elements of infinite order in the center (see Theorem 6.5); the constant $M$ in Theorem 1.7 is the same for the whole class of such groups (Theorem 6.7 and Corollary 6.8).
- Groups of isometries acting properly discontinuously and with compact quotients on products of symmetric spaces and Euclidean buildings, of rank at least two. The asymptotic cones of such groups are Euclidean buildings of rank at least two [37]. Most likely the same is true for such groups of isometries so that the quotients have finite volume, but the proof of this statement is not straightforward.

The main tool in this paper are tree-graded spaces.
Definition 1.10. Let $\mathbb{F}$ be a complete geodesic metric space and let $\mathscr{P}$ be a collection of closed geodesic subsets (called pieces). Suppose that the following two properties are satisfied:
$\left(T_{1}\right)$ Every two different pieces have at most one common point.
$\left(T_{2}\right)$ Every simple geodesic triangle (a simple loop composed of three geodesics) in $\mathbb{F}$ is contained in one piece.

Then we say that the space $\mathbb{F}$ is tree-graded with respect to $\mathscr{P}$.
The main interest in the notion of tree-graded space resides in the following characterization of relatively hyperbolic groups of which the converse part is proven in Section 8 and the direct part in the Appendix written by Osin and Sapir.

Theorem 1.11 (Theorem 8.5). A finitely generated group $G$ is relatively hyperbolic with respect to finitely generated subgroups $H_{1}, \ldots, H_{n}$ if and only if every asymptotic cone $\operatorname{Con}^{\omega}(G ; e, d)$ is tree-graded with respect to $\omega$-limits of sequences of cosets of the subgroups $H_{i}$.

Section 2 contains many general properties of tree-graded spaces.
In particular, by Lemma 2.31 any complete homogeneous geodesic metric space with global cut-points is tree-graded with respect to a certain uniquely defined collection of pieces which are either singletons or without cut-points.

We prove in Proposition 2.17 that the property $\left(T_{2}\right)$ in the definition of tree-graded spaces can be replaced by the assumption that $\mathscr{P}$ covers $\mathbb{F}$ and the following property which can be viewed as a extreme version of the bounded coset penetration property:
$\left(T_{2}^{\prime}\right) \quad$ For every topological arc $\mathfrak{c}:[0, d] \rightarrow \mathbb{F}$ and $t \in[0, d]$, let $\mathfrak{c}[t-a, t+b]$ be a maximal sub-arc of $\mathfrak{c}$ containing $\mathfrak{c}(t)$ and contained in one piece. Then every other topological arc with the same endpoints as $\mathfrak{c}$ must contain the points $\mathfrak{c}(t-a)$ and $\mathfrak{c}(t+b)$.

Moreover, when $\left(T_{2}\right)$ is replaced by $\left(T_{2}^{\prime}\right)$ the condition that the pieces are geodesic can be weakened to the one that pieces are arc-connected. Here by arc-connected we mean the property that two points can be joined by a topological arc. Thus, if we moreover replace the hypothesis of the space being geodesic by the one that it is arc-connected, tree-graded spaces can be considered in a purely topological setting. Most of the properties and arguments in Section 2 hold in this more general setting.

Notice that there are similarities in the study of asymptotic cones of groups and that of boundaries of groups. Boundaries of groups do not necessarily have a natural metric, and rarely are arc-connected spaces, but they have a natural topology and they are also, in many interesting cases, homogeneous spaces with respect to actions by homeomorphisms. Thus, if the boundary of a group is homogeneous and has a global cut-point then most likely it is tree-graded (in the topological sense) with respect to pieces that do not have cut-points. Such a study of boundaries of groups with global cut-points appeared, for example, in the work of Bowditch [6] on the Bestvina-Mess conjecture. Bowditch developed a general theory appropriate for the study of topological homogeneous spaces with global cut-points that is related to the study of tree-graded spaces that we do in this paper. Results related to Bowditch's work in this general setting can be found in [1].

As a byproduct of the arguments in Sections 4 and 8, we obtain many facts about the geometry of Cayley graphs of relatively hyperbolic groups. Recall that given a finitely generated group $G=\langle S\rangle$ and a finite collection $H_{1}, \ldots, H_{n}$ of subgroups of it, one can consider the standard Cayley graph Cayley $(G, S)$ and the modified Cayley graph Cayley $(G, S \cup \mathscr{H})$, where $\mathscr{H}=\bigsqcup_{i=1}^{n}\left(H_{i} \backslash\{e\}\right)$. The standard definition of relative hyperbolicity of a group $G$ with respect to subgroups $H_{1}, \ldots, H_{n}$ is given in terms of the modified Cayley graph Cayley $(G, S \cup \mathscr{H})$. Theorem 1.11 and the results of Section 4 allow us to define the relative hyperbolicity of $G$ with respect to $H_{1}, \ldots, H_{n}$ in terms of Cayley $(G, S)$ only. This is an important ingredient in our rigidity results.

An important part in studying tree-graded spaces is played by saturations of geodesics. If $G$ is relatively hyperbolic with respect to $H_{1}, \ldots, H_{n}, \mathfrak{g}$ is a geodesic in Cayley $(G, S)$ and $M$ is a positive number, then the $M$-saturation of $\mathfrak{g}$ is the union of $\mathfrak{g}$ and all left cosets of $H_{i}$ whose $M$-tubular neighborhoods intersect $\mathfrak{g}$. We show that in the study of relatively hyperbolic groups, saturations play the same role as the geodesics in the study of hyperbolic groups.

More precisely, we use Bowditch's characterization of hyperbolic graphs [7], and show that tubular neighborhoods of saturations of geodesics can play the role of "lines" in that characterization. In particular, we show that for every geodesic triangle $[A, B, C]$ in Cayley $(G, S)$ the $M$-tubular neighborhoods of the saturations of its sides (for some $M$ depending on $G$ and $S$ ) have a common point which is at a bounded distance from the sides of the triangle or a common left coset which is at a bounded distance from the sides.

We also obtain the following analog for relatively hyperbolic groups of the Morse lemma for hyperbolic spaces. Recall that the Morse lemma states that every quasi-geodesic in a hyperbolic space is at a bounded distance from a geodesic joining its endpoints. In the relative hyperbolic version of the lemma we also use the notion of lift $\tilde{\mathfrak{p}}$ of a geodesic $\mathfrak{p}$ in $\operatorname{Cayley}(G, S \cup \mathscr{H})$. Recall that the meaning of it is that one replaces each edge in $\mathfrak{p}$ labelled by an element in $\mathscr{H}$ by a geodesic in Cayley $(G, S$ ) (see also Definition 8.26).

We again do not write the statements in the whole generality.
Notations. Throughout the paper, $\mathscr{N}_{\delta}(A)$ denotes the $\delta$-tubular neighborhood of a subset $A$ in a metric space $X$, that is $\{x \in X \mid \operatorname{dist}(x, A)<\delta\}$. We denote by $\bar{N}_{\delta}(A)$ its closure, that is $\{x \mid \operatorname{dist}(x, A) \leqslant \delta\}$. In the particular case when $A=\{x\}$ we also use the notations $B(x, \delta)$ and $\bar{B}(x, \delta)$ for the tubular neighborhood and its closure.

Theorem 1.12 (Morse property for relatively hyperbolic groups). Let $G=\langle S\rangle$ be a group that is hyperbolic relative to the collection of subgroups $H_{1}, \ldots, H_{m}$. Then there exists a constant $M$ depending only on the
generating set $S$ such that the following holds. Let $\mathfrak{g}$ be a geodesic in Cayley ( $G, S$ ), let $\mathfrak{q}$ be an ( $L, C$ )-quasi-geodesic in Cayley $(G, S)$ and let $\mathfrak{p}$ be an $(L, C)$-quasi-geodesic in Cayley $(G, S \cup \mathscr{H})$. Suppose that $\mathfrak{g}, \mathfrak{q}$ and $\mathfrak{p}$ have the same endpoints. Then for some $\tau$ depending only on $L, C, S$ :
(1) $\mathfrak{q}$ is contained in the $\tau$-tubular neighborhood of the $M$-saturation of $\mathfrak{g}$.
(2) Let $g H_{i}$ and $g^{\prime} H_{j}$ be two left cosets contained in the $M$-saturation of $\mathfrak{g}$. Let $\mathfrak{q}^{\prime}$ be a sub-quasi-geodesic of $\mathfrak{q}$ with endpoints $a \in \mathscr{N}_{\kappa}\left(g H_{i}\right)$ and $b \in \mathscr{N}_{\kappa}\left(g^{\prime} H_{j}\right)$ which intersects $\mathscr{N}_{\kappa}\left(g H_{i}\right)$ and $\mathscr{N}_{\kappa}\left(g^{\prime} H_{j}\right)$ in sets of bounded (in terms of $\kappa$ ) diameter. Then a and $b$ belong to the $\delta$-tubular neighborhood of $\mathfrak{g}$, where $\delta$ depends only on $L, C, \kappa$.
(3) In the Cayley graph Cayley $(G, S \cup \mathscr{H})$, $\mathfrak{q}$ is at Hausdorff distance at most $\tau$ from $\mathfrak{p}$.
(4) In Cayley $(G, S), \mathfrak{q}$ is contained in the $\tau$-tubular neighborhood of the $\tau$-saturation of any lift $\tilde{\mathfrak{p}}$ of $\mathfrak{p}$. In its turn, $\tilde{\mathfrak{p}}$ is contained in the $\tau$-tubular neighborhood of the $\tau$-saturation of $\mathfrak{q}$.

The proof of this theorem and more facts about the geometry of relatively hyperbolic groups are contained in Lemmas 4.25, 4.26 and 4.28, and Propositions 8.25 and 8.28.

Theorem 1.11 and statements about tree-graded spaces from Section 2 imply that for relatively hyperbolic groups, Problem 1.2 has a positive answer.

Corollary 1.13. The fundamental group of an asymptotic cone of a relatively hyperbolic group $G$ is either trivial or of order continuит.

Proof. Suppose that the fundamental group of an asymptotic cone of the group $G$ is non-trivial. By Theorem 1.11, the asymptotic cone of $G$ is tree-graded with respect to a set of pieces that are isometric copies of asymptotic cones of the parabolic subgroups $H_{i}$ with the induced metric. The induced metric on each $H_{i}$ is equivalent to the natural word metric by quasi-convexity (see Lemma 4.15). Moreover, in that set, every piece appears together with continuously many copies.

The argument in the first part of the proof of Proposition 2.22 shows that at least one of the pieces has non-trivial fundamental group $\Gamma$.

The argument in the second part of the proof of Proposition 2.22 implies that the fundamental group of the asymptotic cone of $G$ contains the free product of continuously many copies of $\Gamma$.

The following statement is another straightforward consequence of Theorem 1.11.
Corollary 1.14. If a group $G$ is hyperbolic relative to $\left\{H_{1}, \ldots, H_{m}\right\}$, and each $H_{i}$ is hyperbolic relative to a collection of subgroups $\left\{H_{i}^{1}, \ldots, H_{i}^{n_{i}}\right\}$ then $G$ is hyperbolic relative to $\left\{H_{i}^{j} \mid i \in\{1, \ldots, m\}, j \in\right.$ $\left.\left\{1, \ldots, n_{i}\right\}\right\}$.

See Problem 1.21 below for a discussion of Corollary 1.14.
Note that in the alternative geometric definition of relatively hyperbolic groups given in Theorem 1.11 we do not need the hypothesis that $H_{i}$ are finitely generated. This follows from the quasi-convexity of the groups $H_{i}$ seen as sets in Cayley $(G, S)$ (Lemma 4.15). Moreover, this geometric definition makes sense when $G$ is replaced by a geodesic metric space $X$ and the collection of cosets of the subgroups $H_{i}$ is replaced by a collection $\mathscr{A}$ of subsets of $X$. A similar generalization can be considered for Farb's definition of relative hyperbolicity (including the BCP condition). Thus, both definitions allow to speak of geodesic spaces hyperbolic relative to families of subsets. Such spaces, completely unrelated to groups, do appear
naturally. For instance the complements of unions of disjoint open horoballs in rank one symmetric spaces are hyperbolic with respect to the boundary horospheres. Also, the free product of two metric spaces with basepoints $\left(X, x_{0}\right)$ and ( $Y, y_{0}$ ), as defined in [46, Section 1], is hyperbolic with respect to all the isometric copies of $X$ and $Y$. It might be interesting for instance to study actions of groups on such spaces, hyperbolic with respect to collections of subsets. To some extent, this is already done in the proof of our Theorem 5.13, where a particular case of action of a group by quasi-isometries on an asymptotically tree-graded ( = relatively hyperbolic) space is studied.

Bowditch's characterization of hyperbolic graphs can be easily generalized to arbitrary geodesic metric spaces. So one can expect that an analog of Theorem 1.11 is true for arbitrary geodesic metric spaces.

### 1.1. Open problems

Problem 1.15. Is it possible to drop the condition that $H_{i}$ are unconstricted from the formulation of Theorem 1.6?

An obvious candidate to a counterexample would be, for instance, the pair of groups $G=A * A * A * A$, where $A=\mathbb{Z}^{2}$, and $G^{\prime}=(A * A * A * A) \rtimes \mathbb{Z} / 4 \mathbb{Z}$, where $\mathbb{Z} / 4 \mathbb{Z}$ permutes the factors. The group $G$ is relatively hyperbolic with respect to $A * A * 1 * 1$ and $1 * 1 * A * A$. It is easy to check that the group $G^{\prime}$ is not relatively hyperbolic with respect to any isomorphic copy of $A * A$. Unfortunately this example does not work. Indeed, $G^{\prime}$ is quasi-isometric to $A * A$ by [46], so $G^{\prime}$ is relatively hyperbolic with respect to a subgroup that is quasi-isometric to $A * A$, namely itself. Moreover, it is most likely that $G^{\prime}$ is hyperbolic relative to a proper subgroup isomorphic to $A * \mathbb{Z}$ which is also quasi-isometric to $A * A$ by [46].

Problem 1.16. Corollary 5.24 shows the following. Let $G$ be a group, asymptotically tree-graded as a metric space with respect to a family of subspaces $\mathscr{A}$ satisfying the following conditions:
(1) $\mathscr{A}$ is uniformly unconstricted (see Definition 5.4 for the notion of collection of metric spaces uniformly unconstricted);
(2) there exists a constant $c$ such that every point in every $A \in \mathscr{A}$ is at distance at most $c$ from a bi-infinite geodesic in $A$
(3) for a fixed $x_{0} \in G$ and every $R>0$ the ball $B\left(x_{0}, R\right)$ intersects only finitely many $A \in \mathscr{A}$.

Then the group $G$ is relatively hyperbolic with respect to subgroups $H_{1}, \ldots, H_{m}$ such that every $H_{i}$ is quasi-isometric to some $A \in \mathscr{A}$.

Can one remove some of the conditions (1), (2), (3) from this statement?
Problem 1.17. Is every unconstricted group wide?
Problem 1.18. Is every constricted group $G$ relatively hyperbolic with respect to a collection of proper subgroups $\left\{H_{1}, \ldots, H_{m}\right\}$ ? Here are some more specific questions. Consider the canonical representation of every asymptotic cone as a tree-graded space (with respect to maximal path-connected subsets that are either singletons or without global cut-points, as in Lemma 2.31). Is there a family of subsets $\mathscr{A}$ of $G$ such that each piece in each asymptotic cone of $G$ is an ultralimit of a sequence of sets from $\mathscr{A}$ ? Can one take $\mathscr{A}$ to be the set of all left cosets of a (finite) collection of subgroups $\left\{H_{1}, \ldots, H_{m}\right\}$ ?

Note that a positive answer to Problem 1.18 gives a positive answer to Problem 1.15, as being constricted is a quasi-isometry invariant. Also, it would follow that the rigidity result Theorem 1.7 holds as soon as $G^{\prime}$ is not relatively hyperbolic.

Here is a related question.
Problem 1.19. Is every non-virtually cyclic group without free non-abelian subgroups wide (unconstricted)? Is there a non-virtually cyclic constricted group with all proper subgroups cyclic?

It is easy to notice that in all examples of groups with different asymptotic cones $\operatorname{Con}^{\omega}(G ; e, d)$, one of the cones corresponds to a very fast growing sequence $d=\left(d_{n}\right)$. Equivalently, we can assume that $d_{n}=n$ but $\omega$ contains some fast growing sequence of natural numbers $A=\left\{a_{1}, a_{2}, \ldots\right\}$. What if we avoid such ultrafilters? For example, let $\mathscr{P}$ be the set of all complements of finite sets and of all complements of sequences $A=\left\{a_{1}, a_{2}, \ldots, a_{n}, \ldots\right\}\left(a_{1}<a_{2}<\cdots<a_{n}<\cdots\right)$ which grow faster than linear i.e. $\lim \left(a_{n} / n\right)=\infty$. It is easy to see that $\mathscr{P}$ is a filter. Let $\omega$ be an ultrafilter containing $\mathscr{P}$. Then no set in $\omega$ grows faster than linear. Let us call ultrafilters with that property slow. An asymptotic cone $\operatorname{Con}^{\omega}(G,(n))$ corresponding to a slow ultrafilter also will be called slow.

Problem 1.20. Are there finitely generated groups $G$ with two bi-Lipschitz non-equivalent slow asymptotic cones? Is it true that if a slow asymptotic cone of $G$ has (resp. has no) global cut-points then the group is constricted (resp. wide)? Is it true that if a slow asymptotic cone of $G$ has global cut-points then $G$ contains non-abelian free subgroups?

See Section 6.2 for further discussion of free subgroups of wide (unconstricted) groups.
The next problem is motivated by Corollary 1.14 above.
Problem 1.21. By Corollary 1.14, one can consider a "descending process", finding smaller and smaller subgroups of a (finitely generated) group $G$ with respect to which $G$ is relatively hyperbolic. Does this process always stop? Does every group $G$ contain a finite collection of unconstricted subgroups with respect to which $G$ is relatively hyperbolic?

Problem 1.22. A group $G=\langle S\rangle$ is weakly hyperbolic relative to subgroups $H_{1}, \ldots, H_{n}$ if the Cayley graph Cayley ( $G, S \cup \mathscr{H}$ ) is hyperbolic. It would be interesting to investigate the behavior of weak relatively hyperbolic groups up to quasi-isometry. In particular, it would be interesting to find out if an analog of Theorem 1.6 holds. The arguments used in this paper for the (strong) relative hyperbolicity no longer work. This can be seen on the example of $\mathbb{Z}^{n}$. That group is weakly hyperbolic relative to $\mathbb{Z}^{n-1}$. But a quasi-isometry $\mathfrak{q}: \mathbb{Z}^{n} \rightarrow \mathbb{Z}^{n}$ can transform left cosets of $\mathbb{Z}^{n-1}$ into polyhedral or even more complicated surfaces (see [37, Introduction] for examples). Nevertheless it is not a real counter-example to a theorem similar to Theorem 1.6 for weak hyperbolic groups, as every group quasi-isometric to $\mathbb{Z}^{n}$ is virtually $\mathbb{Z}^{n}$.

### 1.2. Plan of the paper

In Section 2, we establish some basic properties of tree-graded spaces. In particular, we show that tree-graded spaces behave "nicely" with respect to homeomorphisms.

In Section 3, we establish general properties of asymptotic cones and their ultralimits. We show that the ultralimit of a sequence of asymptotic cones of a metric space $X$ is an asymptotic cone of $X$ itself.

In Section 4, we give an "internal" characterization of asymptotically tree-graded metric spaces, i.e. pairs of a metric space $X$ and a collection of subsets $\mathscr{A}$, such that every asymptotic cone $\operatorname{Con}^{\omega}(X ; e, d)$ is tree-graded with respect to $\omega$-limits of sequences of sets from $\mathscr{A}$.

In Section 5, we show that being asymptotically tree-graded with respect to a family of subsets is a quasi-isometry invariant. This implies Theorem 1.6.

In Section 6, we show that asymptotic cones of a non-virtually cyclic group do not have cut-points provided the group either has an infinite cyclic central subgroup, or satisfies a law.

In Section 7, we modify a construction from the paper [26] to prove, in particular, Theorems 1.4 and 1.5 .

In Section 8 and in the Appendix (written by Osin and Sapir), we prove the characterization of relatively hyperbolic groups in terms of their asymptotic cones given in Theorem 1.11. Theorem 1.8 about undistorted subgroups of relatively hyperbolic groups is also proved in Section 8.

## 2. Tree-graded spaces

### 2.1. Properties of tree-graded spaces

Let us recall the definition of tree-graded spaces. We say that a subset $A$ of a geodesic metric space $X$ is a geodesic subset if every two points in $A$ can be connected by a geodesic contained in $A$.

Definition 2.1 (tree-graded spaces). Let $\mathbb{F}$ be a complete geodesic metric space and let $\mathscr{P}$ be a collection of closed geodesic subsets (called pieces). Suppose that the following two properties are satisfied:
$\left(T_{1}\right)$ Every two different pieces have at most one common point.
$\left(T_{2}\right)$ Every simple geodesic triangle (a simple loop composed of three geodesics) in $\mathbb{F}$ is contained in one piece.

Then we say that the space $\mathbb{F}$ is tree-graded with respect to $\mathscr{P}$.
Remark 2.2 (degenerate triangles). We assume that a point is a geodesic triangle composed of geodesics of length 0 . Thus $\left(T_{2}\right)$ implies that the pieces cover $\mathbb{F}$.

The next several lemmas establish some useful properties of tree-graded spaces. Until Proposition 2.17, $\mathbb{F}$ is a tree-graded space with respect to $\mathscr{P}$.

Lemma 2.3. If all pieces in $\mathscr{P}$ are $\mathbb{R}$-trees then $\mathbb{F}$ is an $\mathbb{R}$-tree.
Proof. It is an immediate consequence of $\left(T_{2}\right)$.
Lemma 2.4. Let $M$ be a piece and $x$ a point outside $M$. If $y$ and $z$ are points in $M$ such that there exist geodesics $[x, y]$ and $[x, z]$, joining them to $x$ which intersect $M$ only in $y$ and $z$, respectively, then $y=z$.

Proof. Suppose that $y \neq z$. Join $y$ and $z$ by a geodesic $[y, z]$ in $M$. Let $x^{\prime}$ be the farthest from $x$ intersection point of the geodesics $[x, y]$ and $[x, z]$. The triangle $x^{\prime} y z$ is simple because by the assumption $[x, y] \cup[x, z]$
intersects with $[y, z]$ only in $y$ and $z$. Therefore that triangle is contained in one piece $M^{\prime}$ by $\left(T_{2}\right)$. Since $M \cap M^{\prime}$ contains $[y, z], M=M^{\prime}$ by $\left(T_{1}\right)$, so $x^{\prime} \in M$, a contradiction since $x^{\prime}$ belongs both to $[x, y]$ and to $[x, z]$ but cannot coincide with both $y$ and $z$ at the same time.

Lemma 2.5. Every simple quadrangle (i.e. a simple loop composed of four geodesics) in $\mathbb{F}$ is contained in one piece.

Proof. Let $A_{1}, A_{2}, A_{3}$ and $A_{4}$ be the vertices of the quadrangle. Suppose that each vertex is not on a geodesic joining its neighbors, otherwise we have a geodesic triangle and the statement is trivial. Let $\mathfrak{g}$ be a geodesic joining $A_{1}$ and $A_{3}$. Let $P$ be its last intersection point with $\left[A_{1}, A_{2}\right] \cup\left[A_{1}, A_{4}\right]$. Suppose that $P \in\left[A_{1}, A_{2}\right]$ (the other case is symmetric). Let $Q$ be the first intersection point of $\mathfrak{g}$ with $\left[A_{2}, A_{3}\right] \cup\left[A_{3}, A_{4}\right]$. Replace the arc of $\mathfrak{g}$ between $A_{1}$ and $P$ with the arc of $\left[A_{1}, A_{2}\right]$ between these two points, and the arc of $g$ between $Q$ and $A_{3}$ with the corresponding arc of $\left[A_{2}, A_{3}\right] \cup\left[A_{3}, A_{4}\right]$. Then $g$ thus modified cuts the quadrangle into two simple triangles having in common the geodesic [ $P, Q$ ]. Both triangles are in the same piece by $\left(T_{2}\right)$, and so is the quadrangle.

Lemma 2.6. (1) Each piece is a convex subset of $\mathbb{F}$.
(2) For every point $x \in \mathbb{F}$ and every piece $M \in \mathscr{P}$, there exists a unique point $y \in M$ such that $\operatorname{dist}(x, M)=\operatorname{dist}(x, y)$. Moreover, every geodesic joining $x$ with a point of $M$ contains $y$.

Proof. (1) Suppose that there exists a geodesic $\mathfrak{g}$ joining two points of $M$ and not contained in $M$. Let $z$ be a point in $\mathfrak{g} \backslash M$. Then $z$ is on a sub-arc $\mathfrak{g}^{\prime}$ of $\mathfrak{g}$ intersecting $M$ only in its endpoints, $a, b$. Lemma 2.4 implies $a=b=z \in M$, a contradiction.
(2) Let $y_{n} \in M$ be such that $\lim _{n \rightarrow \infty} \operatorname{dist}\left(x, y_{n}\right)=\operatorname{dist}(x, M)$. Since $M$ is closed, we may suppose that every geodesic $\left[x, y_{n}\right]$ intersects $M$ only in $y_{n}$. It follows by Lemma 2.4 that $y_{1}=y_{2}=\cdots=y$.

Let $z \in M$ and let $\mathfrak{g}$ be a geodesic joining $z$ with $x$. Let $z^{\prime}$ be the last point on $\mathfrak{g}$ contained in $M$. Then $z^{\prime}=y$, by Lemma 2.4.

Definition 2.7. We call the point $y$ in part (2) of Lemma 2.6 the projection of $x$ onto the piece $M$.
Lemma 2.8. Let $M$ be a piece and $x$ a point outside it with $\operatorname{dist}(x, M)=\delta$, and let $y$ be the projection of $x$ onto $M$. Then the projection of every point $z \in \bar{B}(x, \delta)$ onto $M$ is equal to $y$.

Proof. Notice that by part (2) of Lemma $2.6 \bar{B}(x, \delta) \cap M=\{y\}$. Suppose that the projection $z^{\prime}$ of $z \in B(x, \delta)$ onto $M$ is different from $y$. Then $z \neq y$; hence $z$ does not belong to $M$.

Consider a geodesic quadrangle with vertices $x, z, z^{\prime}$ and $y$. By the definition of projection, the interiors of $\left[z, z^{\prime}\right] \cup[x, y]$ and $\left[y, z^{\prime}\right]$ do not intersect.

If there is a common point $p$ of $[x, y]$ and $\left[z, z^{\prime}\right]$ then we get a contradiction with Lemma 2.4 , so $[x, y]$ and $\left[z, z^{\prime}\right]$ are disjoint. In particular $\left[z, z^{\prime}\right] \cup\left[z^{\prime}, y\right] \cup[y, x]$ is a topological arc. Since $z \in \bar{B}(x, \delta) \backslash\{y\}$, the side $[x, z]$ of this quadrangle does not intersect $M$. By part (1) of Lemma 2.6 it follows that $[x, z]$ does not intersect $\left[y, z^{\prime}\right]$.

We can replace if necessary $z$ with the last intersection point of $[z, x]$ with $\left[z, z^{\prime}\right]$ and $x$ with the last intersection point of the geodesics $[x, y]$ and $[x, z]$. We get a simple geodesic quadrangle $x z z^{\prime} y$ in which the side $[x, z]$ possibly reduces to a point. By Lemma 2.5, it belongs to one piece. Since it has $\left[y, z^{\prime}\right]$ in common with $M$, that piece is $M$ by $\left(T_{1}\right)$. But this contradicts the fact that $[x, z] \cap M=\emptyset$.

Corollary 2.9. Every continuous path in $\mathfrak{F}$ which intersects a piece $M$ in at most one point projects onto $M$ in a unique point.

Proof. If the path does not intersect the piece, it suffices to cover it with balls of radius less than the distance from the path to the piece and use Lemma 2.8.

If the path intersects $M$ in a point $x$, we may suppose that $x$ is one of its ends and that the interior of the path does not pass through $x$. Let $z$ be another point on the path and let $y$ be its projection onto $M$. By the previous argument every point $t$ on the path, $t \neq x$, has the same projection $y$ onto $M$. Let $\lim _{n \rightarrow \infty} t_{n}=x, t_{n} \neq x$. Then $\lim _{n \rightarrow \infty} \operatorname{dist}\left(t_{n}, M\right)=\lim _{n \rightarrow \infty} \operatorname{dist}\left(t_{n}, y\right)=0$. Therefore $x=y$.

Corollary 2.10. (1) Every topological arc in $\mathbb{F}$ joining two points in a piece is contained in the piece.
(2) Every non-empty intersection between a topological arc in $\mathbb{F}$ and a piece is a point or a sub-arc.

Proof. (1) If there exists a topological arc $\mathfrak{p}$ in $\mathbb{F}$ joining two points of a piece $M$ and not contained in $M$, then a point $z$ in $\mathfrak{p} \backslash M$ is on a sub-arc $\mathfrak{p}^{\prime}$ of $\mathfrak{p}$ intersecting $M$ only in its endpoints, $a, b$. Corollary 2.9 implies that both $a$ and $b$ are projections of $z$ into $M$, contradiction.
(2) immediately follows from (1).

Corollary 2.11. Let A be a connected subset (possibly a point) in $\mathbb{F}$ which intersects a piece $M$ in at most one point.
(1) The subset $A$ projects onto $M$ in a unique point $x$.
(2) Every path joining a point in $A$ with a point in $M$ contains $x$.

Notation. Let $x \in \mathbb{F}$. We denote by $T_{x}$ the set of points $y \in \mathbb{F}$ which can be joined to $x$ by a topological arc intersecting every piece in at most one point.

Lemma 2.12. Let $x \in \mathbb{F}$ and $y \in T_{x}, y \neq x$. Then every topological arc with endpoints $x, y$ intersects each piece in at most one point. In particular the arc is contained in $T_{x}$.

Proof. Suppose, by contradiction, that there exists a topological arc $\mathfrak{p}$ in $\mathbb{F}$ connecting $x, y$ and intersecting a piece $M$ in more than one point. By Corollary $2.10, M \cap \mathfrak{p}$ is a topological arc with endpoints $a \neq b$. By definition, there also exists an arc $\mathfrak{q}$ connecting $x$ and $y$ and touching each piece in at most one point.

Now consider the two paths connecting $x$ and $M$. The first path $\mathfrak{p}^{\prime}$ is a part of $\mathfrak{p}$ connecting $x$ and $a$. The second path $\mathfrak{q}^{\prime}$ is the composition of the path $\mathfrak{q}$ and a portion of $\mathfrak{p}^{-1}$ connecting $y$ and $b$. By Corollary 2.11 , the path $\mathfrak{q}^{\prime}$ must pass through the point $a$. Since the portion $[y, b]$ of $\mathfrak{p}^{-1}$ does not contain $a$, the path $\mathfrak{q}$ must contain $a$. But then there exists a part $\mathfrak{q}^{\prime \prime}$ of $\mathfrak{q}^{\prime}$ connecting $a$ and $b$ and intersecting $M$ in exactly two points. This contradicts part (1) of Corollary 2.11, as a point in $\mathfrak{q}^{\prime \prime} \backslash\{a, b\}$ would project onto $M$ in both $a$ and $b$.

Lemma 2.13. Let $x \in \mathbb{F}$ and $y \in T_{x}$. Then $T_{x}=T_{y}$.
Proof. It suffices to prove $T_{y} \subset T_{x}$. Let $z \in T_{y}$. By Lemma 2.12, any geodesic connecting $y$ with $x$ or $z$ intersects every piece in at most one point. Let $t$ be the farthest from $y$ intersection point between two geodesics $\mathfrak{p}=[y, x]$ and $\mathfrak{q}=[y, z]$. Then $\mathfrak{r}=[x, t] \cup[t, z]$ is a topological arc. The arc $\mathfrak{r}$ intersects
every piece in at most one point. Indeed, if $\mathfrak{r}$ intersects a piece $M$ in two points $a, b$ then it intersects it in a sub-arc by Corollary 2.10, so at least one of the two segments $[x, t],[t, z]$ intersects $M$ in an arc, a contradiction. Thus $z \in T_{x}$.

Lemma 2.14. Let $x \in \mathbb{F}$.
(1) Every topological arc joining two distinct points in $T_{x}$ is contained in $T_{x}$.
(2) The subset $T_{x}$ is a real tree.

Proof. (1) is an immediate consequence of the two previous lemmas.
(2) First we prove that for every $y, z \in T_{x}$ there exists a unique geodesic joining $y$ and $z$, also contained in $T_{x}$. Since $\mathbb{F}$ is a geodesic space, there exists a geodesic in $\mathbb{F}$ joining $x$ and $y$. By the first part of the lemma, this geodesic is contained in $T_{x}$. Suppose there are two distinct geodesics $\mathfrak{g}, \mathfrak{g}^{\prime}$ in $T_{x}$ joining $y$ and $z$. A point on $\mathfrak{g}$ which is not on $\mathfrak{g}^{\prime}$ is contained in a simple bigon composed of a sub-arc of $\mathfrak{g}$ and a sub-arc of $\mathfrak{g}^{\prime}$. This bigon, by $\left(T_{2}\right)$, is contained in a piece. This contradicts Lemma 2.12.

Now consider a geodesic triangle $y z t$ in $T_{x}$. Deleting, if necessary, a common sub-arc we can suppose that $[y, z] \cap[y, t]=\{y\}$. If $y \notin[z, t]$ then let $z^{\prime}$ be the nearest to $y$ point of $[y, z] \cap[z, t]$ and let $t^{\prime}$ be the nearest to $y$ point of $[y, t] \cap[z, t]$. The triangle $y z^{\prime} t^{\prime}$ is simple; therefore it is contained in one piece by $\left(T_{2}\right)$. This again contradicts Lemma 2.12. Thus $y \in[z, t]$.

Convention: We assume that a 1-point metric space has a cut-point.
Lemma 2.15. Let $A$ be a path-connected subset of $\mathbb{F}$ without a cut-point. Then $A$ is contained in a piece. In particular every simple loop is contained in a piece.

Proof. By our convention, $A$ contains at least two points. Fix a point $x \in A$. The set $A$ cannot be contained in the real tree $T_{x}$, because otherwise it would have a cut-point. Therefore, a topological arc joining in $A$ the point $x$ and some $y \in A$ intersects a piece $M$ in a sub-arc $\mathfrak{p}$. Suppose that $A \not \subset M$. Let $z \in A \backslash M$ and let $z^{\prime}$ be the projection of $z$ onto $M$. Corollary 2.11 implies that every continuous path joining $z$ to any point $\alpha$ of $\mathfrak{p}$ contains $z^{\prime}$. In particular $z^{\prime} \in A$, and $z$ and $\alpha$ are in two distinct connected components of $\mathbb{F} \backslash\left\{z^{\prime}\right\}$. Thus, $z^{\prime}$ is a cut-point of $A$, a contradiction.

Proposition 2.16. Let $\mathbb{F}$ and $\mathbb{F}^{\prime}$ be two tree-graded spaces with respect to the sets of pieces $\mathscr{P}$ and $\mathscr{P}^{\prime}$, respectively. Let $\Psi: \mathbb{F} \rightarrow \mathbb{F}^{\prime}$ be a homeomorphism. Suppose that all pieces in $\mathscr{P}$ and $\mathscr{P}^{\prime}$ do not have cut-points. Then $\Psi$ sends any piece from $\mathscr{P}$ onto a piece from $\mathscr{P}^{\prime}$, and $\Psi\left(T_{x}\right)=T_{\Psi(x)}$ for every $x \in \mathbb{F}$.

Proof. Indeed, for every piece $M$ in $\mathbb{F}, \Psi(M)$ is a path-connected subset of $\mathbb{F}^{\prime}$ without cut-points. Therefore $\Psi(M)$ is inside a piece $M^{\prime}$ of $\mathbb{F}^{\prime}$ by Lemma 2.15. Applying the same argument to $\Psi^{-1}$, we have that $\Psi^{-1}\left(M^{\prime}\right)$ is contained in a piece $M^{\prime \prime}$. Then $M \subseteq \Psi^{-1}\left(M^{\prime}\right) \subseteq M^{\prime \prime}$; hence $M=M^{\prime \prime}$ and $\Psi(M)=M^{\prime}$.


Fig. 1. Property $\left(T_{2}^{\prime}\right)$.
Proposition 2.17. Condition $\left(T_{2}\right)$ in the definition of tree-graded spaces can be replaced by the assumption that pieces cover $\mathfrak{F}$ plus any one of the following conditions:
$\left(T_{2}^{\prime}\right)$ For every topological arc $\mathfrak{c}:[0, d] \rightarrow \mathbb{F}$ and $t \in[0, d]$, let $\mathfrak{c}[t-a, t+b]$ be a maximal sub-arc of $\mathfrak{c}$ containing $\mathfrak{c}(t)$ and contained in one piece. Then every other topological arc with the same endpoints as $\mathfrak{c}$ must contain the points $\mathfrak{c}(t-a)$ and $\mathfrak{c}(t+b)$ (Fig. 1).
$\left(T_{2}^{\prime \prime}\right)$ Every simple loop in $\mathbb{F}$ is contained in one piece.
Proof. Obviously $\left(T_{1}\right)$ and $\left(T_{2}^{\prime}\right)$ imply $\left(T_{2}\right)$. Therefore it is enough to establish the implications $\left(T_{1}\right) \&\left(T_{2}^{\prime \prime}\right) \Rightarrow\left(T_{2}^{\prime}\right)$ and $\left(T_{1}\right) \&\left(T_{2}\right) \Rightarrow\left(T_{2}^{\prime \prime}\right)$. The second of these implications is given by Lemma 2.15 .

Suppose that $\left(T_{1}\right)$ and $\left(T_{2}^{\prime \prime}\right)$ hold for some space $\mathbb{F}$ with respect to some set of pieces $\mathscr{P}$.
Let $\mathfrak{c}:[0, d] \rightarrow \mathbb{F}$ be a topological arc, $t \in[0, d]$, and $a, b$ as in $\left(T_{2}^{\prime}\right)$. If $c^{\prime}:\left[0, d^{\prime}\right] \rightarrow \mathbb{F}$ is another topological arc with the same endpoints as $c$, then $K=c^{-1}\left(c^{\prime}\left[0, d^{\prime}\right]\right)$ is a compact set containing 0 and $d$. Suppose that, say, $t-a \notin K$. Let $\alpha$ be the supremum of $K \cap[0, t-a]$ and $\beta$ be the infimum of $K \cap[t-a, d]$. Then $\alpha<t-a<\beta$. Since $\alpha, \beta \in K$, there exist $\alpha^{\prime}, \beta^{\prime} \in\left[0, d^{\prime}\right]$ such that $\mathfrak{c}^{\prime}\left(\alpha^{\prime}\right)=\mathfrak{c}(\alpha), c^{\prime}\left(\beta^{\prime}\right)=\mathfrak{c}(\beta)$. The restriction of $\mathfrak{c}$ to $[\alpha, \beta]$ and the restriction of $\mathfrak{c}^{\prime}$ to $\left[\alpha^{\prime}, \beta^{\prime}\right]$ form a simple loop which is contained in one piece by $\left(T_{2}^{\prime \prime}\right)$. In particular $\mathfrak{c}([\alpha, \beta])$ is contained in one piece. Since $[t-a, t+b]$ is the maximal interval containing $t$ such that the restriction of $c$ to that interval is contained in one piece, it follows that $b+a \neq 0$. Therefore the intersection of the intervals $[\alpha, \beta]$ and $[t-a, t+b]$ has a non-empty interior. Hence the pieces containing $\mathfrak{c}([\alpha, \beta])$ and $\mathfrak{c}([t-a, t+b])$ must coincide by property $\left(T_{1}\right)$. But this contradicts the maximality of the interval $[t-a, t+b]$.

Remark 2.18. If a collection of subsets $\mathscr{P}$ of a geodesic metric space $X$ satisfy $\left(T_{1}\right)$ and $\left(T_{2}^{\prime \prime}\right)$, and each set in $\mathscr{P}$ is path-connected then each set in $\mathscr{P}$ is a geodesic subspace. Thus if one replaces property $\left(T_{2}\right)$ by the stronger property $\left(T_{2}^{\prime \prime}\right)$ in Definition 2.1 then one can weaken the condition on $\mathscr{P}$.

Proof. Let $M \in \mathscr{P}$, let $x, y$ be two points in $M$ and let $\mathfrak{r}$ be a topological arc joining $x$ and $y$ in $M$. Suppose that a geodesic $\mathfrak{g}$ connecting $x$ and $y$ in $X$ is not contained in $M$. Let $z \in \mathfrak{g} \backslash M$. There exists a simple non-trivial bigon with one side a sub-arc in $r$ and the other a sub-arc in $\mathfrak{g}$ containing $z$. Property $\left(T_{2}^{\prime \prime}\right)$ implies that this bigon is contained in a piece, and property $\left(T_{1}\right)$ implies that this piece is $M$. Hence $z$ is in $M$, a contradiction.

Lemma 2.19. For every $x \in \mathbb{F}, T_{x}$ is a closed subset of $\mathbb{F}$.

Proof. Let $\left(y_{n}\right)$ be a sequence in $T_{x}$ converging to a point $y$. Suppose that the geodesic $[x, y]$ intersects a piece $M$ in a maximal non-trivial sub-arc $[\alpha, \beta]$. We can assume that the geodesic $\left[y_{n}, y\right]$ intersects [ $\left.y_{n}, x\right]$ only in $y_{n}$. Otherwise we can replace $y_{n}$ with the farthest from it intersection point between these two geodesics. By property $\left(T_{2}^{\prime}\right)$ the arc $\left[x, y_{n}\right] \cup\left[y_{n}, y\right]$ must contain $[\alpha, \beta]$. Since $y_{n} \in T_{x}$, it follows by Lemma 2.12 that $[\alpha, \beta] \subset\left[y_{n}, y\right]$ and so $\operatorname{dist}\left(y_{n}, y\right) \geqslant \operatorname{dist}(\alpha, \beta)>0$. This contradicts $\operatorname{dist}\left(y_{n}, y\right) \rightarrow 0$. We conclude that $[x, y]$ intersects every piece in at most one point and that $y \in T_{x}$.

Lemma 2.20. The projection of $\mathfrak{F}$ onto any of the pieces is a metric retraction.
Proof. Let $M$ be a piece, $x, y$ two points in $\mathbb{F}$ and $[x, y]$ a geodesic joining them. If $[x, y] \cap M=\emptyset$ then $[x, y]$ projects onto one point $z$, by Corollary 2.9 , and $d(x, y) \geqslant d(z, z)=0$.

If $[x, y] \cap M=[\alpha, \beta]$ then $\alpha$ is the projection of $x$ onto $M$ and $\beta$ is the projection of $y$ onto $M$, by Corollary 2.9. Obviously $d(x, y) \geqslant d(\alpha, \beta)$.

Lemma 2.21. Let $\mathfrak{p}:[0, l] \rightarrow \mathbb{F}$ be a path in a tree-graded space $\mathbb{F}$. Let $U_{\mathfrak{p}}$ be the union of open subintervals $(a, b) \subset[0, l]$ such that the restriction of $\mathfrak{p}$ onto $(a, b)$ belongs to one piece (we include the trees $T_{x}$ into the set of pieces). Then $U_{p}$ is an open and dense subset of $[0, l]$.

Proof. Suppose that $U_{\mathfrak{p}}$ is not dense. Then there exists a non-trivial interval $(c, d)$ in the complement $[0, l] \backslash U_{\mathfrak{p}}$. Suppose that the restriction $\mathfrak{p}^{\prime}$ of $\mathfrak{p}$ on $(c, d)$ intersects a piece $P$ in two points $y=\mathfrak{p}\left(t_{1}\right), z=\mathfrak{p}\left(t_{2}\right)$. We can assume that $y$ is not in the image of $\left(t_{1}, t_{2}\right.$ ] under $\mathfrak{p}$. Since $y \notin U_{\mathfrak{p}}$ there is a non-empty interval $\left(t_{1}, t_{3}\right)$ such that the restriction of $\mathfrak{p}$ onto that interval does not intersect $P$. Let $t>t_{1}$ be the smallest number in $\left(t_{1}, t_{2}\right]$ such that $z^{\prime}=\mathfrak{p}(t)$ is in $P$. Then $z^{\prime} \neq y$. Applying Corollary 2.11 to the restriction of $\mathfrak{p}$ onto $\left[t_{1}, t\right]$, we get a contradiction. This means that $\mathfrak{p}^{\prime}$ intersects every piece in at most one point. Therefore $\mathfrak{p}^{\prime}$ is contained in a tree $T_{x}$ for some $x$, a contradiction.

Proposition 2.22. Let $\mathbb{F}$ be a tree-graded space with the set of pieces $\mathscr{P}$. If the pieces in $\mathscr{P}$ are locally uniformly contractible then $\pi_{1}(\mathbb{F})$ is the free product of $\pi_{1}(M), M \in \mathscr{P}$.

Proof. We include all trees $T_{x}$ into $\mathscr{P}$. Fix a base point $x$ in $\mathbb{F}$ and for every piece $M_{i} \in \mathscr{P}$ let $y_{i}$ be the projection of $x$ onto $M_{i}$, and let $\mathfrak{g}_{i}$ be a geodesic connecting $x$ and $y_{i}$. We identify $\pi_{1}\left(M_{i}\right)$ with the subgroup $G_{i}=\mathfrak{g}_{i} \pi_{1}\left(M_{i}, y_{i}\right) \mathfrak{g}_{i}^{-1}$ of $\pi_{1}(\mathbb{F}, x)$. Consider an arbitrary loop $\mathfrak{p}:[0, l] \rightarrow \mathbb{F}$ in $\mathbb{F}$ based at $x$. Let $\mathfrak{p}^{\prime}$ be the image of $\mathfrak{p}$. Let $\mathscr{P}_{\mathfrak{p}}$ be the set of pieces from $\mathscr{P}$ which are intersected by $\mathfrak{p}^{\prime}$ in more than one point. By Lemma 2.21 the set $\mathscr{P}_{p}$ is countable.

Let $M \in \mathscr{P}_{p}$. The projection $\mathfrak{p}_{M}$ of $\mathfrak{p}^{\prime}$ onto $M$ is a loop containing the intersection $\mathfrak{p}^{\prime} \cap M$. Let us prove that $\mathfrak{p}_{M}=\mathfrak{p}^{\prime} \cap M$. If there exists a point $z \in \mathfrak{p}_{M} \backslash \mathfrak{p}^{\prime}$ then $z$ is a projection of some point $y \in \mathfrak{p}^{\prime} \backslash M$ onto $M$. By Corollary 2.11, a sub-path of $\mathfrak{p}$ joining $y$ with a point in $\mathfrak{p}^{\prime} \cap P$ must contain $z$, a contradiction.

Therefore $\mathfrak{p}^{\prime}$ is a union of at most countably many loops $\mathfrak{p}_{i}, i \in \mathbb{N}$, contained in pieces from $\mathscr{P}_{\mathfrak{p}}$. By uniform local contractibility of the pieces, all but finitely many loops $\mathfrak{p}_{i}$ are contractible inside the corresponding pieces. Consequently, in the fundamental group $\pi_{1}(\mathbb{F}), \mathfrak{p}$ is a product of finitely many loops from $G_{i}$. Hence $\pi_{1}(\mathbb{F}, x)$ is generated by the subgroups $G_{i}$.

It remains to prove that for every finite sequence of loops $\mathfrak{p}_{i} \in G_{i}, i=1, \ldots, k$, if $M_{i} \neq M_{j}$ for $i \neq j$, and if the loops $\mathfrak{p}_{i}$ are not null-homotopic in $M_{i}$, then the loop $\mathfrak{p}_{1} \mathfrak{p}_{2} \ldots \mathfrak{p}_{n}$ is not null-homotopic in $\mathbb{F}$. Suppose that $\mathfrak{p}$ is null-homotopic, and that $\gamma: t \rightarrow \mathfrak{p}(t)$ is the homotopy, $\mathfrak{p}(0)=\mathfrak{p}, \mathfrak{p}(1)$ is a point. Let $\pi_{i}$ be the projection of $\mathbb{F}$ onto $M_{i}$. Lemma 2.20 implies that $\pi_{i} \circ \gamma: t \rightarrow \mathfrak{p}_{i}^{\prime}(t)$ is a homotopy
which continuously deforms $\mathfrak{p}_{i}^{\prime}$ in $M_{i}$ into a point. Hence each of the loops $\mathfrak{p}_{i}$ is null-homotopic, a contradiction.

### 2.2. Modifying the set of pieces

Lemma 2.23 (gluing pieces together). Let $\mathbb{F}$ be a space which is tree-graded with respect to $\mathscr{P}\left\{M_{k} \mid\right.$ $k \in K\}$.
(1) Let $Y=\bigcup_{k \in F} M_{k}$ be a finite connected union of pieces. Then $\mathbb{F}$ is tree-graded with respect to $\mathscr{P}^{\prime}=\left\{M_{k} \mid k \in K \backslash F\right\} \cup\{Y\}$.
(2) Let $\mathfrak{c}$ be a topological arc in $\mathbb{F}$ (possibly a point) and let $Y(\mathfrak{c})$ be a set of the form $\mathfrak{c} \cup \bigcup_{j \in J} M_{j}$, where $J$ is a subset of $K$ such that every $M_{j}$ with $j \in J$ has a non-empty intersection with $\mathfrak{c}$, and $J$ contains all $i \in K$ such that $M_{i} \cap \mathrm{c}$ is a non-trivial arc.
Then $\mathbb{F}$ is tree-graded with respect to $\mathscr{P}^{\prime}=\left\{M_{k} \mid k \in K \backslash J\right\} \cup\{Y(\mathfrak{c})\}$.
(3) Let $\left\{\mathfrak{c}_{i} ; i \in F\right\}$ be a finite collection of topological arcs in $\mathbb{F}$ and let $Y\left(\mathfrak{c}_{i}\right)=\mathfrak{c}_{i} \cup \bigcup_{j \in J_{i}} M_{j}$ be sets defined as in (2). If $Y=\bigcup_{i \in F} Y\left(\mathfrak{c}_{i}\right)$ is connected then $\mathbb{F}$ is tree-graded with respect to $\mathscr{P}^{\prime}=\left\{M_{k} \mid\right.$ $\left.k \in K \backslash \bigcup_{i \in F} J_{i}\right\} \cup\{Y\}$.

Remark 2.24. In particular all properties on projections on pieces obtained till now hold for sets $Y$ defined as in (1)-(3). We shall call sets of the form $Y(\mathfrak{c})$ sets of type $Y$.

Proof. (1) We first prove that $Y$ is convex. Every $y, y^{\prime} \in Y$ can be joined by a topological arc $c$ : $[0, d] \rightarrow Y$. By Corollary 2.10, we may write $c[0, d]=\bigcup_{k \in F^{\prime}}\left[c[0, d] \cap M_{k}\right]$, where $F^{\prime} \subset F$ and $c[0, d] \cap M_{k}$ is a point or an arc. Property ( $T_{1}$ ) implies that every two such arcs have at most one point in common. Therefore there exists a finite sequence $t_{0}=0<t_{1}<t_{2}<\cdots<t_{n-1}<t_{n}=d$ such that $\mathfrak{c}\left[t_{i}, t_{i+1}\right]=\mathfrak{c}[0, d] \cap M_{k(i)}, k(i) \in F^{\prime}$, for every $i \in\{0,1, \ldots, n-1\}$. Property $\left(T_{2}^{\prime}\right)$ implies that every geodesic between $y$ and $y^{\prime}$ must contain $\mathfrak{c}\left(t_{1}\right), \mathfrak{c}\left(t_{2}\right), \ldots, \mathfrak{c}\left(t_{n-1}\right)$. Hence every such geodesic is of the form $\left[y, \mathfrak{c}\left(t_{1}\right)\right] \cup\left[\mathfrak{c}\left(t_{1}\right), \mathfrak{c}\left(t_{2}\right)\right] \cup \cdots \cup\left[\mathfrak{c}\left(t_{n-1}\right), y\right]$, so by Corollary 2.10 it is contained in $Y$.

For every $k \in K \backslash F, M_{k} \cap Y$, if non-empty, is a convex set composed of finitely many points. Hence it is a point. This and the previous discussion imply that $\mathbb{F}$ is tree-graded with respect to $\mathscr{P}^{\prime}$.
(2) In order to prove that $Y$ is convex, let $\mathfrak{g}$ be a geodesic joining two points $x, y \in Y$. We show that $\mathfrak{g}$ is inside $Y$.

Case I. Suppose that $x, y \in \mathrm{c}$. Consider a point $z=\mathfrak{g}(t)$ in $\mathfrak{g}$. Take the maximal interval $[t-a, t+b]$ such that $\mathfrak{g}([t-a, t+b])$ is contained in one piece $M$. If $a+b \neq 0$ then by property $\left(T_{2}^{\prime}\right)$ the path c must pass through $\mathfrak{g}(t-a)$ and $\mathfrak{g}(t+b)$. By part (1) of Corollary 2.10 the (non-trivial) sub-arc of $\mathfrak{c}$ joining $\mathfrak{g}(t-a)$ and $\mathfrak{g}(t+b)$ is contained in $M$. Then $M$ is one of the pieces contained in $Y$. Therefore $z \in Y$. If $a+b=0$ then again by $\left(T_{2}^{\prime}\right)$ the curve c must pass through $z$, so $z \in Y$. We conclude that in both cases $z \in Y$.

Case II. Suppose that $x \in \mathfrak{c}$ and $y \in M \backslash \mathfrak{c}$, where $M$ is a piece in $Y$. By the definition of $Y, M$ has a non-trivial intersection with $c$. If $x \in M$, we can use the convexity of $M$ (Corollary 2.10 ). So suppose that $x \notin M$.

Let $\alpha$ be the projection of $x$ onto $M$. By Corollary 2.11(2), $\alpha \in c$. Then the sub-arc $c^{\prime}$ of $c$ with endpoints $x$ and $\alpha$ forms together with the geodesic $[\alpha, y] \subseteq M$ a topological arc. Property $\left(T_{2}^{\prime}\right)$ implies that $\alpha \in \mathfrak{g}$. Corollary 2.10(1) implies that the portion of $\mathfrak{g}$ between $\alpha$ and $y$ is contained in $Y$. For the remaining part of $\mathfrak{g}$ we apply the result in Case I of the proof (since both endpoints of that part of $\mathfrak{g}$ belong to $\mathfrak{c}$ ).

Case III. Suppose that $x \in M_{1} \backslash c$ and that $y \in M_{2} \backslash c$. Let $\alpha$ be the projection of $x$ onto $M_{2}$. As before, we obtain that $\alpha \in \mathfrak{c}, \alpha \in \mathfrak{g}$ and that the portion of $\mathfrak{g}$ between $\alpha$ and $y$ is contained in $M_{2}$, hence in $Y$. For the remaining part of $\mathfrak{g}$ we apply the result of Case II.
(3) We argue by induction on the size $k$ of the set $F$. The statement is true for $k=1$ by part (2) of this proposition. Suppose it is true for some $k \geqslant 1$. Let us prove it for $k+1$. We have two cases.

Case I. Suppose that there exist $i, j \in F, i \neq j$, such that the intersection $\mathfrak{c}_{i} \cap Y\left(\mathfrak{c}_{j}\right)$ is not empty. According to part (2) of the proposition and Corollary 2.10(2), the intersection is a sub-arc, and $\mathbb{F}$ is tree-graded with respect to $\mathscr{P}_{j}^{\prime}=\left\{M_{k} \mid k \in K \backslash J_{j}\right\} \cup\left\{Y\left(\mathfrak{c}_{j}\right)\right\}$. Let $Y^{\prime}\left(\mathfrak{c}_{i}\right)=Y\left(\mathfrak{c}_{i}\right) \cup Y\left(\mathfrak{c}_{j}\right)$. Then $Y^{\prime}\left(\mathfrak{c}_{i}\right)$ is a set defined as in part (2) of the proposition but with $\mathscr{P}$ replaced by $\mathscr{P}_{j}^{\prime}$. Thus we can write $Y=Y^{\prime}\left(\mathfrak{c}_{i}\right) \cup$ $\bigcup_{s \in F \backslash\{i, j\}} Y\left(c_{s}\right)$ and use the induction hypothesis.

Case II. For every $i, j \in F, i \neq j$, we have $\mathfrak{c}_{i} \cap Y\left(\mathfrak{c}_{j}\right)=\emptyset$.
Then there are no pieces that appear in both $Y\left(\mathfrak{c}_{i}\right)$ and $Y\left(\mathfrak{c}_{j}\right)$ for $i \neq j \in F$. Hence by $\left(T_{1}\right)$, for every $k \in J_{i}, l \in J_{j}, M_{k} \cap M_{l}$ consists of at most one point. By part (2) of the proposition and Corollary 2.11 that point must be equal to the projection of $\mathfrak{c}_{i}$ onto $Y\left(\mathfrak{c}_{j}\right)$. Therefore $Y\left(\mathfrak{c}_{i}\right) \cap Y\left(\mathfrak{c}_{j}\right)$ is either empty or one point. This implies that $\mathbb{F}$ is tree-graded with respect to $\mathscr{P}^{\prime \prime}=\left\{M_{k} \mid k \in K \backslash \bigcup_{i \in F} J_{i}\right\} \cup\left\{Y\left(\mathfrak{c}_{i}\right) \mid i \in F\right\}$. It remains to apply part (1) of the proposition.

Definition 2.25. Let $\left(M_{1}, x_{1}\right),\left(M_{2}, x_{2}\right), \ldots,\left(M_{k}, x_{k}\right)$ be finitely many metric spaces with fixed basepoints. The bouquet of these spaces, denoted by $\bigvee_{i=1}^{k}\left(M_{i}, x_{i}\right)$, is the metric space obtained from the disjoint union of all $M_{i}$ by identifying all the points $x_{i}$. We call the point $x$ thus obtained the cutpoint of the bouquet. The metric on $\bigvee_{i=1}^{k}\left(M_{i}, x_{i}\right)$ is induced by the metrics on $M_{i}$ in the obvious way.

Clearly each $M_{i}$ is a closed subset of the bouquet $\bigvee_{i=1}^{k}\left(M_{i}, x_{i}\right)$. It is also clear that the bouquet is a geodesic metric space if and only if all $M_{i}$ are geodesic metric spaces.

Lemma 2.26 (cutting pieces by cut-points). Let $\mathbb{F}$ be a space which is tree-graded with respect to $\mathscr{P}=\left\{M_{k} \mid\right.$ $k \in K\}$. Let $I \subset K$ be such that for every $i \in I$ the piece $M_{i}$ is the bouquet of finitely many subsets of it, $\left\{M_{i}^{j}\right\}_{j \in F_{i}}$, and its cut-point is $x_{i}$.

Then $\mathbb{F}$ is tree-graded with respect to the set

$$
\mathscr{P}^{\prime}=\left\{M_{k} \mid k \in K \backslash I\right\} \cup\left\{M_{i}^{j} \mid j \in F_{i}, i \in I\right\} .
$$

Proof. Since $M_{i}^{j} \cap M_{k} \subset M_{i} \cap M_{k}$ for $i \in I, k \in K \backslash I$, and $M_{i}^{j} \cap M_{t}^{s} \subset M_{i} \cap M_{t}$ for $i \neq t, i, t \in I$, property $\left(T_{1}\right)$ for $\left(\mathbb{F}, \mathscr{P}^{\prime}\right)$ is an immediate consequence of property $\left(T_{1}\right)$ for $(\mathbb{F}, \mathscr{P})$.

Let $\Delta$ be a simple geodesic triangle. Property $\left(T_{2}\right)$ for $(\mathbb{F}, \mathscr{P})$ implies that either $\Delta \subset M_{k}$ for some $k \in K \backslash I$ or $\Delta \subset M_{i}$ for some $i \in I$. We only need to consider the second case. Assume that $\Delta$ has a point in $M_{i}^{j_{1}}$ and a point in $M_{i}^{j_{2}}$, with $j_{1} \neq j_{2}$. Then $x_{i}$ is a cut-point for $\Delta$. This contradicts the fact that $\Delta$ is a simple loop. We conclude that there exists $j \in F_{i}$ such that $M_{i}^{j}$ contains $\Delta$. Thus $\mathscr{P}^{\prime}$ satisfies ( $T_{2}$ ).

Lemma 2.13 implies that two trees $T_{x}$ and $T_{y}$ are either disjoint or coincident. Let $\left\{T_{i} \mid i \in I\right\}$ be the collection of all the trees $\left\{T_{x} \mid x \in \mathbb{F}\right\}$.

Remark 2.27. The set $\mathscr{P}^{\prime}=\mathscr{P} \cup\left\{T_{i} \mid i \in I\right\}$ also satisfies properties $\left(T_{1}\right)$ and $\left(T_{2}\right)$. Therefore all the properties and arguments done for $\mathbb{F}$ and $\mathscr{P}$ up to now also hold for $\mathbb{F}$ and $\mathscr{P}^{\prime}$. In this case, $T_{x}=\{x\}$ for every $x \in \mathbb{F}$. The disadvantage of this point of view is that trees $T_{x}$ always have cut-points.

### 2.3. Geodesics in tree-graded spaces

Notation. For every path $\mathfrak{p}$ in a metric space $X$, we denote the start of $\mathfrak{p}$ by $\mathfrak{p}_{-}$and the end of $\mathfrak{p}$ by $\mathfrak{p}_{+}$.
Lemma 2.28. Let $\mathfrak{g}=\mathfrak{g}_{1} \mathfrak{g}_{2} \ldots \mathfrak{g}_{2 m}$ be a curve in a tree-graded space $\mathbb{F}$ which is a composition of geodesics. Suppose that all geodesics $\mathfrak{g}_{2 k}$ with $k \in\{1, \ldots, m-1\}$ are non-trivial and for every $k \in\{1, \ldots, m\}$ the geodesic $g_{2 k}$ is contained in a piece $M_{k}$ while for every $k \in\{0,1, \ldots, m-1\}$ the geodesic $\mathfrak{g}_{2 k+1}$ intersects $M_{k}$ and $M_{k+1}$ only in its respective endpoints. In addition assume that if $\mathfrak{g}_{2 k+1}$ is empty then $M_{k} \neq M_{k+1}$. Then $\mathfrak{g}$ is a geodesic.

Proof. Suppose that $\mathfrak{g}$ is not simple. By ( $T_{2}^{\prime \prime}$ ), any simple loop formed by a portion of $\mathfrak{g}$ has to be contained in one piece $M$. On the other hand the loop must contain the whole neighborhood of one vertex $\left(\mathfrak{g}_{i}\right)_{+}=\left(\mathfrak{g}_{i+1}\right)_{-}$in $\mathfrak{g}$. Let $k$ be such that $\left\{\mathfrak{g}_{i}, \mathfrak{g}_{i+1}\right\}=\left\{\mathfrak{g}_{2 k}, \mathfrak{g}_{2 k \pm 1}\right\}$. The intersection of $M$ and $M_{k}$ contains a sub-arc of $\mathfrak{g}_{2 k}$, whence $M=M_{k}$. At the same time, $M$ contains a sub-arc of $\mathfrak{g}_{2 k \pm 1}$ or (if $\mathfrak{g}_{2 k \pm 1}$ is empty) of $\mathfrak{g}_{2 k-2}$. In all cases we immediately get a contradiction.

Therefore $\mathfrak{g}$ is simple and has two distinct endpoints $x, y$. Consider any geodesic r joining $x$ and $y$. By $\left(T_{2}^{\prime}\right) \mathfrak{r}$ contains all the endpoints of all geodesics $\mathfrak{g}_{i}$. Therefore the length of $\mathfrak{g}$ coincides with the length of $r$ and $\mathfrak{g}$ is itself a geodesic.

Corollary 2.29. Let $M$ and $M^{\prime}$ be two distinct pieces in a tree-graded space $\mathbb{F}$. Suppose that $M^{\prime}$ projects onto $M$ in $x$ and $M$ projects on $M^{\prime}$ in $y$. Let $A$ be a set in $\mathbb{F}$ that projects onto $M^{\prime}$ in $z \neq y$. Then $A$ projects onto $M$ in $x$ and $\operatorname{dist}(A, M) \geqslant \operatorname{dist}\left(M^{\prime}, M\right)$.

Proof. Let $a \in A$ and let $[a, z],[z, y]$ and $[y, x]$ be geodesics. Then $\mathfrak{g}_{a}=[a, z] \cup[z, y] \cup[y, x]$ is a geodesic, according to Lemma 2.28. It cannot intersect $M$ in a sub-geodesic, because $[z, y] \cup$ $[y, x]$ intersects $M$ in $x$. Hence $\mathfrak{g}_{a} \cap M=\{x\}$ and $x$ is the projection of $a$ onto $M$. Also dist $(a, x) \geqslant$ $\operatorname{dist}(y, x)$.

### 2.4. Cut-points and tree-graded spaces

Remark 2.30 (about singletons). Notice that if $\mathbb{F}$ is tree-graded with respect to $\mathscr{P}$ then we can always add some or all one-point subsets (singletons) of $\mathbb{F}$ to $\mathscr{P}$, and $\mathbb{F}$ will be tree-graded with respect to a bigger set of pieces. To avoid using extra pieces, we shall assume in this section that pieces cannot contain other pieces.

Property $\left(T_{1}\right)$ guarantees that this only restricts using singletons as pieces.
Property $\left(T_{2}^{\prime}\right)$ implies that any tree-graded space containing more than one piece has a global cut-point. Here we shall show that any geodesic metric space with cut-points has a uniquely determined collection of pieces with respect to which it is tree-graded.

In order to do this, we need to define a partial order relation on the set of collections of subsets of a space. If $\mathscr{P}$ and $\mathscr{P}^{\prime}$ are collections of subsets of $X$ and a space $X$ is tree-graded with respect to both $\mathscr{P}$
and $\mathscr{P}^{\prime}$, we write $\mathscr{P} \prec \mathscr{P}^{\prime}$ if for every set $M \in \mathscr{P}$ there exists $M^{\prime} \in \mathscr{P}^{\prime}$ such that $M \subset M^{\prime}$. The relation $\prec$ is a partial order because by Remark 2.2, pieces of $\mathscr{P}$ (resp. $\mathscr{P}^{\prime}$ ) cannot contain each other.

Lemma 2.31. Let $X$ be a complete geodesic metric space containing at least two points and let $\mathscr{C}$ be a non-empty set of global cut-points in $X$.
(a) There exists the largest in the sense of $\prec$ collection $\mathscr{P}$ of subsets of $X$ such that

- X is tree-graded with respect to $\mathscr{P}$;
- any piece in $\mathscr{P}$ is either a singleton or a set with no global cut-point from $\mathscr{C}$.

Moreover the intersection of any two distinct pieces from $\mathscr{P}$ is either empty or a point from $\mathscr{C}$.
(b) Let $X$ be a homogeneous space with a cut-point. Then every point in $X$ is a cut-point, so let $\mathscr{C}=X$. Let $\mathscr{P}$ be the set of pieces defined in part (a). Then for every $M \in \mathscr{P}$ every $x \in M$ is the projection of a point $y \in X \backslash M$ onto $M$.

Proof. (a) Let $\mathscr{P}$ be the set of all maximal path-connected subsets $M$ with the property that either $|M|=1$ or cut-points of $M$ do not belong to $\mathscr{C}$. The existence of maximal subsets with this property immediately follows from Zorn's lemma.

Any $M \in \mathscr{P}$ is closed. Indeed, let $\bar{M}$ be the closure of $M$ in $X$ and suppose that $\bar{M} \neq M$. Let $a \in \bar{M} \backslash M$. There exists a sequence of points $\left(a_{n}\right)$ in $M$ converging to $a$. Let $M^{\prime}$ be the union of $M$ and geodesics $\left[a, a_{n}\right], n=1,2, \ldots$ (one geodesic for each $n$ ). By construction, the set $M^{\prime}$ is path-connected. Let us prove that cut-points of $M^{\prime}$ do not belong to $\mathscr{C}$. This will contradict the maximality of $M$.

Let $c \in \mathscr{C} \cap M^{\prime}, x, y \in M^{\prime} \backslash\{c\}$. We want to connect $x$ and $y$ with a path avoiding $c$. If $x, y \in M \backslash\{c\}$ then we are done.

Suppose that $x \in M \backslash\{c\}$ and $y \in\left[a_{n}, a\right]$ for some $n$. The point $x$ can be connected by some path $\mathfrak{p}_{k} \subseteq M$ avoiding $c$ with $a_{k}$ for every $k \in \mathbb{N}$.

If $c \notin\left[a_{n}, y\right]$ then the path $\mathfrak{p}_{n} \cup\left[a_{n}, y\right] \subseteq M^{\prime}$ avoids $c$ and we are done.
If $c \in\left[a_{n}, y\right]$ then $\operatorname{dist}(c, a)>\operatorname{dist}(y, a)$. In particular $c$ is not in $\left[a, a_{m}\right]$ for $m$ large enough. Then we join $y$ with $x$ by a path $[y, a] \cup\left[a, a_{m}\right] \cup \mathfrak{p}_{m}$ avoiding $c$.

It remains to consider the case when $x \in\left[a_{m}, a\right]$ and $y \in\left[a_{n}, a\right]$ for some $m, n$. If $c \notin\left[a_{m}, x\right]$ then we can replace $x$ with $a_{m}$ and use the previous argument. Likewise if $c \notin\left[a_{n}, y\right]$. If $c \in\left[a_{m}, x\right] \cap\left[a_{n}, y\right]$ then we join $x$ and $y$ in $X \backslash\{c\}$ by $[x, a] \cup[a, y]$.

Let $M_{1}, M_{2}$ be distinct sets from $\mathscr{P}, c \in \mathscr{C}$. Suppose that $M_{1} \cap M_{2}$ contains a point $x$ that is different from $c$. Then any point $z_{i} \in M_{i}, z_{i} \neq c, i=1,2$, can be joined with $x$ by a path in $M_{i}$ avoiding $c$. Hence $z_{1}$ and $z_{2}$ can be joined in $M_{1} \cup M_{2}$ by a path avoiding $c$. Consequently if $M_{1} \cap M_{2}$ contains more than one point or contains a point not from $\mathscr{C}$, we get a contradiction with the maximality of $M_{i}$. Thus $\mathscr{P}$ satisfies $\left(T_{1}\right)$ and the intersection of any two sets from $\mathscr{P}$ is in $\mathscr{C}$ or empty.

To prove $\left(T_{2}^{\prime \prime}\right)$ notice that every non-trivial simple loop is path-connected and does not have cut-points, hence it is contained in some $M$.

The fact that each piece $M \in \mathscr{P}$ is a geodesic subset follows from Remark 2.18.
Suppose that $X$ is tree-graded with respect to another collection of pieces $\mathscr{P}^{\prime}$ that contains only singletons and pieces without a cut-points from $\mathscr{C}$. Let $M^{\prime} \in \mathscr{P}^{\prime}$. Then $M^{\prime}$ is contained in a maximal path-connected subset which is either a singleton or without a cut-point in $\mathscr{C}$, that is $M^{\prime} \subset M$ for some $M \in \mathscr{P}$. Thus $\mathscr{P}^{\prime} \prec \mathscr{P}$. Hence $\mathscr{P}$ is the largest in the sense of $\prec$ collection of subsets of $X$ satisfying the conditions of part (a).
(b) Let $M \in \mathscr{P}$. Since $M \neq X$ it follows that one point $x_{0} \in M$ is the projection on $M$ of a point $y_{0} \in X \backslash M$. If $M$ is a point this ends the proof. Suppose in the sequel that $M$ has at least two points. Let $\left[y_{0}, x_{0}\right.$ ] be a geodesic joining $y_{0}$ and $x_{0}$ and let $\left[x_{0}, z_{0}\right]$ be a geodesic in $M$. By the definition of the projection, $\left[y_{0}, x_{0}\right] \cap\left[x_{0}, z_{0}\right]=\left\{x_{0}\right\}$. Let $x$ be an arbitrary point in $M$. Consider an isometry $g$ such that $g\left(x_{0}\right)=x$. Let $[y, x]$ and $[x, z]$ be the respective images of $\left[y_{0}, x_{0}\right]$ and $\left[x_{0}, z_{0}\right]$ under $g$. If $g(M)=M$ then $x$ is the projection of $y$ on $M$. Suppose $g(M) \neq M$. Then $g(M) \cap M=\{x\}$; hence $[x, z] \subset g(M)$ intersects $M$ in $x$. Corollary 2.11 implies that $z$ projects on $M$ in $x$.

Remark 2.32. (1) In general not every point in $\mathscr{C}$ is the intersection point of two distinct pieces. An example is an $\mathbb{R}$-tree without endpoints $X, \mathscr{C}=X$, in which case $\mathscr{P}$ is the set of all singleton subsets of $X$.
(2) Lemma 2.31 implies that every asymptotic cone of a group which has a cut-point is tree-graded with respect to a uniquely determined collection of pieces, each of which is either a singleton or a closed geodesic subset without cut-points.

## 3. Ultralimits and asymptotic cones

### 3.1. Preliminaries

Most of the interesting examples of tree-graded spaces that we know are asymptotic cones of groups. In this section, we start with giving the definitions of ultralimit, asymptotic cone and related objects (most of these definitions are well known). We show that the collection of asymptotic cones of a space is closed under ultralimits. We also show that simple geodesic triangles in ultralimits and asymptotic cones can be approximated by ultralimits of polygons with certain properties. As a consequence we show that the family of tree-graded spaces is also closed under ultralimits. These results play a central part in the theorems obtained in Sections 4 and 7.

Convention: In the sequel $I$ will denote an arbitrary countable set.
Definition 3.1 (ultrafilter). A (non-principal ${ }^{2}$ ) ultrafilter $\omega$ over $I$ is a set of subsets of $I$ satisfying the following conditions:

1. If $A, B \in \omega$ then $A \cap B \in \omega$.
2. If $A \in \omega, A \subseteq B \subseteq I$, then $B \in \omega$.
3. For every $A \subseteq I$ either $A \in \omega$ or $I \backslash A \in \omega$.
4. No finite subset of $I$ is in $\omega$.

Equivalently $\omega$ is a finitely additive measure on the class $\mathscr{P}(I)$ of subsets of $I$ such that each subset has measure either 0 or 1 and all finite sets have measure 0 . If some statement $P(n)$ holds for all $n$ from a set $X$ belonging to an ultrafilter $\omega$, we say that $P(n)$ holds $\omega$-almost surely.

Remark 3.2. By definition $\omega$ has the property that $\omega\left(\bigsqcup_{i=1}^{m} A_{i}\right)=1$ (here $\sqcup$ stands for disjoint union) implies that there exists $i_{0} \in\{1,2, \ldots, m\}$ such that $\omega\left(A_{i_{0}}\right)=1$ and $\omega\left(A_{i}\right)=0$ for every $i \neq i_{0}$. This can be reformulated as follows: let $P_{1}(n), P_{2}(n), \ldots, P_{m}(n)$ be properties such that for any $n \in I$ no two of

[^2]them can be true simultaneously. If the disjunction of these properties holds $\omega$-almost surely then there exists $i \in\{1,2, \ldots, m\}$ such that $\omega$-almost surely $P_{i}(n)$ holds and all $P_{j}(n)$ with $j \neq i$ do not hold.

Definition 3.3 ( $\omega$-limit). Let $\omega$ be an ultrafilter over $I$. For every sequence of points $\left(x_{n}\right)_{n \in I}$ in a topological space $X$, its $\omega$-limit $\lim _{\omega} x_{n}$ is a point $x$ in $X$ such that for every neighborhood $U$ of $x$ the relation $x_{n} \in U$ holds $\omega$-almost surely.

Remark 3.4. If $\omega$-limit $\lim _{\omega} x_{n}$ exists then it is unique, provided the space $X$ is Hausdorff. Every sequence of elements in a compact space has an $\omega$-limit [4].

Definition 3.5 (ultraproduct). For every sequence of sets $\left(X_{n}\right)_{n \in I}$ the ultraproduct $\Pi X_{n} / \omega$ corresponding to an ultrafilter $\omega$ consists of equivalence classes of sequences $\left(x_{n}\right)_{n \in I}, x_{n} \in X_{n}$, where two sequences $\left(x_{n}\right)$ and $\left(y_{n}\right)$ are identified if $x_{n}=y_{n} \omega$-almost surely. The equivalence class of a sequence $\left(x_{n}\right)$ in $\Pi X_{n} / \omega$ is denoted by $\left(x_{n}\right)^{\omega}$. In particular, if all $X_{n}$ are equal to the same $X$, the ultraproduct is called the ultrapower of $X$ and is denoted by $X^{\omega}$.

Recall that if $G_{n}, n \geqslant 1$, are groups then $\Pi G_{n} / \omega$ is again a group with the operation $\left(x_{n}\right)^{\omega}\left(y_{n}\right)^{\omega}=$ $\left(x_{n} y_{n}\right)^{\omega}$.

Definition 3.6 ( $\omega$-limit of metric spaces). Let $\left(X_{n}, \operatorname{dist}_{n}\right), n \in I$, be a sequence of metric spaces and let $\omega$ be an ultrafilter over $I$. Consider the ultraproduct $\Pi X_{n} / \omega$ and an observation point $e=\left(e_{n}\right)^{\omega}$ in $\Pi X_{n} / \omega$. For every two points $x=\left(x_{n}\right)^{\omega}, y=\left(y_{n}\right)^{\omega}$ in $\Pi X_{n} / \omega$ let

$$
D(x, y)=\lim _{\omega} \operatorname{dist}_{n}\left(x_{n}, y_{n}\right)
$$

The function $D$ is a pseudo-metric on $\Pi X_{n} / \omega$ (i.e. it satisfies the triangle inequality and the property $D(x, x)=0$, but for some $x \neq y$, the number $D(x, y)$ can be 0 or $\infty)$. Let $\Pi_{e} X_{n} / \omega$ be the subset of $\Pi X_{n} / \omega$ consisting of elements which are finite distance from $e$ with respect to $D$. The $\omega$-limit $\lim ^{\omega}\left(X_{n}\right)_{e}$ of the metric spaces ( $X_{n}$, dist $_{n}$ ) relative to the observation point $e$ is the metric space obtained from $\Pi_{e} X_{n} / \omega$ by identifying all pairs of points $x, y$ with $D(x, y)=0$. The equivalence class of a sequence $\left(x_{n}\right)$ in $\lim ^{\omega}\left(X_{n}\right)_{e}$ is denoted by $\lim ^{\omega}\left(x_{n}\right)$.

Remark 3.7 (changing the observation point). It is easy to see that if $e, e^{\prime} \in \Pi X_{n} / \omega$ and $D\left(e, e^{\prime}\right)<\infty$ then $\lim ^{\omega}\left(X_{n}\right)_{e}=\lim ^{\omega}\left(X_{n}\right)_{e^{\prime}}$.

Definition 3.8 (asymptotic cone). Let ( $X$, dist) be a metric space, $\omega$ an ultrafilter over a set $I$, and $e=\left(e_{n}\right)^{\omega}$ an observation point. Consider a sequence of numbers $d=\left(d_{n}\right)_{n \in I}$ called scaling constants satisfying $\lim _{\omega} d_{n}=\infty$.

In the ultrapower $X^{\omega}$ we define the subset $X_{e}^{\omega}=\Pi_{e} X_{n} / \omega$, where $\left(X_{n}, \operatorname{dist}_{n}\right)=\left(X, \operatorname{dist} / d_{n}\right)$. We call it ultrapower of $X$ with respect to the observation point $e$.

The $\omega$-limit $\lim ^{\omega}\left(X, \operatorname{dist} / d_{n}\right)_{e}$ is called an asymptotic cone of $X$. It is denoted by $\operatorname{Con}^{\omega}(X ; e, d)$ (see [28,30,54]).

Definition 3.9. For a sequence $\left(A_{n}\right), n \in I$, of subsets of ( $X$, dist) we denote by $\lim ^{\omega}\left(A_{n}\right)$ the subset of $\operatorname{Con}^{\omega}(X ; e, d)$ that consists of all the elements $\lim ^{\omega}\left(x_{n}\right)$ such that $x_{n} \in A_{n} \omega$-almost surely. Notice that if $\lim _{\omega}\left(\operatorname{dist}\left(e_{n}, A_{n}\right) / d_{n}\right)=\infty$ then the set $\lim ^{\omega}\left(A_{n}\right)$ is empty.

Remark 3.10. It is proved in [54] that any asymptotic cone of a metric space is complete. The same proof gives that $\lim ^{\omega}\left(A_{n}\right)$ is always a closed subset of the asymptotic cone $\operatorname{Con}^{\omega}(X ; e, d)$.

Definition 3.11 (quasi-isometries). A quasi-isometric embedding of a metric space ( $X, \operatorname{dist}_{X}$ ) into a metric space $\left(Y, \operatorname{dist}_{Y}\right)$ is a map $\mathrm{q}: X \rightarrow Y$ such that

$$
\frac{1}{L} \operatorname{dist}_{X}\left(x, x^{\prime}\right)-C \leqslant \operatorname{dist}_{Y}\left(\mathfrak{q}(x), \mathfrak{q}\left(x^{\prime}\right)\right) \leqslant L \operatorname{dist}_{X}\left(x, x^{\prime}\right)+C \quad \text { for all } x, x^{\prime} \in X
$$

In particular if $\left(X, \operatorname{dist}_{X}\right)$ is an interval of the real line $\mathbb{R}$ then $\mathfrak{q}$ is called a quasi-geodesic or an (L, C)-quasi-geodesic.

A quasi-isometry is a quasi-isometric embedding $\mathfrak{q}: X \rightarrow Y$ such that there exists a quasi-isometric embedding $\mathfrak{q}^{\prime}: Y \rightarrow X$ with the property that $\mathfrak{q} \circ \mathfrak{q}^{\prime}$ and $\mathfrak{q}^{\prime} \circ q$ are at finite distance from the identity maps.

Remark 3.12 (quasi-injectivity). Although a quasi-isometric embedding is not necessarily injective, a weaker version of injectivity holds: If $\mathfrak{q}$ is an $(L, C)$-quasi-isometric embedding then $\operatorname{dist}(x, y)>L C$ implies $\operatorname{dist}(\mathfrak{q}(x), \mathfrak{q}(y))>0$.

Definition 3.13 (Lipschitz maps). Let $L \geqslant 1$. A map q: $\left(X, \operatorname{dist}_{X}\right) \rightarrow\left(Y, \operatorname{dist}_{Y}\right)$ is called Lipschitz if

$$
\operatorname{dist}_{Y}\left(\mathfrak{q}(x), \mathfrak{q}\left(x^{\prime}\right)\right) \leqslant L \operatorname{dist}_{X}\left(x, x^{\prime}\right)
$$

for every $x, x^{\prime} \in X$. The map $\mathfrak{q}$ is called bi-Lipschitz if it also satisfies

$$
\operatorname{dist}_{Y}\left(\mathfrak{q}(x), \mathfrak{q}\left(x^{\prime}\right)\right) \geqslant \frac{1}{L} \operatorname{dist}_{X}\left(x, x^{\prime}\right)
$$

Remark 3.14. Let $\left(X_{n}\right)$ and $\left(Y_{n}\right)$ be sequences of metric spaces, $e_{n} \in X_{n}, e_{n}^{\prime} \in Y_{n}(n \in I)$. Then it is easy to see that any sequence $\mathfrak{q}_{n}: X_{n} \rightarrow Y_{n}$ of $\left(L_{n}, C_{n}\right)$-quasi-isometries with $\mathfrak{q}_{n}\left(e_{n}\right)=e_{n}^{\prime}, n \in I$, induces an $(L, C)$-quasi-isometry $\mathfrak{q}: \lim ^{\omega}\left(X_{n}\right)_{e} \rightarrow \lim ^{\omega}\left(Y_{n}\right)_{e^{\prime}}$ where $e=\left(e_{n}\right)^{\omega}, e^{\prime}=\left(e_{n}^{\prime}\right)^{\omega}$, and $L=$ $\lim _{\omega} L_{n}, C=\lim _{\omega} C_{n}$ provided $L<\infty, C<\infty$. Moreover, the $\omega$-limit of the images $\mathfrak{q}_{n}\left(X_{n}\right)$ coincides with the image of $\mathfrak{q}$.

Remark 3.15. Let $\mathfrak{q}_{n}:\left[0, \ell_{n}\right] \rightarrow X$ be a sequence of $(L, C)$-quasi-geodesics in a geodesic metric space ( $X$, dist). Then the $\omega$-limit $\lim ^{\omega}\left(\mathfrak{q}_{n}\left(\left[0, \ell_{n}\right]\right)\right)$ in any asymptotic cone $\operatorname{Con}^{\omega}(X, e, d)$ is either empty, or a bi-Lipschitz arc or a bi-Lipschitz ray or a bi-Lipschitz line. This immediately follows from Remark 3.14.

Remark 3.16. Any quasi-isometric embedding $\mathfrak{q}$ of $\left(X, \operatorname{dist}_{X}\right)$ into ( $Y, \operatorname{dist}_{Y}$ ) induces a bi-Lipschitz embedding of $\operatorname{Con}^{\omega}(X ; e, d)$ into $\operatorname{Con}^{\omega}\left(Y ;\left(q\left(e_{n}\right)\right), d\right)$ for every $\omega, e$ and $d$ [30].

Every finitely generated group $G=\langle X\rangle$ can be considered a metric space where the distance between two elements $a, b$ is the length of the shortest group word in $X$ representing $a^{-1} b$. The asymptotic cones of $G$ corresponding to different observation points are isometric [30]. Thus when we consider an asymptotic cone of a finitely generated group, we shall always assume that the observation point $e$ is (1) ${ }^{\omega}$.

Let $G_{n}, n \in I$, be the metric space $G$ with metric dist/ $d_{n}$ for some sequence of scaling constants $\left(d_{n}\right)_{n \in I}$. The set $\Pi_{e} G_{n} / \omega$ denoted by $G_{e}^{\omega}$ is a subgroup of the ultrapower $G^{\omega}$.

Remark 3.17. Notice [30] that the group $G_{e}^{\omega}$ acts on $\operatorname{Con}^{\omega}(G ; e, d)$ by isometries:

$$
\left(g_{n}\right)^{\omega} \lim ^{\omega}\left(x_{n}\right)=\lim ^{\omega}\left(g_{n} x_{n}\right)
$$

This action is transitive, so, in particular, every asymptotic cone of a group is homogeneous.
More generally if a group $G$ acts by isometries on a metric space ( $X$, dist) and there exists a bounded subset $B \subset X$ such that $X=G B$ then all asymptotic cones of $X$ are homogeneous metric spaces.

Definition 3.18 (asymptotic properties). We say that a space has a certain property asymptotically if each of its asymptotic cones has this property. For example, a space may be asymptotically CAT(0), asymptotically without cut-point, etc.

Definition 3.19 (asymptotically tree-graded spaces). Let ( $X$, dist) be a metric space and let $\mathscr{A}=\left\{A_{i} \mid\right.$ $i \in I\}$ be a collection of subsets of $X$. In every asymptotic cone $\operatorname{Con}^{\omega}(X ; e, d)$, we consider the collection of subsets

$$
\mathscr{A}_{\omega}=\left\{\lim ^{\omega}\left(A_{i_{n}}\right) \mid\left(i_{n}\right)^{\omega} \in I^{\omega} \text { such that the sequence }\left(\frac{\operatorname{dist}\left(e_{n}, A_{i_{n}}\right)}{d_{n}}\right) \text { is bounded }\right\} .
$$

We say that $X$ is asymptotically tree-graded with respect to $\mathscr{A}$ if every asymptotic cone $\operatorname{Con}^{\omega}(X ; e, d)$ is tree-graded with respect to $\mathscr{A}_{\omega}$.

This notion is a generalization, in the setting of metric spaces, of the usual notion of (strongly) relatively hyperbolic group.

Corollary 4.30 will show that there is no need to vary the ultrafilter in Definition 3.19: if a space is tree-graded with respect to a collection of subsets for one ultrafilter, it is tree-graded for any other with respect to the same collection of subsets.

### 3.2. Ultralimits of asymptotic cones are asymptotic cones

Definition 3.20 (an ultraproduct of ultrafilters). Let $\omega$ be an ultrafilter over $I$ and let $\mu=\left(\mu_{n}\right)_{n \in I}$ be a sequence of ultrafilters over $I$. We consider each $\mu_{n}$ as a measure on the set $\{n\} \times I$ and $\omega$ as a measure on $I$.

For every subset $A \subseteq I \times I$ we set $\omega \mu(A)$ equal to the $\omega$-measure of the set of all $n \in I$ such that $\mu_{n}(A \cap(\{n\} \times I))=1$.

In other words

$$
\omega \mu(A)=\int \mu_{n}(A \cap(\{n\} \times I)) \mathrm{d} \omega(n) .
$$

Notice that this is a generalization of the standard notion of product of ultrafilters (see [51, Definition 3.2 in Chapter VI]).

Lemma 3.21 (cf. [51, Lemma 3.6 in Chapter VI]). $\omega \mu$ is an ultrafilter over $I \times I$.
Proof. It suffices to prove that $\omega \mu$ is finitely additive and that it takes the zero value on finite sets.

Let $A$ and $B$ be two disjoint subsets of $I \times I$. Then for every $n \in I$ the sets $A \cap(\{n\} \times I)$ and $B \cap(\{n\} \times I)$ are disjoint. Hence (by the additivity of $\left.\mu_{n}\right)$ for every $n \in I$

$$
\mu_{n}((A \cup B) \cap(\{n\} \times I))=\mu_{n}(A \cap(\{n\} \times I))+\mu_{n}(B \cap(\{n\} \times I)) .
$$

Therefore (by the additivity of $\omega$ )

$$
\omega \mu(A \sqcup B)=\omega \mu(A)+\omega \mu(B) .
$$

Let now $A$ be a finite subset of $I \times I$. Then the set of numbers $n$ for which $\mu_{n}(A \cap(\{n\} \times I))=1$ is empty. So $\omega \mu(A)=0$ by definition.

Lemma 3.22 (double ultralimit of sequences). Let $\omega, \mu_{n}, n \in I$, be as in Definition 3.20. Let $r_{k}^{(n)}$ be a uniformly bounded double indexed sequence of real numbers, $k, n \in I$. Then

$$
\begin{equation*}
\lim _{\omega \mu} r_{k}^{(n)}=\lim _{\omega} \lim _{\mu_{n}} r_{k}^{(n)} \tag{1}
\end{equation*}
$$

(the internal limit is taken with respect to $k$ ).
Proof. Let $r=\lim _{\omega \mu} r_{k}^{(n)}$. It follows that, for every $\varepsilon>0$,

$$
\omega \mu\left\{(n, k) \mid r_{k}^{(n)} \in(r-\varepsilon, r+\varepsilon)\right\}=1 \Leftrightarrow \omega\left\{n \in I \mid \mu_{n}\left\{k \mid r_{k}^{(n)} \in(r-\varepsilon, r+\varepsilon)\right\}=1\right\}=1
$$

It follows that

$$
\omega\left\{n \in I \mid \lim _{\mu_{n}} r_{k}^{(n)} \in[r-\varepsilon, r+\varepsilon]\right\}=1
$$

which implies that

$$
\lim _{\omega} \lim _{\mu_{n}} r_{k}^{(n)} \in[r-\varepsilon, r+\varepsilon]
$$

Since this is true for every $\varepsilon>0$ we conclude that $\lim _{\omega} \lim _{\mu_{n}} r_{k}^{(n)}=r$.
Lemma 3.22 immediately implies:
Proposition 3.23 (double ultralimit of metric spaces). Let $\omega$ and $\mu$ be as in Definition 3.20. Let ( $X_{k}^{(n)}$, $\operatorname{dist}_{k}^{(n)}$ ) be a double indexed sequence of metric spaces, $k, n \in I$, and let e be a double indexed sequence of points $e_{k}^{(n)} \in X_{k}^{(n)}$. We denote by $e^{(n)}$ the sequence $\left(e_{k}^{(n)}\right)_{k \in I}$.

The map

$$
\begin{equation*}
\lim _{\omega \mu}\left(x_{k}^{(n)}\right) \mapsto \lim _{\omega}\left(\lim _{\mu_{n}}\left(x_{k}^{(n)}\right)\right) \tag{2}
\end{equation*}
$$

is an isometry from $\lim ^{\omega \mu}\left(X_{k}^{(n)}\right)_{e}$ onto $\lim ^{\omega}\left(\lim ^{\mu_{n}}\left(X_{k}^{(n)}\right)_{e^{(n)}}\right)_{e^{\prime}}$, where $e_{n}^{\prime}=\lim ^{\mu_{n}}\left(e^{(n)}\right)$.
Corollary 3.24 (ultralimits of cones are cones). Let $X$ be a metric space. Let $\omega$ and $\mu$ be as above. For every $n \in I$ let $e^{(n)}=\left(e_{k}^{(n)}\right)_{k \in I}$ be an observation point, and $d^{(n)}=\left(d_{k}^{(n)}\right)_{k \in I}$ be a sequence of scaling
constants satisfying $\lim _{\mu_{n}} d_{k}^{(n)}=\infty$ for every $n \in I$. Let $\operatorname{Con}^{\mu_{n}}\left(X ; e^{(n)}, d^{(n)}\right)$ be the corresponding asymptotic cone of $X$. Then the map

$$
\begin{equation*}
\lim _{\omega \mu}\left(x_{k}^{(n)}\right) \mapsto \lim _{\omega}\left(\lim _{\mu_{n}}\left(x_{k}^{(n)}\right)\right) \tag{3}
\end{equation*}
$$

is an isometry from $\operatorname{Con}^{\omega \mu}(X ; e, d)$ onto

$$
\lim ^{\omega}\left(\operatorname{Con}^{\mu_{n}}\left(X ; e^{(n)}, d^{(n)}\right)\right)_{\left(\lim ^{\mu_{n}}\left(e^{(n)}\right)\right)}
$$

where $e=\left(e_{k}^{(n)}\right)_{(n, k) \in I \times I}$ and $d=\left(d_{k}^{(n)}\right)_{(n, k) \in I \times I}$.
Proof. Let us prove that $\lim _{\omega \rho \mu} d_{k}^{(n)}=\infty$. Let $M>0$. For every $n \in I$ we have that $\lim _{\mu_{n}} d_{k}^{(n)}=\infty$, whence $\mu_{n}\left\{k \in I \mid d_{k}^{(n)}>M\right\}=1$. It follows that $\left\{n \in I \mid \mu_{n}\left\{k \in I \mid d_{k}^{(n)}>M\right\}=1\right\}=I$; therefore its $\omega$-measure is 1 . We conclude that $\omega \mu\left\{(n, k) \mid d_{k}^{(n)}>M\right\}=1$.

It remains to apply Proposition 3.23 to the sequence of metric spaces $\left(X,\left(1 / d_{k}^{(n)}\right)\right.$ dist) and to $e$.

### 3.3. Another definition of asymptotic cones

In $[30,54]$ and some other papers, a more restrictive definition of asymptotic cones is used. In that definition, the set $I$ is equal to $\mathbb{N}$ and the scaling constant $d_{n}$ must be equal to $n$ for every $n$. We shall call these asymptotic cones restrictive.

It is easy to see that every restrictive asymptotic cone is an asymptotic cone in our sense. The converse statement can well be false although we do not have any explicit examples.

Also for every ultrafilter $\omega$ over $I$ and every sequence of scaling constants $d=\left(d_{n}\right)_{n \in I}$, there exists an ultrafilter $\mu$ over $\mathbb{N}$ such that the asymptotic cone $\operatorname{Con}^{\omega}(X ; e, d)$ contains an isometric copy of the restrictive asymptotic cone $\operatorname{Con}^{\mu}(X ; e,(n))$. Indeed, let $\phi$ be a map $I \rightarrow \mathbb{N}$ such that $\phi(i)=\left[d_{i}\right]$. Now define the ultrafilter $\mu$ on $\mathbb{N}$ by $\mu(A)=\omega\left(\phi^{-1}(A)\right)$ for every set $A \subseteq \mathbb{N}$. The embedding $\operatorname{Con}^{\mu}(X ; e,(n)) \rightarrow$ $\operatorname{Con}^{\omega}(X ; e, d)$ is defined by $\lim ^{\mu}\left(x_{n}\right) \mapsto \lim ^{\omega}\left(x_{\phi(i)}\right)_{i \in I}$.

Remark 3.25. In the particular case when the sets $\left\{i \in I \mid\left[d_{i}\right]=k\right\}$ are of uniformly bounded (finite) size, this embedding is a surjective isometry [47].

The restrictive definition of asymptotic cones is, in our opinion, less natural because the $\omega$-limit of restrictive asymptotic cones is not canonically represented as a restrictive asymptotic cone (see Corollary 3.24). Conceivably, it may even not be a restrictive asymptotic cone in general. The next statement shows that it is a restrictive asymptotic cone in some particular cases.

Proposition 3.26. Let $v_{n}, n \in \mathbb{N}$, be a sequence of ultrafilters over $\mathbb{N}$. Let $\left(I_{n}\right)$ be sequence of pairwise disjoint subsets of $\mathbb{N}$ such that $v_{n}\left(I_{n}\right)=1$. Let $C_{n}=\operatorname{Con}^{v_{n}}\left(X ; e^{(n)},(n)\right), n \in \mathbb{N}$, be a restrictive asymptotic cone of a metric space $X$. Then the $\omega$-limit of asymptotic cones $C_{n}$ is a restrictive asymptotic cone.

Proof. Let $\mu_{n}$ be the restriction of $v_{n}$ onto $I_{n}, n \in \mathbb{N}$. Then $C_{n}$ is isometric to $\operatorname{Con}^{\mu_{n}}\left(X ; e^{(n)}, d^{(n)}\right)$ where $d^{(n)}$ is sequence of all numbers from $I_{n}$ in increasing order. By Corollary $3.24, \lim ^{\omega}\left(C_{n}\right)_{\lim ^{\mu_{n}}\left(e^{(n)}\right)}$ is the asymptotic cone $\operatorname{Con}^{\omega \mu}(X ; e, d)$ where $e=\left(e_{k}^{(n)}\right)_{(n, k) \in \mathbb{N} \times \mathbb{N}}$ and $d=\left(d_{k}^{(n)}\right)_{(n, k) \in \mathbb{N} \times \mathbb{N}}$. For every natural
number $a$ the set of pairs $(n, k)$ such that $d_{k}^{(n)}=a$ contains at most one element because the subsets $I_{n} \subseteq \mathbb{N}$ are disjoint. It remains to apply Remark 3.25.

### 3.4. Simple triangles in ultralimits of metric spaces

Definition 3.27 ( $k$-gons). We say that a metric space $P$ is a geodesic (quasi-geodesic) $k$-gon if it is a union of $k$ geodesics (quasi-geodesics) $\mathfrak{q}_{1}, \ldots, \mathfrak{q}_{k}$ such that $\left(\mathfrak{q}_{i}\right)_{+}=\left(\mathfrak{q}_{i+1}\right)_{-}$for every $i=1, \ldots, k$ (here $k+1$ is identified with 1 ).

For every $i=1, \ldots, k$, we denote the polygonal curve $P \backslash\left(\mathfrak{q}_{i-1} \cup \mathfrak{q}_{i}\right)$ by $\mathcal{O}_{x_{i}}(P)$, where $x_{i}=\left(\mathfrak{q}_{i-1}\right)_{+}=$ $\left(\mathfrak{q}_{i}\right)_{-}$. When there is no possibility of confusion we simply denote it by $\mathcal{O}_{x_{i}}$.

Lemma 3.28. (1) Let $P_{n}, n \in \mathbb{N}$, be a sequence of geodesic $k$-gons in metric spaces ( $X_{n}$, dist ${ }_{n}$ ). Let $\omega$ be an ultrafilter over $\mathbb{N}$, such that $\lim ^{\omega}\left(P_{n}\right)=P$, where $P$ is a simple geodesic $k$-gon in the metric space $\lim ^{\omega}\left(X_{n}\right)_{e}$ with metric dist. Let $\mathscr{V}_{n}$ be the set of vertices of $P_{n}$ in the clockwise order. Let $D_{n}$ be the supremum over all points $x$ contained in two distinct edges of $P_{n}$ of the distances $\operatorname{dist}\left(x, \mathscr{V}_{n}\right)$. Then $\lim _{\omega} D_{n}=0$.
(2) Let $P$ be a simple $k$-gon in ( $X$, dist). For every $\delta>0$ we define $D_{\delta}=D_{\delta}(P)$ to be the supremum over all k-gons $P_{\delta}$ in $X$ that are at Hausdorff distance at most $\delta$ from $P$ and over all points $x$ contained in two distinct edges of $P_{\delta}$ of the distances $\operatorname{dist}\left(x, \mathscr{V}_{\delta}\right)$, where $\mathscr{V}_{\delta}$ is the set of vertices of $P_{\delta}$. Then $\lim _{\delta \rightarrow 0} D_{\delta}=0$.

Proof. (1) Since the $\omega$-limit of the diameters of $P_{n}$ is the diameter of $P$, it follows that the diameters of $P_{n}$ are uniformly bounded $\omega$-almost surely. In particular $D_{n}$ is uniformly bounded $\omega$-almost surely; therefore its $\omega$-limit exists and it is finite. Suppose that $\lim _{\omega} D_{n}=2 D>0$. Then $\omega$-almost surely there exists $x_{n}$ contained in two distinct edges of $P_{n}$ such that $\operatorname{dist}_{n}\left(x_{n}, \mathscr{V}_{n}\right)>D$. Without loss of generality we may suppose that $x_{n} \in\left[A_{n}, B_{n}\right] \cap\left[B_{n}, C_{n}\right]$ for every $n$, where $\left[A_{n}, B_{n}\right],\left[B_{n}, C_{n}\right]$ are two consecutive edges of $P_{n}$ such that $\lim ^{\omega}\left(\left[A_{n}, B_{n}\right]\right)=[A, B], \lim ^{\omega}\left(\left[B_{n}, C_{n}\right]\right)=[B, C]$, where $[A, B],[B, C]$ are two consecutive edges of $P$. Then $\lim ^{\omega}\left(x_{n}\right) \in[A, B] \cap[B, C]$, which by simplicity of $P$ implies that $\lim ^{\omega}\left(x_{n}\right)=B$. On the other hand we have that $\operatorname{dist}_{n}\left(x_{n}, \mathscr{V}_{n}\right)>D$, which implies that $\operatorname{dist}\left(\lim ^{\omega}\left(x_{n}\right), B\right) \geqslant D$. We have obtained a contradiction.
(2) Assume that $\lim _{\delta \rightarrow 0} D_{\delta}=2 D>0$. It follows that there exists a sequence $\left(P_{n}\right)$ of $k$-gons endowed with metrics such that their Hausdorff distance to $P$ tends to zero and such that there exists $x_{n}$ contained in two distinct edges of $P_{n}$ and at distance at least $D$ of the vertices of $P_{n}$. According to [33], it follows that $\lim ^{\omega}\left(P_{n}\right)=P$ for every ultrafilter $\omega$. On the other hand $D_{n}>D$ for all $n \in \mathbb{N}$. We thus obtain a contradiction of (1).

Proposition 3.29 (limits of simple polygons). Consider an ultrafilter $\omega$ over $\mathbb{N}$ and a sequence of metric spaces, $\left(X_{n}, \operatorname{dist}_{n}\right), n \in \mathbb{N}$. Let $e \in \Pi X_{n} / \omega$ be an observation point. For every simple geodesic triangle $\Delta$ in $\lim ^{\omega}\left(X_{n}\right)_{e}$, for every sufficiently small $\varepsilon>0$ there exists $k_{0}=k_{0}(\varepsilon)$ and a simple geodesic triangle $\Delta_{\varepsilon}$ with the following properties:
(a) The Hausdorff distance between $\Delta$ and $\Delta_{\varepsilon}$ does not exceed $\varepsilon$.
(b) $\Delta_{\varepsilon}$ contains the midpoints of the edges of $\Delta$.
(c) The triangle $\Delta_{\varepsilon}$ can be written as $\lim ^{\omega}\left(P_{n}^{\varepsilon}\right)$, where each $P_{n}^{\varepsilon}$ is a geodesic $k$-gon in $X_{n}, k \leqslant k_{0}, P_{n}^{\varepsilon}$ is simple and the lengths of all edges of $P_{n}^{\varepsilon}$ are $O(1) \omega$-almost surely.

Proof. Let $A, B, C$ be the vertices of $\Delta$, in the clockwise order, and let $M_{A B}, M_{B C}$ and $M_{A C}$ be the midpoints of $[A, B],[B, C]$ and $[A, C]$, respectively.

We construct $\Delta_{\varepsilon}$ in several steps.
Step I. Constructing not necessarily simple geodesic triangles $\Delta_{\varepsilon}$.
For every small $\delta>0$ we divide each of the halves of edges of $\Delta$ determined by a vertex and a midpoint into finitely many segments of length at least $\delta$ and at most $2 \delta$. Let $\mathscr{V}$ be the set of endpoints of all these segments, endowed with the natural cyclic order. We call $\mathscr{V}$ a $\delta$-partition of $\Delta$. We assume that $\left\{A, B, C, M_{A B}, M_{B C}, M_{A C}\right\} \subset \mathscr{V}$. Every $t \in \mathscr{V}$ can be written as $t=\lim ^{\omega}\left(t_{n}\right)$; hence $\mathscr{V}=\lim ^{\omega}\left(\mathscr{V}_{n}\right)$, where each $\mathscr{V}_{n}$ is endowed with a cyclic order. Let $P_{n}$ be a geodesic $k$-gon with vertices $\mathscr{V}_{n}$, where $k=|\mathscr{V}|$. The limit set $\Delta_{\delta}=\lim ^{\omega}\left(P_{n}\right)$ is a geodesic triangle with vertices $A, B, C$ and at Hausdorff distance at most $\delta$ from $\Delta$.

Notation. Let $E, F$ be two points on an edge of $\Delta_{\delta}$. We denote the part of the geodesic side of $\Delta_{\delta}$ between $E$ and $F$ in $\Delta_{\delta}$ by $[E, F]_{\delta}$. If $E, F$ are two points on an edge of $\Delta$, we denote the part of the side of $\Delta$ between $E$ and $F$ by $[E, F]$. This is to avoid confusion between different geodesics joining two such points.

Step II. Making $\Delta_{\varepsilon}$ simple.
For every $\delta>0$, we consider $D_{\delta}=D_{\delta}(\Delta)$ given by Lemma 3.28. Let

$$
\alpha(\Delta)=\inf \left\{\operatorname{dist}\left(x, \mathcal{O}_{x}(\Delta)\right) \mid x \in\{A, B, C\}\right\}
$$

By Lemma 3.28 we have $\lim _{\delta \rightarrow 0} D_{\delta}=0$. Therefore, for $\delta$ small enough we have

$$
\begin{equation*}
2 D_{\delta}+4 \delta<\alpha(\Delta) \text { and } D_{\delta}+2 \delta \leqslant \frac{1}{10} \min \{\operatorname{dist}(A, B), \operatorname{dist}(B, C), \operatorname{dist}(C, A)\} \tag{4}
\end{equation*}
$$

Fix a $\delta$ satisfying (4), a $\delta$-partition $\mathscr{V}$ of $\Delta$, and a corresponding triangle $\Delta_{\delta}=\lim ^{\omega}\left(P_{n}\right)$.
Let $A_{1}$ and $A_{2}$ be the nearest to $A$ points of $\mathscr{V} \backslash \mathcal{N}_{D_{\delta}+\delta}(A)$ on the edges $[A, B]$ and $[A, C]$, respectively. For an appropriate choice of $\Delta_{\delta}$, we may suppose that $\operatorname{dist}\left(A, A_{1}\right)=\operatorname{dist}\left(A, A_{2}\right)$. We note that $\operatorname{dist}\left(A, A_{1}\right) \in\left[D_{\delta}+\delta, D_{\delta}+2 \delta\right]$. Similarly we take $B_{1} \in[B, C] \cap \mathscr{V}, B_{2} \in[B, A] \cap \mathscr{V}$ and $C_{1} \in[C, A] \cap \mathscr{V}, C_{2} \in[C, B] \cap \mathscr{V}$ with $\operatorname{dist}\left(B, B_{1}\right)=\operatorname{dist}\left(B, B_{2}\right) \in\left[D_{\delta}+\delta, D_{\delta}+2 \delta\right]$ and $\operatorname{dist}\left(C, C_{1}\right)=\operatorname{dist}\left(C, C_{2}\right) \in\left[D_{\delta}+\delta, D_{\delta}+2 \delta\right]$.

Suppose that $\left[A_{1}, B_{2}\right]_{\delta}$ and $\left[B_{1}, C_{2}\right]_{\delta}$ have a point $E$ in common. The definition of $D_{\delta}$ implies that $E \in \mathscr{N}_{D_{\delta}}(\{A, B, C\})$. On the other hand $E \in\left[A_{1}, B_{2}\right]_{\delta}$ implies $E \notin \mathscr{N}_{D_{\delta}}(\{A, B\})$ and $E \in\left[B_{1}, C_{2}\right]_{\delta}$ implies $E \notin \mathscr{N}_{D_{\delta}}(\{B, C\})$, a contradiction.

We conclude, by repeating the previous argument, that the segments $\left[A_{1}, B_{2}\right]_{\delta},\left[B_{1}, C_{2}\right]_{\delta}$ and $\left[C_{1}, A_{2}\right]_{\delta}$ are pairwise disjoint. Since $\operatorname{dist}\left(A, A_{1}\right)$, $\operatorname{dist}\left(B, B_{2}\right) \leqslant D_{\delta}+2 \delta \leqslant \frac{1}{10} \operatorname{dist}(A, B)$, it follows that $M_{A B}$ is contained in $\left[A_{1}, B_{2}\right]_{\delta}$. Likewise, $M_{B C}$ and $M_{A C}$ are contained in $\left[B_{1}, C_{2}\right]_{\delta}$ and $\left[C_{1}, A_{2}\right]_{\delta}$, respectively.

Let $d_{A}$ be the supremum of $\operatorname{dist}(E, A)$ for all $E$ satisfying two conditions: $E \in\left[A_{1}, A\right]_{\delta}$ and $\operatorname{dist}\left(A_{2}, E\right)+\operatorname{dist}(E, A)=\operatorname{dist}\left(A_{2}, A\right)$. Since these two conditions define a closed set, it follows that there exists $A^{\prime} \in\left[A_{1}, A\right]_{\delta}$ such that $\operatorname{dist}\left(A_{2}, A^{\prime}\right)+\operatorname{dist}\left(A^{\prime}, A\right)=\operatorname{dist}\left(A_{2}, A\right)$ and $\operatorname{dist}\left(A, A^{\prime}\right)=d_{A}$. Obviously
$A^{\prime} \notin\left\{A_{1}, A_{2}\right\}$. In other words, $A^{\prime}$ is the farthest from $A$ point in $\left[A_{1}, A\right]_{\delta}$ which is contained in a geodesic joining $A_{2}$ and $A$. Hence $A^{\prime}$ has the property that every geodesic joining it with $A_{2}$ intersects $\left[A_{1}, A^{\prime}\right]_{\delta}$ only in $A^{\prime}$. Similarly we find points $B^{\prime} \in\left[B_{1}, B\right]_{\delta}$ and $C^{\prime} \in\left[C_{1}, C\right]_{\delta}$.

Recall that $\Delta_{\delta}=\lim ^{\omega}\left(P_{n}\right)$. Let $P_{n}^{A}$ be a sequence of polygonal lines in $P_{n}$ with endpoints $A_{n}^{\prime}, B_{n}^{2}$, having as limit $\left[A^{\prime}, B_{2}\right]_{\delta}$. Likewise let $P_{n}^{B}$ and $P_{n}^{C}$ be sequences of polygonal lines in $P_{n}$, with endpoints $B_{n}^{\prime}, C_{n}^{2}$ and $C_{n}^{\prime}, A_{n}^{2}$, having as limits $\left[B^{\prime}, C_{2}\right]_{\delta}$ and $\left[C^{\prime}, A_{2}\right]_{\delta}$, respectively. We consider the new sequence of polygons $P_{n}^{\prime}=P_{n}^{A} \cup\left[B_{n}^{2}, B_{n}^{\prime}\right] \cup P_{n}^{B} \cup\left[C_{n}^{2}, C_{n}^{\prime}\right] \cup P_{n}^{C} \cup\left[A_{n}^{2}, A_{n}^{\prime}\right]$. The limit set $\lim ^{\omega}\left(P_{n}^{\prime}\right)$ is $\left[A^{\prime}, B_{2}\right]_{\delta} \cup$ $\mathfrak{g}_{B_{2} B^{\prime}} \cup\left[B^{\prime}, C_{2}\right]_{\delta} \cup \mathfrak{g}_{C_{2} C^{\prime}} \cup\left[C^{\prime}, A_{2}\right]_{\delta} \cup \mathfrak{g}_{A_{2} A^{\prime}}$ where $\mathfrak{g}_{B_{2} B^{\prime}}=\lim ^{\omega}\left(\left[B_{n}^{2}, B_{n}^{\prime}\right]\right)$ is a geodesic and likewise for $g_{C_{2} C^{\prime}}, \mathfrak{g}_{A_{2} A^{\prime}}$.

We have $\operatorname{dist}\left(C^{\prime}, A\right)=\operatorname{dist}\left(C^{\prime}, A_{2}\right)+\operatorname{dist}\left(A_{2}, A\right)=\operatorname{dist}\left(C^{\prime}, A_{2}\right)+\operatorname{dist}\left(A_{2}, A^{\prime}\right)+\operatorname{dist}\left(A^{\prime}, A\right)$. It follows that by joining the pairs of points $\left(C^{\prime}, A_{2}\right),\left(A_{2}, A^{\prime}\right)$ and $\left(A^{\prime}, A\right)$ by geodesics we obtain a geodesic from $C^{\prime}$ to $A$. In particular $\left[C^{\prime}, A_{2}\right]_{\delta} \cup \mathfrak{g}_{A_{2} A^{\prime}}$ is a geodesic. Likewise, $\left[A^{\prime}, B_{2}\right]_{\delta} \cup \mathfrak{g}_{B_{2} B^{\prime}}$ and $\left[B^{\prime}, C_{2}\right]_{\delta} \cup \mathfrak{g}_{C_{2} C^{\prime}}$ are geodesics. Therefore $\lim ^{\omega}\left(P_{n}^{\prime}\right)$ is a geodesic triangle $\Delta_{\delta}^{\prime}$ with vertices $A^{\prime}, B^{\prime}, C^{\prime}$. By construction the Hausdorff distance between $\Delta_{\delta}^{\prime}$ and $\Delta_{\delta}$ is at most $D_{\delta}+2 \delta$; hence the Hausdorff distance between $\Delta_{\delta}^{\prime}$ and $\Delta$ is at most $D_{\delta}+3 \delta$.

Suppose that two edges of $\Delta_{\delta}^{\prime}$ have a common point $E$. Suppose the two edges are $\left[A^{\prime}, B_{2}\right]_{\delta} \cup g_{B_{2} B^{\prime}}$ and $\left[B^{\prime}, C_{2}\right]_{\delta} \cup \mathfrak{g}_{C_{2} C^{\prime}}$. If $E \in\left[A^{\prime}, A_{1}\right]_{\delta}$ then $\operatorname{dist}(A, E) \leqslant D_{\delta}+2 \delta$. On the other hand $E \in\left[B^{\prime}, C_{2}\right]_{\delta} \cup \mathfrak{g}_{C_{2} C^{\prime}}$ implies $E \in \mathcal{N}_{D_{\delta}+2 \delta}([B, C])$. Hence $\operatorname{dist}(A,[B, C]) \leqslant 2 D_{\delta}+4 \delta<\alpha(\Delta)$, a contradiction.

If $E \in \mathfrak{g}_{C_{2} C^{\prime}}$ then dist $(C, E) \leqslant D_{\delta}+2 \delta$ which together with $E \in\left[A^{\prime}, B_{2}\right]_{\delta} \cup \mathfrak{g}_{B_{2} B^{\prime}} \subset \mathcal{N}_{D_{\delta}+2 \delta}([A, B])$ implies $\operatorname{dist}(C,[A, B]) \leqslant 2 D_{\delta}+4 \delta<\alpha(\Delta)$, a contradiction.

If $E \in\left[A_{1}, B_{2}\right]_{\delta}$ then $E \notin\left[B_{1}, C_{2}\right]_{\delta}$. Also since $\operatorname{dist}(B, E) \geqslant \operatorname{dist}\left(B, B_{2}\right)=\operatorname{dist}\left(B, B_{1}\right)$ it follows that $E \notin\left[B^{\prime}, B_{1}\right]_{\delta}$, a contradiction.

If $E \in \mathfrak{g}_{B_{2} B^{\prime}}$ then an argument similar to the previous gives $E \notin\left[B_{1}, C_{2}\right]_{\delta}$. We conclude that $E \in$ $\left[B^{\prime}, B_{1}\right]_{\delta}$. By the choice of $B^{\prime}$ we have $E=B^{\prime}$.

We conclude that $\Delta_{\delta}^{\prime}$ is a simple geodesic triangle, containing the midpoints of the edges of $\Delta$, at Hausdorff distance at most $D_{\delta}+3 \delta$ from $\Delta$, and $\Delta_{\delta}^{\prime}=\lim ^{\omega}\left(P_{n}^{\prime}\right)$, where $P_{n}^{\prime}$ is a geodesic $m$-gon, with $m \leqslant k+3$.

Step III. Making polygons simple.
Let $D_{n}$ be the supremum over all points $x$ contained in two distinct edges of $P_{n}^{\prime}$ of the distances from $x$ to the vertices of $P_{n}^{\prime}$. Applying Lemma 3.28(1), to $\left(P_{n}^{\prime}\right)$ and to $\Delta_{\delta}^{\prime}=\lim ^{\omega}\left(P_{n}^{\prime}\right)$ we obtain that $D_{n}$ tends to zero as $n \rightarrow \infty$. Let $v_{n}$ be a vertex of $P_{n}^{\prime}$. We consider the farthest point $v_{n}^{\prime}$ in the ball $B\left(v_{n}, 2 D_{n}\right)$ contained in both edges of endpoint the vertex $v_{n}$. Cut the bigon of vertices $v_{n}, v_{n}^{\prime}$ from the polygon, and repeat this operation for every vertex $v_{n}$ of $P_{n}^{\prime}$. As a result, we obtain a new polygon $P_{n}^{\prime \prime}$ which is simple and at Hausdorff distance at most $2 D_{n}$ from $P_{n}^{\prime}$. It follows that $\lim ^{\omega}\left(P_{n}^{\prime \prime}\right)=\lim ^{\omega}\left(P_{n}^{\prime}\right)=\Delta_{\delta}^{\prime}$.

Theorem 3.30 (being tree-graded is closed under ultralimits). For every $n \in \mathbb{N}$ let $\mathbb{F}_{n}$ be a complete geodesic metric space which is tree-graded with respect to a collection $\mathscr{P}_{n}$ of closed geodesic subsets of $\mathbb{F}_{n}$. Let $\omega$ be an ultrafilter over $\mathbb{N}$ and let $e \in \Pi \mathbb{F}_{n} / \omega$ be an observation point. The ultralimit $\lim ^{\omega}\left(\mathbb{F}_{n}\right)_{e}$ is tree-graded with respect to the collection of limit sets

$$
\mathscr{P}_{\omega}=\left\{\lim ^{\omega}\left(M_{n}\right) \mid M_{n} \in \mathscr{P}_{n}, \operatorname{dist}\left(e_{n}, M_{n}\right) \text { bounded uniformly in } n\right\} .
$$

Proof. Property $\left(T_{1}\right)$. Let $\lim ^{\omega}\left(M_{n}\right), \lim ^{\omega}\left(M_{n}^{\prime}\right) \in \mathscr{P}_{\omega}$ be such that there exist two distinct points $x_{\omega}, y_{\omega}$ in $\lim ^{\omega}\left(M_{n}\right) \cap \lim ^{\omega}\left(M_{n}^{\prime}\right)$. It follows that $x_{\omega}=\lim ^{\omega}\left(x_{n}\right)=\lim ^{\omega}\left(x_{n}^{\prime}\right)$ and $y_{\omega} \lim ^{\omega}\left(y_{n}\right)=\lim ^{\omega}\left(y_{n}^{\prime}\right)$,


Fig. 2. Properties $\left(F_{1}\right)$ and ( $F_{2}$ ).
where $x_{n}, y_{n} \in M_{n}, x_{n}^{\prime}, y_{n}^{\prime} \in M_{n}^{\prime}, \operatorname{dist}\left(x_{n}, x_{n}^{\prime}\right)=o(1), \operatorname{dist}\left(y_{n}, y_{n}^{\prime}\right)=o(1)$, while $\operatorname{dist}\left(x_{n}, y_{n}\right)=O(1)$, $\operatorname{dist}\left(x_{n}^{\prime}, y_{n}^{\prime}\right)=O(1)$.

By contradiction suppose that $M_{n} \neq M_{n}^{\prime} \omega$-almost surely. Then property $\left(T_{2}\right)$ of the space $\mathbb{F}_{n}$ and Corollary 2.11 imply that $M_{n}$ projects into $M_{n}^{\prime}$ in a unique point $z_{n}$ and that $z_{n} \in\left[x_{n}, x_{n}^{\prime}\right] \cap\left[y_{n}, y_{n}^{\prime}\right]$. It follows that $\operatorname{dist}\left(x_{n}, z_{n}\right)=o(1)$ and $\operatorname{dist}\left(y_{n}, z_{n}\right)=o(1)$, and therefore that $\operatorname{dist}\left(x_{n}, y_{n}\right)=o(1)$. This contradiction implies that $M_{n}=M_{n}^{\prime} \omega$-almost surely, so $\lim ^{\omega}\left(M_{n}\right)=\lim ^{\omega}\left(M_{n}^{\prime}\right)$.

Property $\left(T_{2}\right)$. Let $\Delta$ be a simple geodesic triangle in $\lim ^{\omega}\left(\mathbb{F}_{n}\right)_{e}$. Consider an arbitrary sufficiently small $\varepsilon>0$ and apply Proposition 3.29. We obtain a simple geodesic triangle $\Delta_{\varepsilon}$ satisfying properties (a), (b), (c) in the conclusion of the proposition. In particular $\Delta_{\varepsilon}=\lim ^{\omega}\left(P_{n}^{\varepsilon}\right)$, where $P_{n}^{\varepsilon}$ is a simple geodesic polygon in $\mathbb{F}_{n}$. Property $\left(T_{2}^{\prime \prime}\right)$ applied to $\mathbb{F}_{n}$ implies that $P_{n}^{\varepsilon}$ is contained in one piece $M_{n}$. Consequently $\Delta_{\varepsilon} \subset \lim ^{\omega}\left(M_{n}\right)$. Property (b) of $\Delta_{\varepsilon}$ implies that $\lim ^{\omega}\left(M_{n}\right)$ contains the three distinct middle points of the edges of $\Delta$. This and property $\left(T_{1}\right)$ already proven imply that all triangles $\Delta_{\varepsilon}$ are contained in the same $\lim ^{\omega}\left(M_{n}\right)$. Property (a) and the fact that $\lim ^{\omega}\left(M_{n}\right)$ is closed imply that $\Delta \subset \lim ^{\omega}\left(M_{n}\right)$.

Definition 3.31. Let $P$ be a polygon with quasi-geodesic edges and with a set of vertices $\mathscr{V}$. Points in $P \backslash \mathscr{V}$ are called interior points of $P$. Let $p \in P$. The inscribed radius in $p$ with respect to $P$ is either the distance from $p$ to the set $\mathcal{O}_{p}$, if $p$ is a vertex, or the distance from $p$ to the set $P \backslash \mathfrak{q}$ if $p$ is contained in the interior of the edge $\mathfrak{q}$ (Fig. 2).

Definition 3.32 (fat polygons). Let $\vartheta>0, \sigma \geqslant 1$ and $v \geqslant 4 \sigma$. We call a $k$-gon $P$ with quasi-geodesic edges $(\vartheta, \sigma, v)$-fat if the following properties hold:
$\left(F_{1}\right)$ (large comparison angles, large inscribed radii in interior points) for every edge $\mathfrak{q}$ with endpoints $\{x, y\}$ we have

$$
\operatorname{dist}\left(\mathfrak{q} \backslash \mathscr{N}_{\sigma \vartheta}(\{x, y\}), P \backslash \mathfrak{q}\right) \geqslant \vartheta ;
$$

$\left(F_{2}\right)$ (large edges, large inscribed radii in vertices) for every vertex $x$ we have

$$
\operatorname{dist}\left(x, \mathcal{O}_{x}\right) \geqslant v \vartheta .
$$

Remark 3.33. (1) For almost all applications, we can assume that $\sigma$ in that definition is equal to 2 , so the "fatness" really depends on two parameters, $\vartheta$ and $\nu$. We need $\sigma$ to make fatness preserved under quasi-isometry (see Theorem 5.1).
(2) Property $\left(F_{1}\right)$ implies that in each of the vertices $x, y$ certain comparison angles are at least $1 / \sigma$ and that in the interior points of $P$ outside $\mathscr{N}_{\sigma \vartheta}(\mathscr{V})$ the inscribed radius is at least $\vartheta$.
(3) Property $\left(F_{2}\right)$ ensures that for every edge $\mathfrak{q}$ the set $\mathfrak{q} \backslash \mathcal{N}_{\sigma \vartheta}(\{x, y\})$ has diameter at least $2 \sigma \vartheta$, in particular it is never empty. It also ensures that the inscribed radius in every vertex is at least $v \vartheta$.

Proposition 3.34 (triangles in an asymptotic cone are $\omega$-limits offat polygons). For every simple geodesic triangle $\Delta$ in $\operatorname{Con}^{\omega}(X ; e, d)$, for every sufficiently small $\varepsilon>0$ there exists $k_{0}=k_{0}(\varepsilon)$ and a simple geodesic triangle $\Delta_{\varepsilon}$ with the following properties:
(a) The Hausdorff distance between $\Delta$ and $\Delta_{\varepsilon}$ does not exceed $\varepsilon$.
(b) $\Delta_{\varepsilon}$ contains the midpoints of the edges of $\Delta$.
(c) For every $\vartheta>0$ and $v \geqslant 8$, the triangle $\Delta_{\varepsilon}$ can be written as $\lim ^{\omega}\left(P_{n}^{\varepsilon}\right)$, where each $P_{n}^{\varepsilon}$ is a geodesic $k$-gon in $X, k \leqslant k_{0}$, and $P_{n}^{\varepsilon}$ is $(\vartheta, 2, v)$-fat $\omega$-almost surely.

Proof. Proposition 3.29 applied to ( $X,\left(1 / d_{n}\right)$ dist), $\omega, e$ and $\Delta$ implies that for every $\varepsilon>0$ there exists $k_{0}=k_{0}(\varepsilon)$ and $\Delta_{\varepsilon}$ satisfying (a) and (b) and such that $\Delta_{\varepsilon}=\lim ^{\omega}\left(P_{n}\right)$, where $P_{n}$ are simple geodesic $k$-gons in $X, 3 \leqslant k \leqslant k_{0}$, such that the lengths of all edges in $P_{n}$ are $O\left(d_{n}\right) \omega$-almost surely. Remark 3.2 implies that there exists $m \in\left\{3, \ldots, k_{0}\right\}$ such that $P_{n}$ have $m$ edges $\omega$-almost surely. Let $\vartheta>0$ and $v \geqslant 8$. We modify the sequence of polygons $\left(P_{n}\right)$ so that their limit set stays the same while the polygons become $(\vartheta, 2, v)$-fat.

Let $\mathscr{V}_{n}=\left\{v_{1}^{n}, v_{2}^{n}, \ldots, v_{m}^{n}\right\}$ be the set of vertices of $P_{n}$ in the clockwise order. We denote the limit set $\lim ^{\omega}\left(\mathscr{V}_{n}\right)$ by $\mathscr{V}$, and we endow it with the clockwise order on $\Delta_{\varepsilon}$. There exists $\varrho>0$ such that for every $v \in \mathscr{V}$, the distance between $v$ and $\mathcal{O}_{v}\left(\Delta_{\varepsilon}\right)$ is at least $2 \varrho$, where $\mathcal{O}_{v}\left(\Delta_{\varepsilon}\right)$ is taken in $\Delta_{\varepsilon}$ considered as a polygon with vertices $\mathscr{V}$. It follows that $\omega$-almost surely for every $i \in\{1,2, \ldots, m\}$ we have $\operatorname{dist}\left(v_{i}^{n}, \mathcal{O}_{v_{i}^{n}}\left(P_{n}\right)\right) \geqslant \varrho d_{n}$. In particular, $\omega$-almost surely all the edges of $P_{n}$ have length at least $\varrho d_{n}$.

Convention: In what follows we use the notation $\left[v_{i}^{n}, v_{i+1}^{n}\right.$ ] for a generic edge of $P_{n}$, where $i+1$ is taken modulo $m$.

Let $\varepsilon_{n}$ be the supremum of distances $\operatorname{dist}\left(x, \mathscr{V}_{n}\right)$ for all $x \in\left[v_{i}^{n}, v_{i+1}^{n}\right] \cap \mathscr{N}_{v \vartheta}\left(\left[v_{j}^{n}, v_{j+1}^{n}\right]\right), i \neq j, i, j \in$ $\{1,2, \ldots, m\}$. Suppose that $\lim _{\omega}\left(\varepsilon_{n} / d_{n}\right)=2 \eta>0$. Then there exist $x_{n} \in\left[v_{i}^{n}, v_{i+1}^{n}\right] \cap \mathcal{N}_{v \vartheta}\left(\left[v_{j}^{n}, v_{j+1}^{n}\right]\right), i \neq$ $j, i, j \in\{1,2, \ldots, m\}$, with $\operatorname{dist}\left(x_{n}, \mathscr{V}_{n}\right) \geqslant \eta d_{n} \omega$-almost surely. Taking the $\omega$-limit, we get a contradiction with the fact that $\Delta_{\varepsilon}$ is simple. Therefore $\lim _{\omega}\left(\varepsilon_{n} / d_{n}\right)=0$.

Notation. We denote by $\mathfrak{N}$ the set of all $n \in \mathbb{N}$ such that for every $i \in\{1,2, \ldots, m\}$ we have $\operatorname{dist}\left(v_{i}^{n}, \mathcal{O}_{v_{i}^{n}}\right) \geqslant \varrho d_{n}$ and such that $\varrho d_{n} \geqslant 2 \varepsilon_{n}+2+(2 v+1) \vartheta$. Obviously $\mathfrak{\Omega} \in \omega$.

Let $\left[v_{i-1}^{n}, v_{i}^{n}\right]$ and $\left[v_{i}^{n}, v_{i+1}^{n}\right]$ be two consecutive edges of $P_{n}$. Let $\bar{v}_{i}^{n}$ be the farthest point of $v_{i}^{n}$ in $\left[v_{i-1}^{n}, v_{i}^{n}\right] \cap \mathscr{N}_{\varepsilon_{n}+1}\left(v_{i}^{n}\right)$ contained in the $v \vartheta$-tubular neighborhood of a different edge $\mathfrak{p}$ of $P_{n}$. The edge $\mathfrak{p}$ has to be at a distance at most $\varepsilon_{n}+1+v \vartheta$ from $v_{i}^{n}$. It follows that for every $n \in \mathfrak{R}$ the edge $\mathfrak{p}$ must be $\left[v_{i}^{n}, v_{i+1}^{n}\right]$. Therefore $\bar{v}_{i}^{n}$ is the farthest from $v_{i}^{n}$ point in $\left[v_{i-1}^{n}, v_{i}^{n}\right]$ contained in $\mathcal{N}_{v \vartheta}\left(\left[v_{i}^{n}, v_{i+1}^{n}\right]\right)$. Let $\tilde{v}_{i}^{n}$ be the farthest from $v_{i}^{n}$ point $t_{n} \in\left[v_{i}^{n}, v_{i+1}^{n}\right]$ such that $\operatorname{dist}\left(\bar{v}_{i}^{n}, t_{n}\right) \leqslant v \vartheta$.It follows that $\operatorname{dist}\left(\bar{v}_{i}^{n}, \tilde{v}_{i}^{n}\right)=v \vartheta$. We modify $P_{n}$ by replacing $\left[\bar{v}_{i}^{n}, v_{i}^{n}\right] \cup\left[v_{i}^{n}, \tilde{v}_{i}^{n}\right]$ with a geodesic $\left[\bar{v}_{i}^{n}, \tilde{v}_{i}^{n}\right]$. We repeat the argument for each of the vertices of $P_{n}$, and in the end we obtain a sequence of polygons $P_{n}^{\prime}$ with at most $2 m$ edges each. As the Hausdorff distance between $P_{n}^{\prime}$ and $P_{n}$ is at most $\varepsilon_{n}+1+v \vartheta, \lim ^{\omega}\left(P_{n}^{\prime}\right)=\lim ^{\omega}\left(P_{n}\right)$.

Let us show that for $n \in \mathfrak{N}, P_{n}^{\prime}$ is $(\vartheta, 2, v)$-fat.

Verification of property $\left(F_{1}\right)$ for $n \in \mathfrak{M}$.
There are two types of edges in $P_{n}^{\prime}$ : edges of the form $\left[\tilde{v}_{i}^{n}, \bar{v}_{i+1}^{n}\right]$, which we shall call restricted edges, and edges of the form $\left[\tilde{v}_{i}^{n}, \tilde{v}_{i}^{n}\right.$ ], which we shall call added edges. We denote by $R E_{n}$ the union of the restricted edges of $P_{n}^{\prime}$ and by $A E_{n}$ the union of the added edges of $P_{n}^{\prime}$.

Let $\left[\tilde{v}_{i}^{n}, \bar{v}_{i+1}^{n}\right.$ ] be a restricted edge. We first show that for $n \in \mathfrak{N}$,

$$
\operatorname{dist}\left(\left[\tilde{v}_{i}^{n}, \bar{v}_{i+1}^{n}\right] \backslash \mathscr{N}_{2 \vartheta}\left(\left\{\tilde{v}_{i}^{n}, \bar{v}_{i+1}^{n}\right\}\right), R E_{n} \backslash\left[\tilde{v}_{i}^{n}, \bar{v}_{i+1}^{n}\right]\right) \geqslant \vartheta .
$$

Suppose there exists $y$ in $\left[\tilde{v}_{i}^{n}, \bar{v}_{i+1}^{n}\right] \backslash \mathscr{N}_{2 \vartheta}\left(\left\{\tilde{v}_{i}^{n}, \bar{v}_{i+1}^{n}\right\}\right)$ contained in $\mathcal{N}_{\vartheta}\left(\left[\tilde{v}_{j}^{n}, \bar{v}_{j+1}^{n}\right]\right)$ which is inside $\mathscr{N}_{\vartheta}\left(\left[v_{j}^{n}, v_{j+1}^{n}\right]\right)$, with $j \neq i$. Then $y \in \mathscr{N}_{\varepsilon_{n}+1}\left(\left\{v_{i}^{n}, v_{i+1}^{n}\right\}\right)$. The choice of $\bar{v}_{i+1}^{n}$ implies that $y \in$ $\mathcal{N}_{\varepsilon_{n}+1}\left(v_{i}^{n}\right)$. Therefore $\operatorname{dist}\left(v_{i}^{n},\left[v_{j}^{n}, v_{j+1}^{n}\right]\right) \leqslant \varepsilon_{n}+1+\vartheta$. The previous inequality implies that $j=i-1$ for $n \in \mathfrak{N}$.

Hence there exists $t \in\left[\tilde{v}_{i-1}^{n}, \bar{v}_{i}^{n}\right]$ such that $\operatorname{dist}(t, y)<\vartheta$. By the definition of $\bar{v}_{i}^{n}$ we have $t=\bar{v}_{i}^{n}$. This contradicts the choice of $\tilde{v}_{i}^{n}$.

Now let us show that for $n \in \mathfrak{N}$,

$$
\operatorname{dist}\left(\left[\tilde{v}_{i}^{n}, \bar{v}_{i+1}^{n}\right] \backslash \mathscr{N}_{2 \vartheta}\left(\left\{\tilde{v}_{i}^{n}, \bar{v}_{i+1}^{n}\right\}\right), A E_{n}\right) \geqslant \vartheta .
$$

Suppose there exists $z$ in $\left[\tilde{v}_{i}^{n}, \bar{v}_{i+1}^{n}\right] \backslash \mathscr{N}_{2 \vartheta}\left(\left\{\tilde{v}_{i}^{n}, \bar{v}_{i+1}^{n}\right\}\right)$ contained in $\mathcal{N}_{\vartheta}\left(\left[\bar{v}_{j}^{n}, \tilde{v}_{j}^{n}\right]\right)$. It follows that $z$ belongs to the $\left(\varepsilon_{n}+v \vartheta+1\right)$-neighborhood of $v_{j}^{n}$ and that $\operatorname{dist}\left(v_{j}^{n},\left[v_{i}^{n}, v_{i+1}^{n}\right]\right) \leqslant \varepsilon_{n}+v \vartheta+1$. For $n \in \mathfrak{M}$ this implies that $j \in\{i, i+1\}$. Suppose $j=i$ (the other case is similar). Let $t \in\left[\bar{v}_{i}^{n}, \tilde{v}_{i}^{n}\right]$ with $\operatorname{dist}(t, z) \leqslant \vartheta$. Then $\operatorname{dist}\left(\tilde{v}_{i}^{n}, t\right) \geqslant \operatorname{dist}\left(\tilde{v}_{i}^{n}, z\right)-\operatorname{dist}(t, z) \geqslant 2 \vartheta-\vartheta \geqslant \operatorname{dist}(t, z)$. It follows that $\operatorname{dist}\left(\bar{v}_{i}^{n}, z\right) \leqslant \operatorname{dist}\left(\bar{v}_{i}^{n}, t\right)+$ $\operatorname{dist}(t, z) \leqslant \operatorname{dist}\left(\bar{v}_{i}^{n}, t\right)+\operatorname{dist}\left(\tilde{v}_{i}^{n}, t\right) \operatorname{dist}\left(\bar{v}_{i}^{n}, \tilde{v}_{i}^{n}\right)=v \vartheta$. This contradicts the choice of $\tilde{v}_{i}^{n}$.

Now consider an added edge $\left[\bar{v}_{i}^{n}, \tilde{v}_{i}^{n}\right] \subset B\left(v_{i}^{n}, \varepsilon_{n}+1+v \vartheta\right)$. Let $n \in \mathfrak{N}$. If there exists $u \in$ $\left[\bar{v}_{i}^{n}, \tilde{v}_{i}^{n}\right] \backslash \mathscr{N}_{2 \vartheta}\left(\left\{\bar{v}_{i}^{n}, \tilde{v}_{i}^{n}\right\}\right)$ contained in $\mathcal{N}_{\vartheta}\left(\left[\bar{v}_{j}^{n}, \tilde{v}_{j}^{n}\right]\right)$ with $j \neq i$ then $u \in \mathcal{N}_{\varepsilon_{n}+1+(v+1) \vartheta}\left(v_{j}^{n}\right)$. It follows that $\operatorname{dist}\left(v_{i}^{n}, v_{j}^{n}\right) \leqslant \operatorname{dist}\left(v_{i}^{n}, u\right)+\operatorname{dist}\left(u, v_{j}^{n}\right) \leqslant 2 \varepsilon_{n}+2+(2 v+1) \vartheta$. This contradicts the fact that $n \in \mathfrak{N}$.

If there exists $s \in\left[\bar{v}_{i}^{n}, \tilde{v}_{i}^{n}\right] \backslash \mathcal{N}_{2 \vartheta}\left(\left\{\bar{v}_{i}^{n}, \tilde{v}_{i}^{n}\right\}\right)$ contained in the $\vartheta$-tubular neighborhood of $\left[\tilde{v}_{j}^{n}, \bar{v}_{j+1}^{n}\right]$ then $v_{i}^{n} \in \mathscr{N}_{(v+1) \vartheta+\varepsilon_{n}+1}\left(\left[v_{j}^{n}, v_{j+1}^{n}\right]\right)$, which together with the hypothesis $n \in \mathfrak{N}$ implies that $j \in\{i-1, i\}$. The fact that $\operatorname{dist}\left(s, \tilde{v}_{i}^{n}\right) \geqslant 2 \vartheta$ together with the choice of $\tilde{v}_{i}^{n}$ implies that $\operatorname{dist}\left(s,\left[\tilde{v}_{i}^{n}, \bar{v}_{i+1}^{n}\right]\right) \geqslant 2 \vartheta$. The fact that $\operatorname{dist}\left(s, \bar{v}_{i}^{n}\right) \geqslant 2 \vartheta$ together with the choice of $\bar{v}_{i}^{n}$ implies that $\operatorname{dist}\left(s,\left[\tilde{v}_{i-1}^{n}, \bar{v}_{i}^{n}\right]\right) \geqslant 2 \vartheta$. Therefore $j \notin\{i-1, i\}$, a contradiction.

Verification of property $\left(F_{2}\right)$ for $n \in \mathfrak{N}$.
Let $\bar{v}=\bar{v}_{i}^{n}$ be a vertex of $P_{n}^{\prime}$ and let $v=v_{i}^{n}$. We have that $\mathcal{O}_{\bar{v}}\left(P_{n}^{\prime}\right)=\left(R E_{n} \backslash\left[\tilde{v}_{i-1}^{n}, v\right]\right) \cup\left(A E_{n} \backslash\left[\bar{v}, \tilde{v}_{i}^{n}\right]\right)$. The set $R E_{n} \backslash\left[\tilde{v}_{i-1}^{n}, \bar{v}\right]$ is composed of $\left[\tilde{v}_{i}^{n}, \bar{v}_{i+1}^{n}\right]$ and of a part $R E_{n}^{\prime}$ contained in $\mathcal{O}_{v}\left(P_{n}\right)$. By construction we have $\operatorname{dist}\left(\bar{v},\left[\tilde{v}_{i}^{n}, \bar{v}_{i+1}^{n}\right]\right) \geqslant v \vartheta$. On theother hand $\operatorname{dist}\left(\bar{v}, R E_{n}^{\prime}\right) \geqslant \operatorname{dist}\left(v, R E_{n}^{\prime}\right)-\operatorname{dist}(\bar{v}, v) \geqslant$ $\operatorname{dist}\left(v, \mathcal{O}_{v}\left(P_{n}\right)\right)-\varepsilon_{n}-1 \geqslant \varrho d_{n}-\varepsilon_{n}-1$, which is larger that $v \vartheta$ for $n \in \mathfrak{N}$.

Since $A E_{n} \backslash\left[\bar{v}, \tilde{v}_{i}^{n}\right] \subset \mathscr{N}_{\varepsilon_{n}+1+v \vartheta}\left(\mathscr{V}_{n} \backslash\{v\}\right)$ it follows that

$$
\operatorname{dist}\left(\bar{v}, A E_{n} \backslash\left[\bar{v}, \tilde{v}_{i}^{n}\right]\right) \geqslant \operatorname{dist}\left(v, \mathscr{V}_{n} \backslash\{v\}\right)-\varepsilon_{n}-1-\left(\varepsilon_{n}+1+v \vartheta\right) \geqslant \varrho d_{n}-\left(2 \varepsilon_{n}+2+v \vartheta\right) \geqslant v \vartheta
$$

for $n \in \mathfrak{n}$.
Now let $\tilde{v}=\tilde{v}_{i}^{n}$ be a vertex of $P_{n}^{\prime}$. We have that $\mathcal{O}_{\tilde{v}}\left(P_{n}^{\prime}\right)=\left(R E_{n} \backslash\left[\tilde{v}, \bar{v}_{i+1}^{n}\right]\right) \cup\left(A E_{n} \backslash[\bar{v}, \tilde{v}]\right)$. As before, we show that $\operatorname{dist}\left(\tilde{v}, A E_{n} \backslash[\bar{v}, \tilde{v}]\right) \geqslant v \vartheta$ for $n \in \mathfrak{M}$.

The set $R E_{n} \backslash\left[\tilde{v}, \bar{v}_{i+1}^{n}\right]$ is composed of $\left[\tilde{v}_{i-1}^{n}, \bar{v}\right]$ and of $R E_{n}^{\prime}$. As above, $\operatorname{dist}\left(\tilde{v}, R E_{n}^{\prime}\right) \geqslant v \vartheta$ for $n \in \mathfrak{N}$. The distance $\operatorname{dist}\left(\tilde{v},\left[\tilde{v}_{i-1}^{n}, \bar{v}\right]\right)$ is at least $v \vartheta$ by the choice of $\bar{v}$.

We conclude that for $n \in \mathfrak{M}$ the polygon $P_{n}^{\prime}$ is $(\vartheta, 2, v)$-fat.


Fig. 3. Property $\left(\alpha_{2}\right)$.

## 4. A characterization of asymptotically tree-graded spaces

In this section, we find metric conditions for a metric space to be asymptotically tree-graded with respect to a family of subsets.

Theorem 4.1 (a characterization of asymptotically tree-graded spaces). Let ( $X$, dist) be a geodesic metric space and let $\mathscr{A}=\left\{A_{i} \mid i \in I\right\}$ be a collection of subsets of $X$. The metric space $X$ is asymptotically tree-graded with respect to $\mathscr{A}$ if and only if the following properties are satisfied:
$\left(\alpha_{1}\right)$ For every $\delta>0$ the diameters of the intersections $\mathcal{N}_{\delta}\left(A_{i}\right) \cap \mathcal{N}_{\delta}\left(A_{j}\right)$ are uniformly bounded for all $i \neq j$.
$\left(\alpha_{2}\right)$ For every $\theta$ from $\left[0, \frac{1}{2}\right)$ there exists a number $M>0$ such that for every geodesic $q$ of length $\ell$ and every $A \in \mathscr{A}$ with $\mathfrak{q}(0), \mathfrak{q}(\ell) \in \mathscr{N}_{\theta \ell}(A)$ we have $\mathfrak{q}([0, \ell]) \cap \mathscr{N}_{M}(A) \neq \emptyset$.
$\left(\alpha_{3}\right)$ For every $k \geqslant 2$ there exist $\vartheta>0, v \geqslant 8$ and $\chi>0$ such that every $k$-gon $P$ in $X$ with geodesic edges which is $(\vartheta, 2, v)$-fat satisfies $P \subset \mathscr{N}_{\chi}(A)$ for some $A \in \mathscr{A}$ (Fig. 3).

Remark 4.2. (1) If the space $X$ is asymptotically uniquely geodesic (for instance asymptotically $C A T(0)$ ) then in $\left(\alpha_{3}\right)$ it is enough to consider $k=3$ (only triangles).
(2) From the proof of Theorem 4.1, it will be clear that conditions $\left(\alpha_{2}\right),\left(\alpha_{3}\right)$ can be replaced by the following stronger conditions:
$\left(\alpha_{2}^{\prime}\right)$ For every $L \geqslant 1, C \geqslant 0$, and $\theta \in\left[0, \frac{1}{2}\right.$ ) there exists $M>0$ such that for every $(L, C)$-quasi-geodesic $\mathfrak{q}$ defined on $[0, \ell]$ and every $A \in \mathscr{A}$ such that $\mathfrak{q}(0), \mathfrak{q}(\ell) \in \mathscr{N}_{\theta \ell / L}(A)$ we have $\mathfrak{q}([0, \ell]) \cap \mathscr{N}_{M}(A) \neq \emptyset$.
$\left(\alpha_{3}^{\prime}\right)$ For every $L \geqslant 1, C \geqslant 0$ and $k \geqslant 2$, and for every $\sigma \geqslant 1$ and $v \geqslant 4 \sigma$, there exist $\vartheta_{0}>0$ such that for every $\vartheta \geqslant \vartheta_{0}$ every $k$-gon $P$ with ( $L, C$ )-quasi-geodesic edges which is $\left(\vartheta, \sigma, v\right.$ )-fat is contained in $\mathscr{N}_{\chi}(A)$ for some $A \in \mathscr{A}$, where $\chi=\sigma L^{2} \vartheta+c$ with $c$ a constant independent of $\vartheta$.
(3) Also from the proof of Theorem 4.1, it will be clear that for every $\varepsilon \leqslant \frac{1}{2}$ the condition $\left(\alpha_{2}\right)$ can be replaced by the following weaker condition:
$\left(\alpha_{2}^{\varepsilon}\right)$ For every $\theta$ from $[0, \varepsilon)$ there exists a number $M>0$ such that for every geodesic $\mathfrak{q}$ of length $\ell$ and every $A \in \mathscr{A}$ with $\mathfrak{q}(0), \mathfrak{q}(\ell) \in \mathscr{N}_{\theta \ell}(A)$ we have $\mathfrak{q}([0, \ell]) \cap \mathscr{N}_{M}(A) \neq \emptyset$.
(Notice that condition $\left(\alpha_{2}\right)$ is the same as the condition $\left(\alpha_{2}^{1 / 2}\right)$.)
(4) If $\mathscr{A}=\left\{A_{i} \mid i \in I\right\}$ satisfies conditions $\left(\alpha_{1}\right),\left(\alpha_{2}\right),\left(\alpha_{3}\right)$, then the family $\mathscr{N}_{c}(\mathscr{A})=\left\{\mathscr{N}_{c}\left(A_{i}\right) \mid i \in I\right\}$ also satisfies these conditions, for every $c>0$.

Proof of Theorem 4.1. First we show that conditions $\left(\alpha_{1}\right),\left(\alpha_{2}^{\varepsilon}\right)$ (for an arbitrary $\varepsilon \leqslant \frac{1}{2}$ ) and ( $\alpha_{3}$ ) imply that $X$ is asymptotically tree-graded with respect to $\mathscr{A}$.

Lemma $4.3\left(\left(\alpha_{1}\right)\right.$ and $\left(\alpha_{2}^{\varepsilon}\right)$ imply uniform quasi-convexity). Let $(X, d)$ be a geodesic metric space and let $\mathscr{A}=\left\{A_{i} \mid i \in I\right\}$ be a collection of subsets of $X$ satisfying properties $\left(\alpha_{1}\right)$ and $\left(\alpha_{2}^{\varepsilon}\right)$ for some $\varepsilon$. Let $M_{0}=M_{0}(\theta)$ be the number from property $\left(\alpha_{2}^{\varepsilon}\right)$ corresponding to $\theta=\frac{2}{3} \varepsilon$.

There exists $t>0$ such that for every $A \in \mathscr{A}, M \geqslant M_{0}$ and $x, y \in \mathscr{N}_{M}(A)$, every geodesic joining $x$ and $y$ in $X$ is contained in $\mathscr{N}_{t M}(A)$.

Proof. Suppose, by contradiction, that for every $n \in \mathbb{N}$ there exist $M_{n} \geqslant M_{0}, x_{n}, y_{n} \in \mathscr{N}_{M_{n}}\left(A_{n}\right)$ and a geodesic $\left[x_{n}, y_{n}\right]$ not contained in $\mathscr{N}_{n M_{n}}\left(A_{n}\right)$. For every $n \geqslant 1$ let $D_{n}$ be the infimum of the distances between points $x, y \in \mathscr{N}_{M_{n}}(A)$ for some $A \in \mathscr{A}$ such that $[x, y] \not \subset \mathscr{N}_{n M_{n}}(A)$ for some geodesic $[x, y]$.

We note that $D_{n} \geqslant 2(n-1) M_{n} \geqslant 2(n-1) M_{0}$; hence $\lim _{n \rightarrow \infty} D_{n}=\infty$. For every $n \geqslant 1$, choose $x_{n}, y_{n} \in$ $\mathcal{N}_{M_{n}}\left(A_{n}\right)$ such that $\operatorname{dist}\left(x_{n}, y_{n}\right)=D_{n}+1$. Also choose $a_{n}, b_{n} \in\left[x_{n}, y_{n}\right]$ such that $\operatorname{dist}\left(x_{n}, a_{n}\right)=$ $\operatorname{dist}\left(y_{n}, b_{n}\right)=\theta\left(D_{n}+1\right) / 2$. Then $\operatorname{dist}\left(a_{n}, A_{n}\right) \leqslant \operatorname{dist}\left(a_{n}, x_{n}\right)+\operatorname{dist}\left(x_{n}, A_{n}\right) \leqslant \theta\left(D_{n}+1\right) / 2+M_{n} \leqslant \theta\left(D_{n}+\right.$ 1) $/ 2+\left(D_{n}+1\right) / 2(n-1)$. Likewise $\operatorname{dist}\left(b_{n}, A_{n}\right) \leqslant \theta\left(D_{n}+1\right) / 2+\left(D_{n}+1\right) / 2(n-1)$. On the other hand $\operatorname{dist}\left(a_{n}, b_{n}\right) \geqslant \operatorname{dist}\left(x_{n}, y_{n}\right)-\operatorname{dist}\left(x_{n}, a_{n}\right)-\operatorname{dist}\left(y_{n}, b_{n}\right) \geqslant(1-\theta)\left(D_{n}+1\right)$. For $n$ large enough we have $\theta / 2+1 / 2(n-1) \leqslant \frac{2}{3} \theta$. We apply $\left(\alpha_{2}^{\varepsilon}\right)$ with $\theta=\frac{2}{3} \varepsilon$ to $\left[a_{n}, b_{n}\right]$ and we deduce that there exists $z_{n} \in\left[a_{n}, b_{n}\right] \cap \mathscr{N}_{M_{0}}\left(A_{n}\right)$. We have that either $\left[x_{n}, z_{n}\right] \not \subset \mathcal{N}_{n M_{n}}\left(A_{n}\right)$ or $\left[z_{n}, y_{n}\right] \not \subset \mathscr{N}_{n M_{n}}\left(A_{n}\right)$, while $\operatorname{dist}\left(x_{n}, z_{n}\right), \operatorname{dist}\left(z_{n}, y_{n}\right) \leqslant(1-\theta / 2)\left(D_{n}+1\right)<D_{n}$ for $n$ large enough. This contradicts the choice of $D_{n}$.

Lemma 4.4. Let $(X, d)$ be a geodesic metric space and let $\mathscr{A}=\left\{A_{i} \mid i \in I\right\}$ be a collection of subsets of $X$ satisfying properties $\left(\alpha_{1}\right)$ and $\left(\alpha_{2}^{\varepsilon}\right)$ for some $\varepsilon$. Then in every asymptotic cone $\operatorname{Con}^{\omega}(X ; e, d)$, every set $\lim ^{\omega}\left(A_{n}\right)$ is connected and a geodesic subspace.

Proof. Indeed, consider any two points $x=\lim ^{\omega}\left(x_{n}\right), y=\lim ^{\omega}\left(y_{n}\right)$ in $\lim ^{\omega}\left(A_{n}\right)$, and geodesics $\mathfrak{q}_{n}$ connecting $x_{n}, y_{n}$ in $X$. Then by Lemma 4.3, $\mathfrak{q}_{n}$ is inside $\mathcal{N}_{M}\left(A_{n}\right)$ for some fixed $M$. Therefore the geodesic $\lim ^{\omega}\left(\mathfrak{q}_{n}\right)$ is inside $\lim ^{\omega}\left(\mathscr{N}_{M}\left(A_{n}\right)\right)=\lim ^{\omega}\left(A_{n}\right)$.

Lemma 4.5. Let $(X, d)$ be a geodesic metric space and let $\mathscr{A}=\left\{A_{i} \mid i \in I\right\}$ be a collection of subsets of $X$ satisfying properties $\left(\alpha_{1}\right)$ and $\left(\alpha_{2}^{\varepsilon}\right)$. Then in every asymptotic cone $\operatorname{Con}^{\omega}(X ; e, d)$ the collection of subsets $\mathscr{A}_{\omega}$ satisfies $\left(T_{1}\right)$.

Proof. Suppose that, in an asymptotic cone $\operatorname{Con}^{\omega}(X ; e, d)$ of $X$, the intersection $\lim ^{\omega}\left(A_{i_{n}}\right) \cap \lim ^{\omega}\left(A_{j_{n}}\right)$ contains two distinct points $\lim ^{\omega}\left(x_{n}\right), \lim ^{\omega}\left(y_{n}\right)$ but $A_{i_{n}} \neq A_{j_{n}} \omega$-almost surely. For every $n \geqslant 1$ consider a geodesic $\left[x_{n}, y_{n}\right]$. Its length $\ell_{n}$ is $O\left(d_{n}\right)$ while $\delta_{n}$ defined as the maximum of the distances $\operatorname{dist}\left(x_{n}, A_{i_{n}}\right), \operatorname{dist}\left(x_{n}, A_{j_{n}}\right), \operatorname{dist}\left(y_{n}, A_{i_{n}}\right), \operatorname{dist}\left(y_{n}, A_{j_{n}}\right)$, is $o\left(d_{n}\right)$. According to Lemma 4.3, $\left[x_{n}, y_{n}\right]$ is contained in $\mathscr{N}_{t \delta_{n}}\left(A_{i_{n}}\right) \cap \mathscr{N}_{t \delta_{n}}\left(A_{j_{n}}\right)$ for some $t>0$.

Consider $a_{n}, b_{n} \in\left[x_{n}, y_{n}\right]$ at distance $6 t \delta_{n}$ from $x_{n}$ and $y_{n}$, respectively. Property $\left(\alpha_{2}^{\varepsilon}\right)$ can be applied twice, to $\left[x_{n}, a_{n}\right] \subset\left[x_{n}, y_{n}\right]$ and $A_{i_{n}}$ (resp. $A_{j_{n}}$ ) for $n$ large enough. It implies that there exist $z_{n} \in$ $\left[x_{n}, a_{n}\right] \cap \mathscr{N}_{M_{0}}\left(A_{i_{n}}\right)$ and $z_{n}^{\prime} \in\left[x_{n}, a_{n}\right] \cap \mathscr{N}_{M_{0}}\left(A_{j_{n}}\right)$ (where $M_{0}$ is the same as in Lemma 4.3). A similar
argument for $\left[b_{n}, y_{n}\right] \subset\left[x_{n}, y_{n}\right]$ and $A_{i_{n}}$ (resp. $A_{j_{n}}$ ) implies that there exist $u_{n} \in\left[b_{n}, y_{n}\right] \cap \mathcal{N}_{M_{0}}\left(A_{i_{n}}\right)$ and $u_{n}^{\prime} \in\left[b_{n}, y_{n}\right] \cap \mathscr{N}_{M_{0}}\left(A_{j_{n}}\right)$. Hence $\left[a_{n}, b_{n}\right] \subset\left[z_{n}, u_{n}\right] \subset \mathscr{N}_{t M_{0}}\left(A_{i_{n}}\right)$ and $\left[a_{n}, b_{n}\right] \subset\left[z_{n}^{\prime}, u_{n}^{\prime}\right] \subset$ $\mathscr{N}_{t M_{0}}\left(A_{j_{n}}\right)$. It follows that $\left[a_{n}, b_{n}\right] \subset \mathscr{N}_{t M_{0}}\left(A_{i_{n}}\right) \cap \mathscr{N}_{t M_{0}}\left(A_{j_{n}}\right)$, while $\operatorname{dist}\left(a_{n}, b_{n}\right)=O\left(d_{n}\right)$. This contradicts property $\left(\alpha_{1}\right)$.

Lemma 4.6 (asymptotic $\left(T_{1}\right)$ and ( $\alpha_{3}$ ) implies asymptotic $\left(T_{2}\right)$ ). Let ( $X$, dist) be a geodesic metric space and let $\mathscr{A}=\left\{A_{i} \mid i \in I\right\}$ be a collection of subsets of $X$. Suppose that property $\left(\alpha_{3}\right)$ holds. Then every simple geodesic triangle in any asymptotic cone $\operatorname{Con}^{\omega}(X ; e, d)$ is contained in one of the sets from $\mathscr{A}_{\omega}$.

Proof. Let $\Delta$ be a simple geodesic triangle in $\operatorname{Con}^{\omega}(X ; e, d)$. Let $\varepsilon_{m}=1 / 2^{m}$ be fixed, for every large enough integer $m$. By Proposition 3.34, we can find $k_{0}$ and a simple triangle $\Delta_{m}=\Delta_{\varepsilon_{m}}=\lim ^{\omega}\left(P_{n}^{m}\right)$ satisfying properties (a),(b) and (c) for $\vartheta$ and $v \geqslant 8$ given by $\left(\alpha_{3}\right)$ for $k_{0}\left(\varepsilon_{m}\right)$. It follows that $\omega$-almost surely, $P_{n}^{m}$ are contained in $\mathscr{N}_{\chi}\left(A_{n}\right)$ for some $A_{n} \in \mathscr{A}$. We conclude that $\Delta_{m} \subset A_{\omega}=\lim ^{\omega}\left(A_{n}\right)$. By property (b) all triangles $\Delta_{m}$ have at least 3 distinct points in common (e.g. the midpoints of the edges of $\Delta$ ). This and property $\left(T_{1}\right)$ of the collection $\mathscr{A}_{\omega}$ imply that the set $A_{\omega}$ is independent of $m$. Since $\Delta$ is a Hausdorff limit of $\Delta_{m}$ and $A_{\omega}$ is closed (see Remark 3.10), we deduce that $\Delta \subset A_{\omega}$.

Lemmas $4.4,4.5$ and 4.6 show that $\left(\alpha_{1}\right),\left(\alpha_{2}^{\varepsilon}\right)$ and $\left(\alpha_{3}\right)$ imply that the space $X$ is asymptotically treegraded. Now we prove the (stronger version of the) converse statement.

Lemma 4.7 (asymptotic ( $T_{1}$ ) implies $\left(\alpha_{1}\right)$ ). Let ( $X$, dist) be a geodesic metric space asymptotically satisfying $\left(T_{1}\right)$ with respect to $\mathscr{A}$. Then $X$ satisfies $\left(\alpha_{1}\right)$ with respect to $\mathscr{A}$.

Proof. By contradiction, suppose $X$ asymptotically satisfies ( $T_{1}$ ) but for some $\delta>0$ there exists a sequence of pairs of points $x_{n}, y_{n}$ in $\mathscr{N}_{\delta}\left(A_{i_{n}}\right) \cap \mathscr{N}_{\delta}\left(A_{j_{n}}\right)$, where $A_{i_{n}}$ and $A_{j_{n}}$ are distinct sets in $\mathscr{A}$, with $\lim _{n \rightarrow \infty} \operatorname{dist}\left(x_{n}, y_{n}\right)=\infty$. Set the observation point $e$ to be $\left(x_{n}\right)^{\omega}$, and let $d_{n}=\operatorname{dist}\left(x_{n}, y_{n}\right)$ for every $n \geqslant 1$. Then $M_{1}=\lim ^{\omega}\left(A_{i_{n}}\right)$ and $M_{2}=\lim ^{\omega}\left(A_{j_{n}}\right)$ are not empty, so these are distinct pieces in $\operatorname{Con}^{\omega}(X ; e, d)$. The limits $x=\lim ^{\omega}\left(x_{n}\right)$ and $y=\lim ^{\omega}\left(y_{n}\right)$ are distinct points in $\operatorname{Con}^{\omega}(X ; e, d)$ that belong to both $M_{1}$ and $M_{2}$. This contradicts ( $T_{1}$ ).

Definition 4.8 (almost closest points). Let $x \in X, A, B \subseteq X$. A point $y \in A$ is called an almost closest to $x$ point in $A$ if $\operatorname{dist}(x, y) \leqslant \operatorname{dist}(x, A)+1$. Points $a \in A, b \in B$ are called almost closest representatives of $A$ and $B$ if $\operatorname{dist}(a, b) \leqslant \operatorname{dist}(A, B)+1$.

Definition 4.9 (almost projection). Let $x$ be a point in $X$ and $A \subset X$. The almost projection of $x$ on $A$ is the set of almost closest to $x$ points in $A$. For every subset $B$ of $X$ we define the almost projection $\operatorname{proj}_{A}(B)$ of $B$ onto $A$ as $\bigcup_{b \in B} \operatorname{proj}_{A}(b)$.

Remark 4.10. If all $A \in \mathscr{A}$ were closed sets and the space $X$ was proper (i.e. all balls in $X$ compact) then we could use closest points and usual projections instead of almost closest points and almost projections.

Lemma 4.11. If the space $X$ is asymptotically tree-graded with respect to $\mathscr{A}$ then for every $x \in X$, $A \in \mathscr{A}$, with $\operatorname{dist}(x, A)=2 d$

$$
\operatorname{diam}\left(\operatorname{proj}_{A}\left(\mathscr{N}_{d}(x)\right)=o(d)\right.
$$

Proof. Suppose there exists $\varepsilon>0$ and $x_{n} \in X, A_{n} \in \mathscr{A}$ with $\operatorname{dist}\left(x_{n}, A_{n}\right)=2 d_{n}, \lim _{n \rightarrow \infty} d_{n}=\infty$, and the projection $\operatorname{proj}_{A_{n}}\left(\mathscr{N}_{d_{n}}\left(x_{n}\right)\right)$ is of diameter at least $\varepsilon d_{n}$. Let $e=\left(x_{n}\right)$ and $d=\left(d_{n}\right)$. In the asymptotic cone $\operatorname{Con}^{\omega}(X ; e, d)$, we have the point $x=\lim ^{\omega}\left(x_{n}\right)$ at distance 2 of $A=\lim ^{\omega}\left(A_{n}\right)$, two points $y, z \in \mathcal{N}_{1}(x)$, and two points $y^{\prime}, z^{\prime}$ in $A$ such that $y^{\prime}, z^{\prime}$ are the respective projections of $y, z$ onto $A$, but $\operatorname{dist}\left(y^{\prime}, z^{\prime}\right) \geqslant \varepsilon$. This contradicts Lemma 2.8.

Lemma 4.12 (asymptotically tree-graded implies $\left.\left(\alpha_{2}^{\prime}\right)\right)$. Let ( $X$, dist) be a geodesic metric space which is asymptotically tree-graded with respect to $\mathscr{A}$. Then $X$ satisfies $\left(\alpha_{2}^{\prime}\right)$.

Proof. Fix $L \geqslant 1, C \geqslant 0$. By contradiction, suppose that for some fixed $\theta \in\left[0, \frac{1}{2}\right.$ ) there exists a sequence of $(L, C)$-quasi-geodesics $\mathfrak{q}_{n}:\left[0, \ell_{n}\right] \rightarrow X$ and a sequence of sets $A_{n} \in \mathscr{A}$, such that $\mathfrak{q}_{n}(0), \mathfrak{q}_{n}\left(\ell_{n}\right) \in$ $\mathcal{N}_{\theta \ell_{n} / L}\left(A_{n}\right)$ and $\operatorname{dist}\left(\mathfrak{q}_{n}\left(\left[0, \ell_{n}\right]\right), A_{n}\right)=2 D_{n}, \lim _{n \rightarrow \infty} D_{n}=\infty$. Since $\operatorname{dist}\left(\mathfrak{q}_{n}\left(\left[0, \ell_{n}\right]\right), A_{n}\right) \leqslant L \ell_{n}+$ $\theta \ell_{n} / L$ this implies $\lim _{n \rightarrow \infty} \ell_{n}=\infty$.

Let $t_{0}=0<t_{1}<\cdots<t_{m-1}<t_{m}=\ell_{n}$ be such that $\left(D_{n}-C\right) / 2 L \leqslant \operatorname{dist}\left(t_{i}, t_{i+1}\right) \leqslant\left(D_{n}-C\right) / L$ for all $i \in$ $\{0,1, \ldots, m-1\}$. We have $m \leqslant 3 L \ell_{n} / D_{n}$ for large enough $n$. Let $y_{i}$ be an almost projection of $\mathfrak{q}_{n}\left(t_{i}\right)$ onto $A_{n}$. According to Lemma 4.11, $\operatorname{dist}\left(y_{i}, y_{i+1}\right)=o\left(D_{n}\right)$. Consequently $\operatorname{dist}\left(\mathfrak{q}_{n}(0), \mathfrak{q}_{n}\left(\ell_{n}\right)\right) \leqslant \operatorname{dist}\left(\mathfrak{q}_{n}(0), y_{0}\right)$ $+\sum_{i=0}^{m-1} \operatorname{dist}\left(y_{i}, y_{i+1}\right)+\operatorname{dist}\left(y_{m}, \mathfrak{q}_{n}\left(\ell_{n}\right)\right) \leqslant 2 \theta \ell_{n} / L+m \cdot o\left(D_{n}\right) \leqslant 2 \theta \ell_{n} / L+3 L o(1) \ell_{n}$. On the other hand $\operatorname{dist}\left(\mathfrak{q}_{n}(0), \mathfrak{q}_{n}\left(\ell_{n}\right)\right) \geqslant \ell_{n} / L-C$. This is a contradiction with $\theta<\frac{1}{2}$.

It remains to prove that being asymptotically tree-graded implies $\left(\alpha_{3}\right)$.
Definition 4.13 (almost geodesics). If an ( $L, C$ )-quasi-geodesic $\mathfrak{q}$ is $L$-Lipschitz then $\mathfrak{q}$ will be called an (L, C)-almost geodesic.

Remark 4.14. Every ( $L, C$ )-quasi-geodesic in a geodesic metric space is at bounded (in terms of $L, C$ ) distance from an ( $L+C, C$ )-almost geodesic with the same endpoints [12, Proposition 8.3.4].

Lemma 4.15 (At is uniformly quasi-convex with respect to quasi-geodesics). Let $X$ be a geodesic metric space which is asymptotically tree-graded with respect to a collection of subsets $\mathscr{A}$. For every $L \geqslant 1$ and $C \geqslant 0$, there exists $t \geqslant 1$ such that for every $d \geqslant 1$ and for every $A \in \mathscr{A}$, every ( $L, C$ )-quasi-geodesic joining two points in $\mathscr{N}_{d}(A)$ is contained in $\mathscr{N}_{t d}(A)$.

Proof. Suppose by contradiction that there exists a sequence $\mathfrak{q}_{n}:\left[0, \ell_{n}\right] \rightarrow X$ of ( $L, C$ )-quasi-geodesics with endpoints $x_{n}, y_{n} \in \mathscr{N}_{d_{n}}\left(A_{n}\right)$ such that there exists $z_{n} \in \mathfrak{q}_{n}\left(\left[0, \ell_{n}\right]\right)$ with $k_{n}=\operatorname{dist}\left(z_{n}, A_{n}\right) \geqslant n d_{n} \geqslant n$. By Remark 4.14, we can assume that each $\mathfrak{q}_{n}$ is an $(L+C, C)$-almost geodesic. This allows us to choose $z_{n} \in \mathfrak{q}_{n}\left(\left[0, \ell_{n}\right]\right)$ so that $\operatorname{dist}\left(z_{n}, A_{n}\right)$ is maximal. In $\operatorname{Con}^{\omega}\left(X ;\left(z_{n}\right),\left(k_{n}\right)\right)$, the limit set $\mathfrak{q}=\lim ^{\omega}\left(\mathfrak{q}_{n}\right)$ is either a topological arc with endpoints in $\lim ^{\omega}\left(A_{n}\right)$ and not contained in $\lim ^{\omega}\left(A_{n}\right)$, or a bi-Lipschitz ray with origin in $\lim ^{\omega}\left(A_{n}\right)$ or a bi-Lipschitz line (Remark 3.15). Notice also that $\mathfrak{q}$ is contained in $\mathscr{N}_{1}\left(\lim ^{\omega}\left(A_{n}\right)\right)$. In all three cases we obtain a contradiction with Corollary 2.9.

Let ( $X$, dist) be a geodesic space that is asymptotically tree-graded with respect to the collection of subsets $\mathscr{A}$.

Notation. For every $L \geqslant 1, C \geqslant 0$, we denote by $M(L, C)$ the constant given by $\left(\alpha_{2}^{\prime}\right)$ for $\theta=\frac{1}{3}$. We also denote by dist the distance function in any of the asymptotic cones of $X$.

Conventions: To simplify the notations and statements, in the sequel we shall not mention the constants $L \geqslant 1$ and $C \geqslant 0$ for each quasi-geodesic anymore. We assume that all constants provided by the following lemmas in the section depend on $L$ and $C$.

Lemma 4.16. Let $\mathfrak{q}_{n}:\left[0, \ell_{n}\right] \rightarrow X, n \geqslant 1$, be a sequence of $(L, C)$-quasi-geodesics in $X$ and let $A_{n}$, $n \geqslant 1$, be a sequence of sets in $\mathscr{A}$. Suppose that $\operatorname{dist}\left(\mathfrak{q}_{n}(0), A_{n}\right)=o\left(\ell_{n}\right), \operatorname{dist}\left(\mathfrak{q}_{n}\left(\ell_{n}\right), A_{n}\right)=o\left(\ell_{n}\right) \omega$ almost surely. Then there exists $t_{n}^{1} \in\left[0, \frac{1}{3} \ell_{n}\right], t_{n}^{2} \in\left[\frac{2}{3} \ell_{n}, \ell_{n}\right]$ such that $\mathfrak{q}_{n}\left(t_{n}^{i}\right) \in \mathcal{N}_{M}\left(A_{n}\right), i=1$, 2, where $M=M(L, C), \omega$-almost surely.

Proof. By Lemma 4.15, the quasi-geodesic $\mathfrak{q}_{n}$ is inside $\mathcal{N}_{t_{n}}\left(A_{n}\right)$ for $t_{n}=o\left(\ell_{n}\right)$. It remains to apply ( $\alpha_{2}^{\prime}$ ) to the quasi-geodesics $\mathfrak{q}_{n}\left(\left[0, \frac{1}{3} \ell_{n}\right]\right)$ and $\mathfrak{q}_{n}\left(\left[\frac{2}{3} \ell_{n}, \ell_{n}\right]\right)$.

Lemma 4.17 (linear divergence). For every $\varepsilon>0$ and every $M \geqslant M(L, C)$ there exists $t_{\varepsilon}>0$ such that if $A \in \mathscr{A}, \mathfrak{q}$ is a quasi-geodesic with origin $a \in \mathscr{N}_{M}(A)$, such that $\mathfrak{q} \cap \mathscr{N}_{M}(A)=\{a\}$ and $t \geqslant t_{\varepsilon}$, then

$$
\operatorname{dist}(\mathfrak{q}(t), A)>(1-\varepsilon) \operatorname{dist}(\mathfrak{q}(t), a) .
$$

Proof. We suppose that for some $\varepsilon>0$ there exists a sequence $A_{n} \in \mathscr{A}$, a sequence $\mathfrak{q}_{n}$ of quasi-geodesics with origin $a_{n} \in \mathscr{N}_{M}\left(A_{n}\right)$ such that $\mathfrak{q}_{n} \cap \mathscr{N}_{M}\left(A_{n}\right)=\left\{a_{n}\right\}$, and a sequence of numbers $t_{n} \rightarrow \infty$ with the property

$$
\operatorname{dist}\left(\mathfrak{q}_{n}\left(t_{n}\right), A_{n}\right) \leqslant(1-\varepsilon) \operatorname{dist}\left(\mathfrak{q}_{n}\left(t_{n}\right), a_{n}\right)
$$

In $\operatorname{Con}^{\omega}\left(X ;\left(a_{n}\right),\left(t_{n}\right)\right)$, we obtain the points $a=\lim ^{\omega}\left(a_{n}\right) \in \lim ^{\omega}\left(A_{n}\right)$ and $b=\lim ^{\omega}\left(\mathfrak{q}_{n}\left(t_{n}\right)\right)$, joined by the bi-Lipschitz arc $\mathfrak{q}([0,1])=\lim ^{\omega}\left(\mathfrak{q}_{n}\left(\left[0, t_{n}\right]\right)\right)$, such that

$$
\operatorname{dist}\left(b, \lim ^{\omega}\left(A_{n}\right)\right) \leqslant(1-\varepsilon) \operatorname{dist}(b, a)
$$

It follows that the projection of $b$ on $\lim ^{\omega}\left(A_{n}\right)$ is a point $c \neq a$. Corollary 2.11 implies that $\mathfrak{q}([0,1])$ contains $c$ and Corollary 2.10 implies that a sub-arc $\mathfrak{q}([0,2 \beta])$ of $\mathfrak{q}([0,1])$ is contained in $\lim ^{\omega}\left(A_{n}\right)$. We apply Lemma 4.16 to the sub-quasi-geodesic $\mathfrak{q}_{n}\left(\left[0, \beta t_{n}\right]\right)$ and obtain that this sub-quasi-geodesics intersects $\mathscr{N}_{M}\left(A_{n}\right)$ in a point different from $a_{n}$, a contradiction.

Lemma 4.18. For every $\varepsilon>0, \delta>0$ and $M \geqslant M(L, C)$ there exists $D>0$ such that for every $A \in \mathscr{A}$ and every two quasi-geodesics $\mathfrak{q}_{i}:\left[0, \ell_{i}\right] \rightarrow X, i=1,2$, that connect $a \in \mathscr{N}_{M}(A)$ with two points $b_{1}$ and $b_{2}$, respectively, if the diameter of $\mathfrak{q}_{1} \cap \mathscr{N}_{M}(A)$ does not exceed $\delta, b_{2} \in \mathcal{N}_{M}(A)$, and $\operatorname{dist}\left(a, b_{2}\right) \geqslant D$ then

$$
\operatorname{dist}\left(b_{1}, b_{2}\right) \geqslant \frac{1}{L+\varepsilon}\left(\ell_{1}+\ell_{2}\right) .
$$

Proof. Suppose there exist sequences $\mathfrak{q}_{i}^{(n)}:\left[0, \ell_{i}^{(n)}\right] \rightarrow X, i=1,2, n \geqslant 1$, of pairs of quasi-geodesics joining $a^{(n)} \in \mathscr{N}_{M}\left(A_{n}\right)$ to $b_{i}^{(n)}$ such that $\mathfrak{q}_{1}^{(n)} \cap \mathscr{N}_{M}\left(A_{n}\right)$ has diameter at most $\delta, b_{2}^{(n)} \in \mathscr{N}_{M}\left(A_{n}\right)$, $\lim _{n \rightarrow \infty} \operatorname{dist}\left(a^{(n)}, b_{2}^{(n)}\right)=\infty$, but

$$
\begin{equation*}
\operatorname{dist}\left(b_{1}^{(n)}, b_{2}^{(n)}\right) \leqslant \frac{1}{L+\varepsilon}\left(\ell_{1}^{(n)}+\ell_{2}^{(n)}\right) \tag{5}
\end{equation*}
$$



Fig. 4. Lemma 4.19.

Denote $\operatorname{dist}\left(a^{(n)}, b_{1}^{(n)}\right)$ by $f_{n}$ and $\operatorname{dist}\left(a^{(n)}, b_{2}^{(n)}\right)$ by $d_{n}$. Since $\ell_{1}^{(n)} \leqslant L\left(f_{n}+C\right), \ell_{2}^{(n)} \leqslant L\left(d_{n}+C\right)$, for every large enough $n$ the inequality (5) implies that

$$
\begin{equation*}
\operatorname{dist}\left(b_{1}^{(n)}, b_{2}^{(n)}\right) \leqslant(1-\gamma)\left(f_{n}+d_{n}\right) \tag{6}
\end{equation*}
$$

for some $\gamma>0$.
Case I. Suppose that $\lim ^{\omega}\left(f_{n} / d_{n}\right)<\infty$. In the asymptotic cone $\operatorname{Con}^{\omega}\left(X ;\left(a_{n}\right),\left(d_{n}\right)\right)$, the two points $\lim ^{\omega}\left(b_{i}^{(n)}\right), i=1,2$, are joined by the Lipschitz $\operatorname{arc}_{\lim }{ }^{\omega}\left(\mathfrak{q}_{1}^{(n)}\right) \cup \lim ^{\omega}\left(\mathfrak{q}_{2}^{(n)}\right)$ (it is Lipschitz as any union of two Lipschitz arcs). Lemma 4.17 implies that

$$
\lim ^{\omega}\left(\mathfrak{q}_{1}^{(n)}\right) \cap \lim ^{\omega}\left(\mathfrak{q}_{2}^{(n)}\right)=\lim ^{\omega}\left(a^{(n)}\right)
$$

(here we use the fact that the diameters of the intersections $\mathfrak{q}_{1}^{(n)}$ with $\mathscr{N}_{M}\left(A_{n}\right)$ are uniformly bounded, so we can cut a comparatively little piece of each $\mathfrak{q}_{1}^{(n)}$ to make it satisfy the conditions of Lemma 4.17).

Thus the points $\lim ^{\omega}\left(b_{i}^{(n)}\right)$ are joined by the simple $\operatorname{arc}^{\lim }{ }^{\omega}\left(\mathfrak{q}_{1}^{(n)}\right) \cup \lim ^{\omega}\left(\mathfrak{q}_{2}^{(n)}\right)$. This and property $\left(T_{2}^{\prime}\right)$ imply that every geodesic joining $\lim ^{\omega}\left(b_{1}^{(n)}\right)$ and $\lim ^{\omega}\left(b_{2}^{(n)}\right)$ contains $\lim ^{\omega}\left(a^{(n)}\right)$. Therefore

$$
\operatorname{dist}\left(\lim ^{\omega}\left(b_{1}^{(n)}\right), \lim ^{\omega}\left(b_{2}^{(n)}\right)\right)=\operatorname{dist}\left(\lim ^{\omega}\left(b_{1}^{(n)}\right), \lim ^{\omega}\left(a^{(n)}\right)\right)+\operatorname{dist}\left(\lim ^{\omega}\left(a^{(n)}\right), \lim ^{\omega}\left(b_{2}^{(n)}\right)\right)
$$

This contradicts inequality (6).
Case II. Suppose that $\lim _{\omega}\left(f_{n} / d_{n}\right)=\infty$. In the asymptotic cone $\operatorname{Con}^{\omega}\left(X ;\left(a^{(n)}\right),\left(f_{n}\right)\right)$, we denote $a=\lim ^{\omega}\left(a^{(n)}\right)=\lim ^{\omega}\left(b_{2}^{(n)}\right) \in \lim ^{\omega}\left(A_{n}\right)$ and $b=\lim ^{\omega}\left(b_{1}^{(n)}\right)$. Then inequality (6) implies that $\operatorname{dist}(a, b) \leqslant$ $(1-\gamma) \operatorname{dist}(a, b)$, a contradiction.

Lemma 4.19. For every $M \geqslant M(L, C), \varepsilon>0$ and $\delta>0$ there exists $D^{\prime}>0$ such that for every $A \in \mathscr{A}$, and every two quasi-geodesics $\mathfrak{q}_{i}:\left[0, \ell_{i}\right] \rightarrow X, i=1,2$, joining $a$ in $\mathcal{N}_{M}(A)$ with $b_{i}$, if the diameter of $\mathfrak{q}_{1} \cap \mathcal{N}_{M}(A)$ does not exceed $\delta, b_{2} \in \mathscr{N}_{M}(A)$, dist $\left(a, b_{2}\right) \geqslant D^{\prime}$, then the union $\mathfrak{q}_{1} \sqcup \mathfrak{q}_{2}$ of these two quasi-geodesics is an ( $L+\varepsilon, K$ )-quasi-geodesic, where $K=2 D^{\prime}$ (Fig. 4).

Proof. Let $\mathfrak{q}=\mathfrak{q}_{1} \sqcup \mathfrak{q}_{2}:\left[0, \ell_{1}+\ell_{2}\right] \rightarrow X$. For every $\left[t_{1}, t_{2}\right] \subset\left[0, \ell_{1}+\ell_{2}\right]$ we have

$$
\operatorname{dist}\left(\mathfrak{q}\left(t_{1}\right), \mathfrak{q}\left(t_{2}\right)\right) \leqslant L\left(t_{2}-t_{1}\right)+2 C
$$

by the triangular inequality. This implies $\operatorname{dist}\left(\mathfrak{q}\left(t_{1}\right), \mathfrak{q}\left(t_{2}\right)\right) \leqslant(L+\varepsilon)\left(t_{2}-t_{1}\right)+K$, for $K \geqslant 2 C$. We need to prove that for some well-chosen $K$ we have

$$
\begin{equation*}
\frac{1}{L+\varepsilon}\left(t_{2}-t_{1}\right)-K \leqslant \operatorname{dist}\left(\mathfrak{q}\left(t_{1}\right), \mathfrak{q}\left(t_{2}\right)\right) . \tag{7}
\end{equation*}
$$

We consider the constant $D$ given by Lemma 4.18 and set $D^{\prime}=2 L^{2}(D+C)+C$ and $K=2 D^{\prime}$. The hypothesis $\operatorname{dist}\left(a, b_{2}\right) \geqslant D^{\prime}$ implies that $\ell_{2} \geqslant 2 L(D+C)$.

Let $\left[t_{1}, t_{2}\right] \subset\left[0, \ell_{1}+\ell_{2}\right]$. If $t_{2}-t_{1}$ is smaller than $2 L(D+C)$ then (7) obviously holds. Suppose that $t_{2}-t_{1} \geqslant 2 L(D+C)$. If $\left[t_{1}, t_{2}\right] \cap\left[\ell_{1}, \ell_{1}+\ell_{2}\right]$ is an interval of length at least $L(D+C)$ then the distance between $\mathfrak{q}\left(\ell_{1}\right)$ and $\mathfrak{q}\left(t_{2}\right)$ is bigger than $D$. Lemma 4.18 implies (7).

The same inequality is true if $\left(t_{1}, t_{2}\right)$ does not contain $\ell_{1}$. Suppose that $\left[t_{1}, t_{2}\right] \cap\left[\ell_{1}, \ell_{1}+\ell_{2}\right]$ is a non-trivial interval of length at most $L(D+C)$. Then

$$
\begin{aligned}
\operatorname{dist}\left(\mathfrak{q}\left(t_{1}\right), \mathfrak{q}\left(t_{2}\right)\right) & \geqslant \operatorname{dist}\left(\mathfrak{q}\left(t_{1}\right), \mathfrak{q}\left(\ell_{1}\right)\right)-\operatorname{dist}\left(\mathfrak{q}\left(t_{2}\right), \mathfrak{q}\left(\ell_{1}\right)\right) \\
& \geqslant \frac{1}{L}\left(\ell_{1}-t_{1}\right)-D^{\prime} \geqslant \frac{1}{L}\left(t_{2}-t_{1}\right)-2 D^{\prime}
\end{aligned}
$$

and (7) holds.
Definition 4.20 (saturations). For every ( $L, C$ )-quasi-geodesic $\mathfrak{q}$ in $X$ we define the saturation $\operatorname{Sat}(\mathfrak{q})$ as the union of $\mathfrak{q}$ and all $A \in \mathscr{A}$ with $\mathscr{N}_{M}(A) \cap \mathfrak{q} \neq \emptyset$.

Lemma 4.21. Let $\mathfrak{q}_{n}$ be a sequence of ( $L, C$ )-quasi-geodesics in $X$. In every asymptotic cone Con ${ }^{\omega}$ $(X ; e, d)$ if the limit $\lim ^{\omega}\left(\operatorname{Sat}\left(\mathfrak{q}_{n}\right)\right)$ is not empty then it is either a piece $\lim ^{\omega}\left(A_{n}\right)$ from $\mathscr{A}_{\omega}$, or the union of $\mathfrak{p}=\lim ^{\omega}\left(\mathfrak{q}_{n}\right)$ and a collection of pieces from $\mathscr{A}_{\omega}$ such that each piece intersects $\lim ^{\omega}\left(\mathfrak{q}_{n}\right)$ in at least one point and all pieces from $\mathscr{A}_{\omega}$ that intersect $\lim ^{\omega}\left(\mathfrak{q}_{n}\right)$ in a non-trivial sub-arc are in the collection (recall that by Corollary 2.10 if a piece in a tree-graded space intersects an arc in more than two points then it intersects the arc by a sub-arc).

Proof. Case I. Suppose that $\lim _{\omega}\left(\operatorname{dist}\left(e_{n}, \mathfrak{q}_{n}\right) / d_{n}\right)<\infty$. Let $u_{n} \in \mathfrak{q}_{n}$ be an almost closest point to $e_{n}$ in $\mathfrak{q}_{n}$.

Suppose that a piece $A=\lim ^{\omega}\left(A_{n}\right)$ intersects $\mathfrak{q}=\lim ^{\omega}\left(\mathfrak{q}_{n}\right)$ in an arc $\mathfrak{q}\left(\left[t_{1}, t_{2}\right]\right), t_{1}<t_{2}$. This arc is a limit of sub-quasi-geodesics $\mathfrak{q}_{n}^{\prime}$ of $\mathfrak{q}_{n}$ defined on intervals of length $\left(t_{2}-t_{1}\right) d_{n}$. The ends of $\mathfrak{q}_{n}^{\prime}$ are at distance $o\left(d_{n}\right)$ from $A_{n} \omega$-almost surely. Lemma 4.16 implies that $\omega$-almost surely $A_{n} \subseteq \operatorname{Sat}\left(\mathfrak{q}_{n}\right)$ since $\operatorname{diam}\left(\mathcal{N}_{M}\left(A_{n}\right) \cap \mathfrak{q}_{n}\right)=O\left(d_{n}\right)$.

Suppose $A$ is such that $A_{n} \subseteq \operatorname{Sat}\left(\mathfrak{q}_{n}\right)$ and $\lim _{\omega}\left(\operatorname{dist}\left(e_{n}, A_{n}\right) / d_{n}\right)<\infty$. Let $a_{n}$ be an almost nearest point to $u_{n}$ in $\mathfrak{q}_{n} \cap \mathscr{N}_{M}\left(A_{n}\right)$. Lemma 4.15 implies that the sub-arc $\mathfrak{q}_{n}^{\prime}$ of $\mathfrak{q}_{n}$ with endpoints $u_{n}$ and $a_{n}$ is contained $\omega$-almost surely in $\mathcal{N}_{t_{n}}\left(A_{n}\right)$ for some number $t_{n}=O\left(d_{n}\right)$. If $\lim _{\omega}\left(\operatorname{dist}\left(u_{n}, a_{n}\right) / d_{n}\right)=\infty$ then by applying Lemma 4.16 we obtain ( $\omega$-almost surely) a point in $\mathfrak{q}_{n} \cap \mathcal{N}_{M}\left(A_{n}\right)$ nearer to $u_{n}$ than $a_{n}$ by a distance $O\left(d_{n}\right)$, a contradiction. Hence $\lim _{\omega} \operatorname{dist}\left(u_{n}, a_{n}\right) / d_{n}<\infty$. Then $a=\lim ^{\omega}\left(a_{n}\right)$ exists and is an intersection point of $A$ with $\mathfrak{q}$.

Case II. Suppose that $\lim _{\omega}\left(\operatorname{dist}\left(e_{n}, \mathfrak{q}_{n}\right) / d_{n}\right)=\infty$. Let $A_{n} \subset \operatorname{Sat}\left(\mathfrak{q}_{n}\right)$ be such that $\lim _{\omega}\left(\operatorname{dist}\left(e_{n}, A_{n}\right) /\right.$ $\left.d_{n}\right)<\infty$. We have $A=\lim ^{\omega}\left(A_{n}\right) \subseteq \lim ^{\omega}\left(\operatorname{Sat}\left(\mathfrak{q}_{n}\right)\right)$. Suppose there exists $B=\lim ^{\omega}\left(B_{n}\right) \subset \lim ^{\omega}\left(\operatorname{Sat}\left(\mathfrak{q}_{n}\right)\right)$ with $B \neq A$ whence $B_{n} \neq A_{n} \omega$-almost surely.

For every $n \geqslant 1$, let $y_{n}$ be an almost closest to $e_{n}$ point in $A_{n}$. Also pick $b_{n}=\mathfrak{q}_{n}\left(t_{n}\right) \in \mathscr{N}_{M}\left(B_{n}\right)$. If $\operatorname{dist}\left(t_{n}, \mathfrak{q}_{n}^{-1}\left(\mathscr{N}_{M}\left(A_{n}\right)\right)\right)=0$ then we set $s_{n}=t_{n}$. Otherwise let $s_{n}$ be the almost closest to $t_{n}$ number in $\mathfrak{q}_{n}^{-1}\left(\mathcal{N}_{M}\left(A_{n}\right)\right)$. We assume that $s_{n} \leqslant t_{n}$ otherwise we can reverse the orientation of $\mathfrak{q}_{n}$. Then the diameter of the intersection of $\mathfrak{q}_{n}\left(\left[s_{n}, t_{n}\right]\right)$ with $\mathscr{N}_{M}\left(A_{n}\right)$ is bounded in terms of $L$, $C$. By Lemma 4.19, $\mathfrak{r}_{n}=\left[y_{n}, \mathfrak{q}_{n}\left(s_{n}\right)\right] \cup \mathfrak{q}_{n}\left(\left[s_{n}, t_{n}\right]\right)$ is an $(L+\varepsilon, K)$-quasi-geodesic where $\left[y_{n}, \mathfrak{q}_{n}\left(s_{n}\right)\right]$ is any geodesic connecting $y_{n}$ and $\mathfrak{q}_{n}\left(s_{n}\right)$ in $X$.

Notice that $\operatorname{dist}\left(y_{n}, B_{n}\right) \leqslant O\left(d_{n}\right), \mathfrak{q}_{n}\left(t_{n}\right) \in B_{n}$. Then by Lemma 4.15, $\mathrm{r}_{n} \subseteq \mathcal{N}_{O\left(d_{n}\right)}\left(B_{n}\right) \omega$-almost surely. Applying Lemma 4.16 we find $y_{n}^{\prime}, a_{n}^{\prime}$ in $\left[y_{n}, \mathfrak{q}_{n}\left(s_{n}\right)\right]$ with $\operatorname{dist}\left(y_{n}^{\prime}, a_{n}^{\prime}\right)=O\left(d_{n}\right)$ which belong to both $\mathcal{N}_{M}\left(A_{n}\right)$ and $\mathscr{N}_{M}\left(B_{n}\right)$. This contradicts property $\left(\alpha_{1}\right)$.

Thus we can conclude that there is no sequence $B_{n} \subset \operatorname{Sat}\left(\mathfrak{q}_{n}\right)$ with $B_{n} \neq A_{n} \omega$-almost surely, such that $\lim _{\omega}\left(\operatorname{dist}\left(e_{n}, B_{n}\right) / d_{n}\right)<\infty$. Hence in this case $\lim ^{\omega}\left(\operatorname{Sat}\left(\mathfrak{q}_{n}\right)\right)=A$.

Lemma 4.22. For every $d>0$, every (L,C)-quasi-geodesic $\mathfrak{q}$ and every $A \in \mathscr{A}, \mathcal{N}_{M}(A) \cap \mathfrak{q}=\emptyset$, the diameter of $\mathscr{N}_{d}(A) \cap \mathscr{N}_{d}(\operatorname{Sat}(\mathfrak{q}))$ is bounded in terms of d, L, C.

Proof. Suppose that for some $d>0$ and some ( $L, C$ ) there exist sequences of ( $L, C$ )-quasi-geodesics $\mathfrak{q}_{n}$, of sets $A_{n} \in \mathscr{A}, A_{n} \not \subset \operatorname{Sat}\left(\mathfrak{q}_{n}\right)$, and of points $x_{n}, y_{n} \in \mathcal{N}_{d}\left(A_{n}\right) \cap \mathcal{N}_{d}\left(\operatorname{Sat}\left(\mathfrak{q}_{n}\right)\right)$ such that the sequence $\operatorname{dist}\left(x_{n}, y_{n}\right)=p_{n}$ is unbounded. Consider the corresponding asymptotic cone $\operatorname{Con}^{\omega}\left(X ;\left(x_{n}\right),\left(p_{n}\right)\right)$. The limit sets $\lim ^{\omega}\left(A_{n}\right)$ and $\lim ^{\omega}\left(\operatorname{Sat}\left(\mathfrak{q}_{n}\right)\right)$ contain points $x=\lim ^{\omega}\left(x_{n}\right)$ and $y=\lim ^{\omega}\left(y_{n}\right)$ in common, $\operatorname{dist}(x, y)=1$. By Lemma 4.21, either $\lim ^{\omega}\left(\operatorname{Sat}\left(\mathfrak{q}_{n}\right)\right)$ is $\lim ^{\omega}\left(A_{n}^{\prime}\right)$ with $A_{n}^{\prime} \in \mathscr{A}, A_{n}^{\prime} \neq A_{n}(\omega$-almost surely, or $\lim ^{\omega}\left(\operatorname{Sat}\left(\mathfrak{q}_{n}\right)\right)$ is equal to $Y(\mathfrak{q})$ where $\mathfrak{q}$ is the $\operatorname{arc} \lim ^{\omega}\left(\mathfrak{q}_{n}\right)$, and $\lim ^{\omega}\left(A_{n}\right) \not \subset \lim ^{\omega}\left(\operatorname{Sat}\left(\mathfrak{q}_{n}\right)\right)$. In the first case we get a contradiction with property $\left(T_{1}\right)$ for $\mathscr{A}$. In the second case we get a contradiction with Lemma 2.23(2).

Lemma 4.23 (uniform variant of Lemma 4.11 for saturations). For every $x \in X$ and every $(L, C)$-quasigeodesic $\mathfrak{q}$ in $X$ with $\operatorname{dist}(x, \operatorname{Sat}(\mathfrak{q}))=2 d$,

$$
\operatorname{diam}\left(\operatorname{proj}_{\operatorname{Sat}(\mathrm{q})}\left(\mathcal{N}_{d}(x)\right)=o(d)\right.
$$

Proof. By contradiction, suppose that there exists a sequence of quasi-geodesics $\mathfrak{q}_{n}$ and points $x_{n}$ with $\lim _{\omega} \operatorname{dist}\left(x_{n}, \operatorname{Sat}\left(\mathfrak{q}_{n}\right)\right)=2 d_{n}$ such that $\lim _{\omega} d_{n}=\infty$, and the almost projection of $\mathcal{N}_{d_{n}}\left(x_{n}\right)$ on $\operatorname{Sat}\left(\mathfrak{q}_{n}\right)$ has diameter at least $t d_{n}$ for some fixed $t$. In the asymptotic cone $\operatorname{Con}^{\omega}\left(X,\left(x_{n}\right),\left(d_{n}\right)\right)$ we have, according to Lemma 4.21, that $\lim ^{\omega}\left(\operatorname{Sat}\left(\mathfrak{q}_{n}\right)\right)$ is either one piece or a set of type $Y$. We apply Lemma 2.23(2), and get a contradiction.

Lemma 4.24 (uniform property ( $\alpha_{2}^{\prime}$ ) for saturations). For every $\lambda \geqslant 1, \kappa \geqslant 0$ and $\theta \in\left[0, \frac{1}{2}\right.$ ) there exists $R$ such that for every $(\lambda, \kappa)$-quasi-geodesic $c:[0, \ell] \rightarrow X$ joining two points in $\mathscr{N}_{\theta \ell / L}(\operatorname{Sat}(\mathfrak{q}))$, where $\mathfrak{q}$ is a quasi-geodesic, we have $\mathfrak{c}([0, \ell]) \cap \mathscr{N}_{R}(\operatorname{Sat}(\mathfrak{q})) \neq \emptyset$ (in particular, the constant $R$ does not depend on $\mathfrak{q}$ ).

Proof. One can simply repeat the argument of Lemma 4.12 but use Lemma 4.23 instead of Lemma 4.11.

Lemma 4.25 (uniform quasi-convexity of saturations). For every $\lambda \geqslant 1, \kappa \geqslant 0$, there exists $\tau$ such that for every $R \geqslant 1$, for every quasi-geodesic $\mathfrak{q}$, the saturation $\operatorname{Sat}(\mathfrak{q})$ has the property that every $(\lambda, \kappa)$ -quasi-geodesic $\mathfrak{c}$ joining two points in its $R$-tubular neighborhood is entirely contained in its $\tau R$-tubular neighborhood.

Proof. By Remark 4.14, it is enough to prove the statement for $(\lambda, \kappa)$-almost geodesics c. Suppose there exists a sequence of quasi-geodesics $\mathfrak{q}_{n}$, a sequence of numbers $R_{n} \geqslant 1$, a sequence $\mathfrak{c}_{n}$ of $(\lambda, \kappa)$-almost geodesics joining the points $x_{n}, y_{n}$ in the $R_{n}$-tubular neighborhood of $\operatorname{Sat}\left(\mathfrak{q}_{n}\right)$ such that $\mathfrak{c}_{n}$ is not contained in the $n R_{n}$-tubular neighborhood of $\operatorname{Sat}\left(\mathfrak{q}_{n}\right)$.

Let $z_{n} \in \mathfrak{c}_{n}$ be such that $d_{n}=\operatorname{dist}\left(z_{n}, \operatorname{Sat}\left(\mathfrak{q}_{n}\right)\right)$ is maximal. By Lemma 4.21, in the asymptotic cone $\operatorname{Con}^{\omega}\left(X ;\left(z_{n}\right),\left(d_{n}\right)\right)$, we have that $S=\lim ^{\omega}\left(\operatorname{Sat}\left(\mathfrak{q}_{n}\right)\right)$ is either one piece or a set $Y(\mathfrak{q})$ of type $Y$. On the other hand by Remark $3.15 \lim ^{\omega}\left(\mathfrak{c}_{n}\right)$ is either a topological arc with endpoints in $S$ and not contained in it, or a bi-Lipschitz ray with origin in $S$ or a bi-Lipschitz line. In addition, $\lim ^{\omega}\left(c_{n}\right)$ is contained in $\mathscr{N}_{1}(S)$. In all three cases Lemma 2.23(2) and Corollary 2.9 give a contradiction.

Lemma 4.26 (saturations of polygonal lines). Let $X$ be a geodesic metric space. Then the following is true for every $k \geqslant 1$.
(1) For every $n \geqslant 1$, let $\bigcup_{i=1}^{k} \mathfrak{q}_{i}^{(n)}$ be a polygonal line composed of (L,C)-quasi-geodesics $\mathfrak{q}_{i}^{(n)}$. Then in every asymptotic cone the limit set $\lim ^{\omega}\left(\bigcup_{i=1}^{k} \operatorname{Sat}\left(\mathfrak{q}_{i}^{(n)}\right)\right)=\bigcup_{i=1}^{k} \lim ^{\omega}\left(\operatorname{Sat}\left(\mathfrak{q}_{i}^{(n)}\right)\right)$ is either a piece or a connected union of sets of type $Y$ (as in Lemma 2.23(3)).
(2) The results in Lemmas $4.23,4.24,4.25$ are true if we replace $\operatorname{Sat}(\mathfrak{q})$ with $\bigcup_{i=1}^{k} \operatorname{Sat}\left(\mathfrak{q}_{i}\right)$, where $\bigcup_{i=1}^{k} \mathfrak{q}_{i}$ is a polygonal line composed of ( $L, C$ )-quasi-geodesics.
(3) For every $\delta>0$, for every polygonal line $\bigcup_{i=1}^{k} \mathfrak{q}_{i}$ composed of ( $L, C$ )-quasi-geodesics, and every $A \in \mathscr{A}$ such that $A \not \subset \bigcup_{i=1}^{k} \operatorname{Sat}\left(\mathfrak{q}_{i}\right)$, the intersection $\mathcal{N}_{\delta}(A) \cap \mathscr{N}_{\delta}\left(\bigcup_{i=1}^{k} \operatorname{Sat}\left(\mathfrak{q}_{i}\right)\right)$ has a uniformly bounded diameter in terms of $A, \mathfrak{q}_{1}, \ldots, \mathfrak{q}_{k}$.

Proof. We prove simultaneously (1), (2) and (3) by induction on $k$. For $k=1$ all three statements are true. Suppose they are true for $i \leqslant k$. We prove them for $k+1$. We note that (1) implies (2) in the same way as Lemma 4.21 implies the cited lemmas, and the implication (1) $\Rightarrow$ (3) follows from Lemma 2.23(3) (the argument is essentially the same as in Lemma 4.22). Thus it is enough to prove part (1).

Let $\operatorname{Con}^{\omega}(X ; e, d)$ be an asymptotic cone. We suppose that

$$
\lim _{\omega} \frac{\operatorname{dist}\left(e_{n}, \bigcup_{i=1}^{k+1} \operatorname{Sat}\left(q_{i}^{(n)}\right)\right)}{d_{n}}<\infty
$$

(otherwise the $\omega$-limit is empty). There are two possible situations.
Case I. Suppose that there exists an integer $i$ between 2 and $k$ such that

$$
\lim _{\omega} \frac{\operatorname{dist}\left(e_{n}, \operatorname{Sat}\left(\mathfrak{q}_{i}^{(n)}\right)\right)}{d_{n}}<\infty
$$

By the inductive hypothesis $\lim ^{\omega}\left(\bigcup_{j=1}^{i} \operatorname{Sat}\left(\mathfrak{q}_{j}^{(n)}\right)\right)$ is a set of type $Y$, and so is the set

$$
\lim ^{w}\left(\bigcup_{j=i}^{k+1} \operatorname{Sat}\left(\mathfrak{q}_{j}^{(n)}\right)\right)
$$

These two sets have a common non-empty subset $\lim ^{\omega}\left(\operatorname{Sat}\left(\mathfrak{q}_{i}^{(n)}\right)\right)$. Since a connected union of two sets of type $Y$ is again a set of type $Y$, statement (1) follows.

Case II. Suppose that for every $i$ between 2 and $k$, we have

$$
\lim _{\omega} \frac{\operatorname{dist}\left(e_{n}, \operatorname{Sat}\left(\mathfrak{q}_{i}^{(n)}\right)\right)}{d_{n}}=\infty
$$

If the same is true either for $i=1$ or for $i=k+1$ one can apply Lemma 4.21. Thus suppose that for $i=1, k+1$, we have

$$
\lim _{\omega} \frac{\operatorname{dist}\left(e_{n}, \operatorname{Sat}\left(\mathfrak{q}_{i}^{(n)}\right)\right)}{d_{n}}<\infty
$$

By Lemma 4.21, for $i=1, k+1$, for the limit set $\lim ^{\omega}\left(\operatorname{Sat}\left(\mathfrak{q}_{i}^{(n)}\right)\right)$ one of the following two possibilities occurs:
$\left(\mathbf{A}_{i}\right)$ it is equal to $\lim ^{\omega}\left(A_{n}\right)$, where $A_{n} \in \mathscr{A}, A_{n} \subseteq \operatorname{Sat}\left(\mathfrak{q}_{i}^{(n)}\right)$;
$\left(\mathbf{B}_{i}\right)$ it is equal to $Y\left(\mathfrak{q}_{i}\right)$ as in Lemma 2.23(2), where $\mathfrak{q}_{i}=\lim ^{\omega}\left(\mathfrak{q}_{i}^{(n)}\right)$.
It remains to show that the union $\lim ^{\omega}\left(\operatorname{Sat}\left(\mathfrak{q}_{1}^{(n)}\right)\right) \cup \lim ^{\omega}\left(\operatorname{Sat}\left(\mathfrak{q}_{k+1}^{(n)}\right)\right)$ is connected.
Suppose that we are in the situation $\left(\mathbf{B}_{1}\right)$. Let $u_{n} \in \mathfrak{q}_{1}^{(n)}$ be an almost nearest point from $e_{n}$. Then $\operatorname{dist}\left(u_{n}, e_{n}\right)=O\left(d_{n}\right)$. Let $v_{n} \in \bigcup_{j=2}^{k+1} \operatorname{Sat}\left(\mathfrak{q}_{j}^{(n)}\right)$ be an almost nearest point to $e_{n}$. By our assumption, $\omega$-almost surely $v_{n} \in \operatorname{Sat}\left(\mathfrak{q}_{k+1}^{(n)}\right)$ and $\operatorname{dist}\left(v_{n}, e_{n}\right)=O\left(d_{n}\right)$. Hence $\operatorname{dist}\left(u_{n}, v_{n}\right)=O\left(d_{n}\right)$. Let $R_{k}$ be the constant given by the variant of Lemma 4.24 for polygonal lines composed of $k(L, C)$-quasi-geodesics with $(\lambda, \kappa)=(L, C), \theta=\frac{1}{3}$ (that $R_{k}$ exists by the induction hypothesis). Let $a_{n}$ be an almost nearest point from $u_{n}$ in $\mathfrak{q}_{1}^{(n)} \cap \mathscr{N}_{R_{k}}\left(\bigcup_{j=2}^{k+1} \operatorname{Sat}\left(\mathfrak{q}_{j}^{(n)}\right)\right)$. Let $\mathfrak{p}^{(n)}$ be the sub-quasi-geodesic of $\mathfrak{q}_{1}^{(n)}$ with endpoints $u_{n}$ and $a_{n}$. According to part (2) of the proposition (which by the induction assumption is true for $k$ ), $\mathfrak{p}^{(n)} \subset \mathscr{N}_{t d_{n}}\left(\bigcup_{j=2}^{k+1} \operatorname{Sat}\left(\mathfrak{q}_{j}^{(n)}\right)\right)$ for some $t$ independent on $n$. If $\operatorname{dist}\left(u_{n}, a_{n}\right) \gg d_{n}$ then according to Lemma 4.24 there exists another point on $\mathfrak{p}^{(n)} \cap \mathscr{N}_{R_{k}}\left(\bigcup_{j=2}^{k+1} \operatorname{Sat}\left(\mathfrak{q}_{j}^{(n)}\right)\right)$ whose distance from $u_{n}$ is smaller than $\operatorname{dist}\left(a_{n}, u_{n}\right)$ by $O\left(d_{n}\right)$, a contradiction. Therefore $\operatorname{dist}\left(u_{n}, a_{n}\right) \leqslant O\left(d_{n}\right)$ and the limit point $\lim ^{\omega}\left(a_{n}\right)$ is a common point of $\mathfrak{q}_{1}$ and $\lim ^{\omega}\left(\bigcup_{i=2}^{k+1} \operatorname{Sat}\left(\mathfrak{q}_{i}^{(n)}\right)\right)=\lim ^{\omega}\left(\operatorname{Sat}\left(\mathfrak{q}_{k+1}^{(n)}\right)\right)$.

The same argument works if we are in the situation $\left(\mathbf{B}_{k+1}\right)$. Therefore we suppose that we are in the situations $\left(\mathbf{A}_{1}\right)$ and $\left(\mathbf{A}_{k+1}\right)$. We have that $\lim ^{\omega}\left(\operatorname{Sat}_{\left(\mathfrak{q}_{i}^{(n)}\right)}\right)$, $i=1, k+1$, is equal to $\lim ^{\omega}\left(A_{i}^{(n)}\right)$, where $A_{i}^{(n)} \in \mathscr{A}, A_{i}^{(n)} \subseteq \operatorname{Sat}\left(\mathfrak{q}_{i}^{(n)}\right)$. Suppose that $A_{1}^{(n)} \neq A_{k+1}^{(n)} \omega$-almost surely. Let $v_{i}^{(n)} \in \operatorname{Sat}\left(\mathfrak{q}_{i}^{(n)}\right)$ be an almost nearest point from $e_{n}$. By hypothesis $v_{i}^{(n)} \in A_{i}^{(n)}$.

The two assumptions

$$
\lim _{\omega} \frac{\operatorname{dist}\left(e_{n}, \operatorname{Sat}\left(\mathfrak{q}_{i}^{(n)}\right)\right)}{d_{n}}=\infty
$$

$i \in\{2, \ldots, k\}$, and

$$
\lim ^{\omega}\left(\operatorname{Sat}\left(\mathfrak{q}_{k+1}^{(n)}\right)\right)=\lim ^{\omega}\left(A_{k+1}^{(n)}\right)
$$

imply that $A_{1}^{(n)} \not \subset \bigcup_{i=2}^{k+1} \operatorname{Sat}\left(\mathfrak{q}_{i}^{(n)}\right) \omega$-almost surely.
Suppose that $\left[0, \ell_{1}^{(n)}\right]$ is the domain of $\mathfrak{q}_{1}^{(n)}$. The following two cases may occur.
Case I. If the distance from $\ell_{1}^{(n)}$ to the pre-image $\left(\mathfrak{q}_{1}^{(n)}\right)^{-1}\left(A_{1}^{(n)}\right)$ is at most $L C+1$ then we denote $\mathfrak{q}_{1}^{(n)}\left(\ell_{1}^{(n)}\right)$ by $a_{n}$. We have that $\operatorname{dist}\left(a_{n}, \mathfrak{q}_{1}^{(n)} \cap A_{1}^{(n)}\right) \leqslant L^{2} C+L+C$, which implies by Lemma 4.15 that a geodesic $\mathfrak{p}_{n}=\left[v_{1}^{(n)}, a_{n}\right]$ is contained in the $t\left(L^{2} C+L+C\right)$-tubular neighborhood of $A_{1}^{(n)}$.

Case II. If the distance from $\ell_{1}^{(n)}$ to $\left(\mathfrak{q}_{1}^{(n)}\right)^{-1}\left(A_{1}^{(n)}\right)$ is larger than $L C+1$, then we consider $t_{n} \in\left[0, \ell_{1}^{(n)}\right]$ at distance $L C+1$ of $\left(\mathfrak{q}_{1}^{(n)}\right)^{-1}\left(A_{1}^{(n)}\right)$ such that all points in $\left[t_{n}, \ell_{1}^{(n)}\right]$ are at distance at least $L C+1$ of $\left(\mathfrak{q}_{1}^{(n)}\right)^{-1}\left(A_{1}^{(n)}\right)$. We denote by $a_{n}$ the point $\mathfrak{q}_{1}^{(n)}\left(t_{n}\right)$. According to Lemma 4.15 we have that a geodesic [ $\left.v_{1}^{(n)}, a_{n}\right]$ is contained in the $t\left(L^{2} C+L+C\right)$-tubular neighborhood of $A_{1}^{(n)}$.

By our assumption, $\lim _{\omega}\left(\operatorname{dist}\left(v_{1}^{(n)}, a_{n}\right) / d_{n}\right)=\infty$. Lemma 4.19 implies that $\left[v_{1}^{(n)}, a_{n}\right]$ and the restriction of $\mathfrak{q}_{1}^{(n)}$ to $\left[t_{n}, \ell_{1}^{(n)}\right]$ form an $(L+\varepsilon, K)$-quasi-geodesic $\omega$-almost surely. We denote it by $\mathfrak{p}_{n}$.

Both in Case I and in Case II we have obtained an $(L+\varepsilon, K)$-quasi-geodesic $\mathfrak{p}_{n}$ with one of the endpoints $v_{1}^{(n)}$ and the other one contained in $\mathfrak{q}_{2}^{(n)}$. The distance from $v_{1}^{(n)}$ to $\bigcup_{i=2}^{k+1} \operatorname{Sat}\left(\mathfrak{q}_{i}^{(n)}\right)$ does not exceed $\operatorname{dist}\left(v_{1}^{(n)}, v_{k+1}^{(n)}\right)$; hence it is at most $O\left(d_{n}\right)$. It follows that $\mathfrak{p}_{n} \subset \mathcal{N} O\left(d_{n}\right)\left(\bigcup_{i=2}^{k+1} \operatorname{Sat}\left(\mathfrak{q}_{i}^{(n)}\right)\right)$. In particular $\left[v_{1}^{(n)}, a_{n}\right]$ is contained in the same tubular neighborhood. Since the length $\lambda_{n}$ of $\left[v_{1}^{(n)}, a_{n}\right]$ satisfies $\lim _{\omega}\left(\lambda_{n} / d_{n}\right)=\infty$, by applying Lemmas 4.24 and 4.25 we obtain that a sub-segment $\left[\alpha_{n}, \beta_{n}\right]$ of $\left[v_{n}^{1}, a_{n}\right]$ of length $\lambda_{n} / 2$ is contained in $\mathscr{N}_{\tau R}\left(\bigcup_{i=2}^{k+1} \operatorname{Sat}\left(\mathfrak{q}_{n}^{i}\right)\right)$, where $R$ is a universal constant. On the other hand we have $\left[\alpha_{n}, \beta_{n}\right] \subset \mathscr{N}_{t\left(L^{2} C+L+C\right)}\left(A_{1}^{(n)}\right)$. This contradicts the inductive hypothesis (3). We conclude that if we are in situation $\left(\mathbf{A}_{1}\right)$ then $\lim _{\omega}\left(\operatorname{dist}\left(e_{n}, \operatorname{Sat}\left(\mathfrak{q}_{n}^{k+1}\right)\right) / d_{n}\right)=\infty$.

Corollary 4.27. Let $\Delta$ be a quasi-geodesic triangle. Then every edge $\mathfrak{a}$ of $\Delta$ is contained in an $M$-tubular neighborhood of $\operatorname{Sat}(\mathfrak{b}) \cup S a t(\mathfrak{c})$, where $\mathfrak{b}$ and $\mathfrak{c}$ are the two other edges of $\Delta$ and $M$ is a universal constant.

Lemma 4.28. For every $R>0, k \in \mathbb{N}$ and $\delta>0$ there exists $x>0$ such that if $\bigcup_{i=1}^{k} \mathfrak{q}_{i}$ is a polygonal line composed of quasi-geodesics and $A, B \in \mathscr{A}, A \cup B \subset \bigcup_{i=1}^{k} \operatorname{Sat}\left(\mathfrak{q}_{i}\right), A \neq B$, the following holds. Let $a \in \mathscr{N}_{R}(A)$ and $b \in \mathscr{N}_{R}(B)$ be two points that can be joined by a quasi-geodesic $\mathfrak{p}$ such that $\mathfrak{p} \cap \mathscr{N}_{R}(A)$ and $\mathfrak{p} \cap \mathscr{N}_{R}(B)$ has diameter at most $\delta$. Then $\{a, b\} \subset \mathscr{N}_{x}\left(\bigcup_{i=1}^{k} \mathfrak{q}_{i}\right)$.

Proof. Suppose $\mathfrak{q}_{i}$ is defined on the interval [ $0, \ell_{i}$ ]. Let $\mathfrak{r}:\left[0, \sum_{i=1}^{k} \ell_{i}\right] \rightarrow X$ be the map defined by $\mathfrak{r}\left(\sum_{i=1}^{j-1} \ell_{i}+t\right)=\mathfrak{q}_{j}(t)$, for all $t \in\left[0, \ell_{j}\right]$ and all $j \in\{2, \ldots, k\}$. It satisfies

$$
\begin{equation*}
\operatorname{dist}(\mathfrak{r}(t), \mathfrak{r}(s)) \leqslant L|t-s|+k C . \tag{8}
\end{equation*}
$$

Let $x$ be a point in $\mathfrak{r} \cap \mathscr{N}_{M}(B)$ and $t_{x} \in\left[0, \sum_{i=1}^{k} \ell_{i}\right]$ such that $\mathfrak{r}\left(t_{x}\right)=x$. We have two cases.
(a) If the distance from $t_{x}$ to the pre-image $\mathrm{r}^{-1}\left(\mathscr{N}_{M}(A)\right)$ does not exceed $L C+1$ then $x \in$ $\mathcal{N}_{M+L^{2} C+L+k C}(A)$ by (8). By Lemma 4.19, if $\operatorname{dist}(a, x)$ is larger than $D^{\prime}$ then the union of $\mathfrak{p}$ and a geodesic $[a, x]$ form an $(L+\varepsilon, K)$-quasi-geodesic, with endpoints in $\mathcal{N}_{R+M}(B)$. It follows that this quasigeodesic and in particular $[a, x]$ are contained in $\mathscr{N}_{t(M+R)}(B)$. On the other hand $[a, x]$ is contained in
$\mathscr{N}_{t\left(M+R+L^{2} C+L+k C\right)}(A)$. If dist $(a, x)$ is larger than the diameter given by $\left(\alpha_{1}\right)$ for $\delta=t\left(M+R+L^{2} C+\right.$ $L+k C$ ) then we obtain a contradiction with $\left(\alpha_{1}\right)$.
(a) Suppose that the distance from $t_{x}$ to $r^{-1}\left(\mathcal{N}_{M}(A)\right)$ is larger than $L C+1$. Consider $s_{0}$ at distance $L C+1$ from $\mathfrak{r}^{-1}\left(\mathcal{N}_{M}(A)\right)$ such that every $s$ between $s_{0}$ and $t_{x}$ is at distance at least $L C+1$ from $\mathfrak{r}^{-1}\left(\mathscr{N}_{M}(A)\right)$. It follows that $\mathfrak{r}\left(\left[s_{0}, t_{x}\right]\right)$ or $\mathfrak{r}\left(\left[t_{x}, s_{0}\right]\right)$ is disjoint of $\mathscr{N}_{M}(A)$. Let $y=\mathfrak{r}\left(s_{0}\right)$. The restriction $\mathfrak{r}^{\prime}$ of $\mathfrak{r}$ to $\left[s_{0}, t_{x}\right]$ or $\left[t_{x}, s_{0}\right]$ can be written as $\bigcup_{j=1}^{m} \mathfrak{q}_{j}^{\prime}$, where $m \leqslant k$ and each $\mathfrak{q}_{j}^{\prime}$ coincides with one of the $\mathfrak{q}_{i}$ 's or a restriction of it. We note that $A \not \subset \operatorname{Sat}\left(\mathrm{r}^{\prime}\right)$.

If the distance from $a$ to $y$ is larger than the constant $D^{\prime}$ given by Lemma 4.19 then $\mathfrak{p}$ and a geodesic $[a, y]$ form an ( $L+\varepsilon, K$ )-quasi-geodesic. Lemma 4.26(2) implies that this quasi-geodesic, and in particular $[a, y]$, is contained in the $\tau R$-tubular neighborhood of $\operatorname{Sat}\left(\mathfrak{r}^{\prime}\right)$. On the other hand, $[a, y]$ is contained in the $t\left(R+M+L^{2} C+L+k C\right)$-tubular neighborhood of $A$. For dist $(a, y)$ larger than the diameter given by Lemma 4.26(3), for $\delta=\max \left(t\left(R+M+L^{2} C+L+k C\right), \tau R\right)$ we obtain a contradiction.

Lemma 4.29. Suppose that a metric space $X$ is asymptotically tree-graded with respect to $\mathscr{A}$. Then $X$ satisfies $\left(\alpha_{3}^{\prime}\right)$.

Proof. Let $k \geqslant 2, \sigma \geqslant 1$ and $v \geqslant 4 \sigma$. Fix a sufficiently large number $\vartheta$ (it will be clear later in the proof how large $\vartheta$ should be). Let $P$ be a $k$-gon with quasi-geodesic edges that is $(\vartheta, \sigma, v$ )-fat. Changing if necessary the polygon by a finite Hausdorff distance, we may suppose that its edges are ( $L+C, C$ )-almost geodesics.

Let $\mathfrak{q}:[0, \ell] \rightarrow X$ be an edge with endpoints $\mathfrak{q}(0)=x, \mathfrak{q}(\ell)=y$. We denote $\mathfrak{q}_{1}, \mathfrak{q}_{2}, \ldots, \mathfrak{q}_{k-1}$ the other edges in the clockwise order. By Lemma 4.26(2),

$$
\mathfrak{q} \subset \mathscr{N}_{\tau R}\left(\bigcup_{i=1}^{k-1} \operatorname{Sat}\left(\mathfrak{q}_{i}\right)\right)
$$

We take $\vartheta>\tau R$. Then for every point $z \in \mathfrak{q} \backslash \mathscr{N}_{\sigma \vartheta}(\{x, y\})$ there exists $A \subset \operatorname{Sat}\left(\mathfrak{q}_{i}\right), i \in\{1,2, \ldots, k-1\}$ such that $z \in \mathscr{N}_{\tau R}(A)$. If such a point $z$ is contained in $\mathscr{N}_{\tau R}(A) \cap \mathscr{N}_{\tau R}(B), A \neq B$, then Lemma 4.28 implies that $z \in \mathcal{N}_{x}\left(\bigcup_{i=1}^{k-1} \mathfrak{q}_{i}\right)$, where $x$ depends on $\tau R$ and $k$. If we choose $\vartheta>x$ then this gives a contradiction.

Let $t_{\mathfrak{q}}$ be the supremum of the numbers $t \in[0, \ell]$ contained in $\mathfrak{q}^{-1}\left(\mathcal{N}_{\sigma \vartheta}(x)\right)$. Let $s_{\mathfrak{q}}$ be the infimum of the numbers in $\left[t_{\mathfrak{q}}, \ell\right]$ contained in $\mathfrak{q}^{-1}\left(\mathcal{N}_{\sigma \vartheta}(y)\right)$. Let $a_{\mathfrak{q}}=\mathfrak{q}\left(t_{\mathfrak{q}}\right)$ and $b_{\mathfrak{q}}=\mathfrak{q}\left(s_{\mathfrak{q}}\right)$. We note that $\operatorname{dist}\left(a_{\mathfrak{q}}, x\right)=\sigma \vartheta$ and $\operatorname{dist}\left(b_{\mathfrak{q}}, y\right)=\sigma \vartheta$. According to the argument in the paragraph above, $\mathfrak{q}\left(\left[t_{\mathfrak{q}}, s_{\mathfrak{q}}\right]\right)$ is covered by the family of open sets $\mathscr{N}_{\tau R}(A)$, with $A \subset \operatorname{Sat}\left(\mathfrak{q}_{i}\right), i \in\{1,2, \ldots, k-1\}$, and the traces of these sets on $\mathfrak{q}\left(\left[t_{\mathfrak{q}}, s_{\mathfrak{q}}\right]\right)$ are pairwise disjoint. The connectedness of $\mathfrak{q}\left(\left[t_{\mathfrak{q}}, s_{\mathfrak{q}}\right]\right)$ implies that there exists $A$ as above such that $\mathfrak{q}\left(\left[t_{\mathrm{q}}, s_{\mathrm{q}}\right]\right) \subset \mathscr{N}_{\tau R}(A)$.

Thus, for every edge $\mathfrak{q}$ a sub-arc $\mathfrak{q}^{\prime}:\left[t_{\mathfrak{q}}, s_{\mathfrak{q}}\right] \rightarrow X$ with endpoints $a_{\mathfrak{q}}, b_{\mathfrak{q}}$ is contained in $\mathscr{N}_{\tau R}(A)$ for some $A \subset \operatorname{Sat}\left(\mathfrak{q}_{i}\right), i \in\{1,2, \ldots, k-1\}$ ( $A$ may depend on $\mathfrak{q}$ ). We note that $t_{\mathfrak{q}}$ and $\ell-s_{\mathfrak{q}}$ are less than $\sigma \vartheta L+C$; hence $\left.\mathfrak{q}\right|_{\left[0, t_{\mathrm{q}}\right]} \in \mathscr{N}_{\sigma \vartheta L^{2}+L C+C}\left(a_{\mathfrak{q}}\right)$ and $\left.\mathfrak{q}\right|_{\left[s_{q}, \ell\right]} \in \mathscr{N}_{\sigma \vartheta L^{2}+L C+C}\left(b_{\mathfrak{q}}\right)$.

Suppose that we have two consecutive edges $\mathfrak{q}_{1}, \mathfrak{q}_{2}$ with endpoints $x, y$ and $y, z$, respectively, such that $\mathfrak{q}_{1}^{\prime} \subset \mathscr{N}_{\tau R}(A)$ and $\mathfrak{q}_{2}^{\prime} \subset \mathscr{N}_{\tau R}(B), A \neq B$. We denote $\mathfrak{q}_{3}, \mathfrak{q}_{4}, \ldots, \mathfrak{q}_{k}$ the other edges in the clockwise order. We have $\mathfrak{q}_{i}^{\prime}:\left[t_{\mathfrak{q}_{i}}, s_{\mathfrak{q}_{i}}\right] \rightarrow X$ with endpoints $a_{\mathfrak{q}_{i}}, b_{\mathfrak{q}_{i}}$. Suppose $b_{\mathfrak{q}_{1}}=\mathfrak{q}_{1}^{\prime} \cap \mathscr{N}_{\sigma \vartheta}(y)$ and $a_{\mathfrak{q}_{2}}=\mathfrak{q}_{2}^{\prime} \cap \mathscr{N}_{\sigma \vartheta}(y)$.

Let $\overline{\mathfrak{q}}_{1}$ be the restriction of $\mathfrak{q}_{1}^{\prime}$ to $\left[t_{\mathfrak{q}_{1}}, t_{\mathfrak{q}_{1}}+3 L \tau R\right]$ and $\tilde{\mathfrak{q}}_{1}=\left[x, a_{\mathfrak{q}_{1}}\right] \cup \overline{\mathfrak{q}}_{1}$. We note that since $\operatorname{dist}\left(a_{\mathfrak{q}_{1}}, b_{\mathfrak{q}_{1}}\right) \geqslant \operatorname{dist}(x, y)-2 \sigma \vartheta \geqslant v \vartheta-2 \sigma \vartheta \geqslant 2 \sigma \vartheta$, we have $s_{\mathfrak{q}_{1}}-t_{\mathfrak{q}_{1}} \geqslant 2 \sigma \vartheta / L-C$, so for $\vartheta$ large enough we have $s_{\mathfrak{q}_{1}}-t_{\mathfrak{q}_{1}} \geqslant 10 L \tau R$ and the restriction $\overline{\mathfrak{q}}_{1}$ makes sense.

Likewise we construct $\tilde{\mathfrak{q}}_{2}=\overline{\mathfrak{q}}_{2} \cup\left[b_{\mathfrak{q}_{2}}, z\right]$, where $\overline{\mathfrak{q}}_{2}$ is the restriction of $\mathfrak{q}_{2}^{\prime}$ to the last sub-interval of length $3 L \tau R$.

Let $[a, b]$ be a geodesic joining the points $a=a_{\mathfrak{q}_{2}}$ and $b=b_{\mathfrak{q}_{1}}$. It has length at most $2 \sigma \vartheta$. Let $\left[a^{\prime}, b^{\prime}\right] \subset[a, b]$ be a sub-geodesic which intersects $\mathscr{N}_{\tau R}(A)$ in $a^{\prime}$ and $\mathscr{N}_{\tau R}(B)$ in $b^{\prime}$ (eventually reduced to a point). Notice that $A \subseteq \operatorname{Sat}\left(\tilde{\mathfrak{q}}_{1}\right), B \subseteq \operatorname{Sat}\left(\tilde{\mathfrak{q}}_{2}\right)$. Lemma 4.28 applied to the polygonal line $\tilde{\mathfrak{q}}_{2} \cup \bigcup_{i=3}^{k} \mathfrak{q}_{i} \cup \tilde{\mathfrak{q}}_{1}$ and to the points $a^{\prime}, b^{\prime}$ implies that $\left\{a^{\prime}, b^{\prime}\right\} \subset \mathscr{N}_{x}\left(\tilde{\mathfrak{q}}_{2} \cup \bigcup_{i=3}^{k} \mathfrak{q}_{i} \cup \tilde{\mathfrak{q}}_{1}\right)$, where $x$ depends on $\tau R$. Since $\operatorname{dist}\left(y,\left\{a^{\prime}, b^{\prime}\right\}\right)$ is at most $2 \sigma \vartheta$, it follows that $y \in \mathcal{N}_{x+2 \sigma \vartheta}\left(\tilde{\mathfrak{q}}_{2} \cup \bigcup_{i=3}^{k} \mathfrak{q}_{i} \cup \tilde{\mathfrak{q}}_{1}\right) \subset$ $\mathcal{N}_{\chi+3 \sigma \vartheta+3 L^{2} \tau R+C}\left(\bigcup_{i=3}^{k} \mathfrak{q}_{i}\right)$. On the other hand property $\left(F_{2}\right)$ implies that dist $\left(y, \bigcup_{i=3}^{k} \mathfrak{q}_{i}\right) \geqslant v \vartheta \geqslant 4 \sigma \vartheta$. For $\vartheta$ large enough this gives a contradiction.

We conclude that there exists $A \in \mathscr{A}$ such that $\bigcup_{i=1}^{k} \mathfrak{q}_{i}^{\prime} \subset \mathscr{N}_{\tau R}(A)$. Hence $P$ is inside the $(\tau R+$ $\sigma \vartheta L^{2}+L C+C$ )-tubular neighborhood of $A$.

The following corollary immediately follows from the proof of Theorem 4.1.
Corollary 4.30 (there is no need to vary the ultrafilter in Definition 3.19). Let $X$ be a metric space, and let $\mathscr{A}$ be a collection of subsets in $X$. Let $\omega$ be any ultrafilter over $\mathbb{N}$. Suppose that every asymptotic cone $\operatorname{Con}^{\omega}(X ; e, d)$ is tree-graded with respect to the collection of sets $\lim ^{\omega}\left(A_{n}\right), A_{n} \in \mathscr{A}$. Then $X$ is asymptotically tree-graded with respect to $\mathscr{A}$.

## 5. Quasi-isometric behavior

One of the main reasons we are interested in the property of being asymptotically tree-graded is the rigid behavior of this property with respect to quasi-isometry.

### 5.1. Asymptotically tree-graded spaces

Theorem 5.1 (being asymptotically tree-graded is a geometric property). Let $X$ be a metric space and let $\mathscr{A}$ be a collection of subsets of $X$. Let $\mathfrak{q}$ be a quasi-isometry $X \rightarrow X^{\prime}$. Then:
(1) If $X$ satisfies properties $\left(\alpha_{1}\right)$ and $\left(\alpha_{2}^{\prime}\right)$ with respect to $\mathscr{A}$ then $X^{\prime}$ satisfies properties $\left(\alpha_{1}\right)$ and $\left(\alpha_{2}^{\varepsilon}\right)$, for a sufficiently small $\varepsilon$, with respect to $\mathfrak{q}(\mathscr{A})=\{\mathfrak{q}(A) \mid A \in \mathscr{A}\}$.
(2) If $X$ satisfies $\left(\alpha_{3}^{\prime}\right)$ with respect to $\mathscr{A}$ then $X^{\prime}$ satisfies $\left(\alpha_{3}\right)$ with respect to $\mathfrak{q}(\mathscr{A})$.
(3) If $X$ is asymptotically tree-graded with respect to $\mathscr{A}$ then $X^{\prime}$ is asymptotically tree-graded with respect to $q(\mathscr{A})$.

Proof. (1) follows from Theorem 4.1 and Remark 4.2.
(2) Assume that $\mathfrak{q}$ is an ( $L, C$ )-quasi-isometry and that $\overline{\mathfrak{q}}: X^{\prime} \rightarrow X$ is an ( $L, C$ )-quasi-isometry so that $\overline{\mathfrak{q}} \circ \mathfrak{q}$ and $\mathfrak{q} \circ \overline{\mathfrak{q}}$ are at distance at most $C$ from the respective identity maps.

Fix an arbitrary integer $k \geqslant 2$. Let $\sigma=2 L^{2}+1$ and $v=4 \sigma$. Property ( $\alpha_{3}^{\prime}$ ) in $X$ implies that for the constants $L, C$ of the quasi-isometries, for the given $k, \sigma$ and $v$ there exists $\vartheta_{0}$ such that for every $\vartheta \geqslant \vartheta_{0}$ a $k$-gon with ( $L, C$ )-quasi-geodesic edges in $X$ which is $\left(\vartheta, \sigma, v\right.$ )-fat is contained in $\mathcal{N}_{\chi}(A)$, where $A \in \mathscr{A}$ and $\chi=\chi(L, C, k, \sigma, v, \vartheta)$.

Let $\vartheta_{1}=\max \left(\vartheta_{0}, 2 L^{2} C+C\right)$ and let $\theta=L\left(\vartheta_{1}+C\right)$. Let $P$ be a geodesic $k$-gon in $X^{\prime}$ which is $(\theta, 2, v)$ fat. Then $\overline{\mathfrak{q}}(P)$ is a $k$-gon in $X$ with $(L, C)$-quasi-geodesic edges which is ( $\vartheta_{1}, \sigma, v$ )-fat. Consequently, $\overline{\mathfrak{q}}(P) \subset \mathscr{N}_{\chi}(A)$, where $A \in \mathscr{A}$ and $\chi=\chi\left(L, C, k, \sigma, v, \vartheta_{1}\right)$. It follows that $P \subset \mathscr{N}_{C}(\mathfrak{q} \circ \overline{\mathfrak{q}}(P)) \subset$ $\mathcal{N}_{L \chi+2 C}(\mathfrak{q}(A))$.
(3) The statement follows from (1) and (2). It also follows immediately from the definition of asymptotically tree-graded spaces. Indeed, it is easy to see that $\omega$-limits of sequences of subsets commute with quasi-isometries. Since quasi-isometric spaces have bi-Lipschitz equivalent asymptotic cones (Remark 3.16) it remains to note that a metric space that is bi-Lipschitz equivalent to a space that is tree-graded with respect to $\mathscr{P}$, is itself tree-graded with respect to the images of the sets in $\mathscr{P}$ under the bi-Lipschitz map.

Definition 5.2. Let $B$ be a geodesic metric space. We say that $B$ is wide if every asymptotic cone of $B$ does not have global cut-points.

We say that $B$ is constricted if every asymptotic cone of $B$ has a global cut-point.
We say that $B$ is unconstricted if there exists an ultrafilter $\omega$ and a sequence $d=\left(d_{n}\right)$ of scaling constants satisfying $\lim _{\omega} d_{n}=\infty$ such that for every observation point $e=\left(e_{n}\right)^{\omega}$ the asymptotic cone $\operatorname{Con}^{\omega}(B ; e, d)$ has no cut-points.

Remark 5.3. (1) Note that "unconstricted" is in general more than the negation of "constricted", as the latter only means that there exists one asymptotic cone without cut-points. The two notions coincide for finitely generated groups, according to the comment following Remark 3.16.
(2) Note also that most probably "wide" is stronger than "unconstricted", but we do not have an example of an unconstricted group which is not wide (see Problem 1.17).

Definition 5.2 has the following uniform version.
Definition 5.4. Let $\mathscr{B}$ be a family of geodesic metric spaces. We say that $\mathscr{B}$ is uniformly wide if for every sequence $B_{n}$ of metric spaces in $\mathscr{B}$ with metrics dist ${ }_{n}$ and basepoints $b_{n} \in B_{n}$, for every ultrafilter $\omega$ and for every sequence of scaling constants $\left(d_{n}\right)$ with $\lim _{\omega} d_{n}=\infty$, the ultralimit $\lim ^{\omega}\left(B_{n},\left(1 / d_{n}\right) \operatorname{dist}_{n}\right)_{b}$ is without cut-points.

We say that $\mathscr{B}$ is uniformly unconstricted if for every sequence $B_{n}$ of metric spaces in $\mathscr{B}$ with metrics $\operatorname{dist}_{n}$, there exists an ultrafilter $\omega$ and a sequence of scaling constants $d=\left(d_{n}\right)$ with $\lim _{\omega} d_{n}=\infty$ such that for every sequence of basepoints $b_{n} \in B_{n}$, the ultralimit $\lim ^{\omega}\left(B_{n},\left(1 / d_{n}\right) \operatorname{dist}_{n}\right)_{b}$ is without cut-points.

## Remark 5.5.

(a) All metric spaces in a family that is uniformly wide (uniformly unconstricted) are wide (unconstricted).
(b) If $\mathscr{B}$ is a family of wide metric spaces containing only finitely many pairwise non-isometric spaces then $\mathscr{B}$ is uniformly wide.
(c) For examples of groups that are wide or unconstricted and of families of groups that are uniformly wide or unconstricted, see Section 6.

Proposition 5.6. Let metric space $X$ be asymptotically tree-graded with respect to a collection of subsets $\mathscr{A}$. Let $\mathscr{B}$ be a family of metric spaces which is uniformly unconstricted. Suppose that for some constant $c$, every point in every space $B \in \mathscr{B}$ is at distance at most c from an infinite geodesic in $B$. Then for
every $(L, C)$ there exists $M=M(L, C, \mathscr{B})$ such that for every $B \in \mathscr{B}$ and every $(L, C)$-quasi-isometric embedding $\mathfrak{q}: B \rightarrow X$ there exists $A \in \mathscr{A}$ such that $\mathfrak{q}(B) \subset \mathscr{N}_{M}(A)$.

Proof. We argue by contradiction and assume that there is a sequence of metric spaces $B_{n} \in \mathscr{B}$ and a sequence of ( $L, C$ )-quasi-isometric embeddings $\mathfrak{q}_{n}: B_{n} \rightarrow X$ such that $\mathfrak{q}_{n}\left(B_{n}\right) \not \subset \mathscr{N}_{n}(A)$ for all $A \in \mathscr{A}$. By definition there exists an ultrafilter $\omega$ and a sequence $d=\left(d_{n}\right)$ with $\lim _{\omega} d_{n}=\infty$ such that for every sequence of basepoints $b_{n} \in B_{n}$, the ultralimit $\lim ^{\omega}\left(B_{n},\left(1 / d_{n}\right) \operatorname{dist}_{n}\right)_{b}$ is without cut-points. Fix a point $b_{n} \in B_{n}$. Let $e=\left(\mathfrak{q}_{n}\left(b_{n}\right)\right)$. In $\operatorname{Con}^{\omega}(X ; e, d)$, the limit set $\lim ^{\omega}\left(\mathfrak{q}_{n}\left(B_{n}\right)\right)$ is a bi-Lipschitz image of $\lim ^{\omega}\left(B_{n},\left(1 / d_{n}\right) \operatorname{dist}_{n}\right)_{b}$; therefore it is without cut-points. Lemma 2.15 implies that

$$
\begin{equation*}
\lim ^{\omega}\left(\mathfrak{q}_{n}\left(B_{n}\right)\right) \subset \lim ^{\omega}\left(A_{n}\right), \quad \text { where } A_{n} \in \mathscr{A} \tag{9}
\end{equation*}
$$

Consider a sequence $u_{n} \in B_{n}$ such that $\lim _{\omega}\left(\operatorname{dist}_{n}\left(b_{n}, u_{n}\right) / d_{n}\right)<\infty$. Each $u_{n}$ is contained in $\mathscr{N}_{c}\left(\mathfrak{g}_{n}\right)$, where $\mathfrak{g}_{n}$ is a bi-infinite geodesic in $B_{n}$. Suppose that $\mathfrak{g}_{n}$ is parameterized with respect to the arc-length in $\left(B_{n},\left(1 / d_{n}\right) \operatorname{dist}_{n}\right)$ and so that $\operatorname{dist}_{n}\left(u_{n}, \mathfrak{g}_{n}(0)\right)<c$. The inclusion in (9) implies that for every $t \in \mathbb{R}$, $\lim _{\omega}\left(\operatorname{dist}_{n}\left(\mathfrak{g}_{n}\left(\mathfrak{g}_{n}(t)\right), A_{n}\right) / d_{n}\right)=0$. Therefore for every $s<t$ we have $\omega$-a.s. that the image by $\mathfrak{q}_{n}$ of the segment $g_{n}([s, t])$ contains a point in $\mathscr{N}_{M_{0}}\left(A_{n}\right)$, where $M_{0}$ is the constant given by $\left(\alpha_{2}^{\prime}\right)$, for $L$ and $C$. By taking first $s<t<0$ then $0<s<t$, we may deduce that there exist $\alpha_{n}<0<\beta_{n}$ such that $\mathfrak{q}_{n}\left(\mathfrak{g}_{n}\left(\alpha_{n}\right)\right), \mathfrak{q}_{n}\left(\mathfrak{g}_{n}\left(\beta_{n}\right)\right) \in \mathscr{N}_{M_{0}}\left(A_{n}\right)$. We conclude that $\mathfrak{q}_{n}\left(\mathfrak{g}_{n}(0)\right) \in \mathcal{N}_{\tau M_{0}}\left(A_{n}\right)$, by Lemma 4.15. Hence $\mathfrak{q}_{n}\left(u_{n}\right) \in \mathcal{N}_{M}\left(A_{n}\right) \omega$-almost surely, where $M=\tau M_{0}+L c+C$.

Let $x_{n} \in B_{n}$ be such that $\mathfrak{q}_{n}\left(x_{n}\right) \in \mathfrak{q}_{n}\left(B_{n}\right) \backslash \mathscr{N}_{n}\left(A_{n}\right)$ and let $\left[b_{n}, x_{n}\right]$ be a geodesic in $B_{n}$. The previous argument implies that $\lim _{\omega}\left(\operatorname{dist}_{n}\left(b_{n}, x_{n}\right) / d_{n}\right)=\infty$ and that for every $t$ the point $b_{n}(t)$ on $\left[b_{n}, x_{n}\right]$ at distance $t d_{n}$ of $b_{n}$ has the image by $\mathfrak{q}_{n}$ contained in $\mathscr{N}_{M}\left(A_{n}\right) \omega$-almost surely. Let $y_{n}$ be the farthest point from $b_{n}$ in the closure of $\left[b_{n}, x_{n}\right] \cap \mathfrak{q}_{n}^{-1}\left(\mathcal{N}_{M}\left(A_{n}\right)\right)$. We have that $\lim _{\omega}\left(\operatorname{dist}_{n}\left(b_{n}, y_{n}\right) / n\right)=\infty$. Also, $y_{n} \in$ $\left[b_{n}, x_{n}\right] \cap \overline{\mathfrak{q}_{n}^{-1}\left(\mathscr{N}_{M}\left(A_{n}\right)\right)}$ implies that for every $\varepsilon>0$ the distance from $\mathfrak{q}_{n}\left(y_{n}\right)$ to $A_{n}$ is at most $M+L \varepsilon+C$. Hence $\mathfrak{q}_{n}\left(y_{n}\right) \in \mathscr{N}_{M+C+1}\left(A_{n}\right)$. On the other hand, $b_{n} \in \mathscr{N}_{M}\left(A_{n}\right) \omega$-almost surely. According to Lemma 4.15, $\mathfrak{q}_{n}\left(\left[b_{n}, y_{n}\right]\right) \subset \mathscr{N}_{\tau(M+C+1)}\left(A_{n}\right) . \operatorname{In} \operatorname{Con}^{\omega}\left(X ;\left(\mathfrak{q}_{n}\left(y_{n}\right)\right), d\right), \mathfrak{q}=\lim ^{\omega}\left(\mathfrak{q}_{n}\left(\left[b_{n}, y_{n}\right]\right)\right)$ is a bi-Lipschitz ray contained in $A=\lim ^{\omega}\left(A_{n}\right)$ and in $\lim ^{\omega}\left(\mathfrak{q}_{n}\left(B_{n}\right)\right)$. Since $\lim ^{\omega}\left(\mathfrak{q}_{n}\left(B_{n}\right)\right)$ is the image of a bi-Lipschitz embedding of the ultralimit $\lim ^{\omega}\left(B_{n},\left(1 / d_{n}\right) \text { dist }_{n}\right)_{y}$, it is without cut-points; therefore it is contained in a piece $A^{\prime}=\lim ^{\omega}\left(A_{n}^{\prime}\right)$. Property $\left(T_{1}\right)$ implies that $A=A^{\prime}$. In particular $\lim ^{\omega}\left(\mathfrak{q}_{n}\left(\left[y_{n}, x_{n}\right]\right)\right) \subset A$. The same argument as before yields that every sequence $v_{n} \in B_{n}$ such that $\lim _{\omega}\left(\operatorname{dist}_{n}\left(y_{n}, v_{n}\right) / d_{n}\right)<\infty$ satisfies $\mathfrak{q}_{n}\left(v_{n}\right) \in \mathscr{N}_{M}\left(A_{n}\right) \omega$-almost surely. Hence, $\operatorname{dist}\left(\lim ^{\omega}\left(\mathfrak{q}_{n}\left(y_{n}\right)\right), \lim ^{\omega}\left(\mathfrak{q}_{n}\left(x_{n}\right)\right)\right)=\infty$ and there exists $v_{n} \in\left[y_{n}, x_{n}\right]$ such that $\operatorname{dist}\left(\lim ^{\omega}\left(\mathfrak{q}_{n}\left(y_{n}\right)\right), \lim ^{\omega}\left(\mathfrak{q}_{n}\left(v_{n}\right)\right)\right)>0$ and $\mathfrak{q}_{n}\left(v_{n}\right) \in \mathscr{N}_{M}\left(A_{n}\right)$, which contradicts the choice of $y_{n}$.

Remark 5.7. The condition that every point is contained in the $c$-tubular neighborhood of a bi-infinite geodesic is satisfied for instance if $B$ is a geodesic complete locally compact homogeneous metric space of infinite diameter. In particular it is true for Cayley graphs of infinite finitely generated groups.

Corollary 5.8. Let $X$ be asymptotically tree-graded with respect to a collection of subsets $\mathscr{A}$. Let $B$ be an unconstricted metric space. Then every ( $L, C$ )-quasi-isometric embedding $\mathfrak{q}: B \rightarrow X$ maps $B$ into an $M$-neighborhood of a piece $A \in \mathscr{A}$, where $M$ depends only on $L, C$ and $B$.

Notation. We shall denote the Hausdorff distance between two sets $A, B$ in a metric space by hdist $(A, B)$.

### 5.2. Asymptotically tree-graded groups

Definition 5.9. We say that a finitely generated group $G$ is asymptotically tree-graded with respect to the family of subgroups $\left\{H_{1}, H_{2}, \ldots, H_{k}\right\}$ if the Cayley graph Cayley $(G)$ with respect to some (and hence every) finite set of generators is asymptotically tree-graded with respect to the collection of left cosets $\left\{g H_{i} \mid g \in G, i=1,2, \ldots, k\right\}$.

Remark 5.10. If $\left\{H_{1}, H_{2}, \ldots, H_{k}\right\} \neq\{G\}$ and if every $H_{i}$ is infinite then every $H_{i}$ has infinite index in $G$.

Proof. Indeed, a finite index subgroup is at bounded distance of the whole group, which would contradict $\left(\alpha_{1}\right)$.

Proposition 5.11. Let $G=\langle S\rangle$ be a group that is asymptotically tree-graded with respect to subgroups $H_{1}, \ldots, H_{n}$. Then each of the subgroups $H_{i}$ is finitely generated.

Proof. Take $h \in H_{i}$ and consider a geodesic $\mathfrak{g}$ in $\operatorname{Cayley}(G, S)$ connecting 1 and $h$. By Lemma 4.15 there exists a constant $M>0$ such that $\mathfrak{g}$ is in the $M$-tubular neighborhood of $H_{i}$. Let $v_{1}, \ldots, v_{k}$ be the consecutive vertices of $\mathfrak{g}$. For each $j=1, \ldots, k$ consider a vertex $w_{j}$ in $H_{i}$ at distance $\leqslant M$ from $v_{j}$. Then the distance between $w_{j}$ and $w_{j+1}$ is at most $2 M+1, j=1, \ldots, k-1$. Hence each element $w_{j}^{-1} w_{j+1}$ belongs to $H_{i}$ and is of length at most $2 M+1$. Since $h$ is a product of these elements, we can conclude that $H_{j}$ is generated by all its elements of length at most $2 M+1$.

Remark 5.12. Corollary 5.8 gives certain restrictions on the groups that can be quasi-isometrically embedded into asymptotically tree-graded groups. For instance, if $G$ is a group asymptotically treegraded with respect to a finite family of free Abelian groups of rank at most $r$, no free Abelian group of rank at least $r+1$ can be quasi-isometrically embedded into $G$.

Theorem 5.13. Let $X$ be a space that is asymptotically tree-graded with respect to a collection of subspaces $\mathscr{A}$. Assume that
(1) $\mathscr{A}$ is uniformly unconstricted;
(2) for some constant c every point in every $A \in \mathscr{A}$ is at distance at most c from a bi-infinite geodesic in $A$;
(3) for a fixed $x_{0} \in X$ and every $R>0$ the ball $B\left(x_{0}, R\right)$ intersects finitely many $A \in \mathscr{A}$.

Let $G$ be a finitely generated group which is quasi-isometric to $X$. Then there exist subsets $A_{1}, \ldots, A_{m} \in$ $\mathscr{A}$ and subgroups $H_{1}, \ldots, H_{m}$ of $G$ such that
(I) every $A \in \mathscr{A}$ is quasi-isometric to $A_{i}$ for some $i \in\{1,2, \ldots, m\}$;
(II) $H_{i}$ is quasi-isometric to $A_{i}$ for every $i \in\{1,2, \ldots, m\}$;
(III) $G$ is asymptotically tree-graded with respect to the family of subgroups $\left\{H_{1}, H_{2}, \ldots, H_{m}\right\}$.

Proof. First we show (in the next lemma) that there is a natural quasi-transitive quasi-action of $G$ on $X$ by quasi-isometries.

Notation. Let $g \in G$. We denote by $\mathbf{g}$ the multiplication on the left by $g$ in $G$.
Lemma 5.14. Let $\mathfrak{q}: G \rightarrow X$ and $\overline{\mathfrak{q}}: X \rightarrow G$ be $\left(L_{0}, C_{0}\right)$-quasi-isometries such that $\mathfrak{q} \circ \overline{\mathfrak{q}}$ is at distance $C_{0}$ from the identity map on $X$ and the same is true for $\overline{\mathfrak{q}} \circ \mathfrak{q}$ with respect to the identity map on $G$.
(1) For every $g \in G$ the map $\mathfrak{q}_{g}=\mathfrak{q} \circ \mathbf{g} \circ \overline{\mathfrak{q}}: X \rightarrow X$ is an $(L, C)$-quasi-isometry, where $L=L_{0}^{2}$ and $C=L_{0} C_{0}+C_{0}$.
(2) For $g, h \in G$ the map $\mathfrak{q}_{g} \circ \mathfrak{q}_{h}$ is at distance at most $C$ from the map $\mathfrak{q}_{g h}$.
(3) For every $g \in G$ the map $\mathfrak{q}_{g} \circ \mathfrak{q}_{g^{-1}}$ is at distance at most $C+C_{0}$ from the identity.
(4) For every $x, y \in X$ there exists $g \in G$ such that $\operatorname{dist}\left(x, q_{g}(y)\right) \leqslant C_{0}$.

Proof. Statement (1) follows from the fact that $\mathbf{g}$ acts as an isometry on $G$. Statement (2) is a consequence of the fact that $\overline{\mathfrak{q}} \circ \mathfrak{q}$ is at distance at most $C_{0}$ from the identity map on $G$. For (3) we use (2) and the fact that $\mathfrak{q} \circ \overline{\mathfrak{q}}$ is at distance at most $C_{0}$ from the identity map on $X$.
(4) Let $g=\overline{\mathfrak{q}}(x)$ and $h=\overline{\mathfrak{q}}(y)$. Then $\mathfrak{q}_{h g^{-1}}(x)=\mathfrak{q}(h)=\mathfrak{q}(\overline{\mathfrak{q}}(y))$, which is at distance at most $C_{0}$ from $y$.

Notation. Let $H$ be a subgroup in $G$ and let $x \in X$. We denote by $H x$ the set $\left\{\mathfrak{q}_{h}(x) \mid h \in H\right\}$.
Proposition 5.6, Remark 5.7 and hypothesis (1) imply that there exists $M=M(L, C)$ such that for every $A \in \mathscr{A}$ and every $(L, C)$-quasi-isometric embedding $\mathfrak{q}: A \rightarrow X$ there exists $A^{\prime} \in \mathscr{A}$ such that $\mathfrak{q}(A) \subset \mathscr{N}_{M}\left(A^{\prime}\right)$.

Lemma 5.15. (1) If $A, A^{\prime} \in \mathscr{A}$ satisfy $A \subset \mathscr{N}_{r}\left(A^{\prime}\right)$ for some $r>0$ then $A=A^{\prime}$.
(2) Let $\mathfrak{q}: X \rightarrow X$ and $\overline{\mathfrak{q}}$ be $(L, C)$-quasi-isometries such that $\mathfrak{q} \circ \overline{\mathfrak{q}}$ and $\overline{\mathfrak{q}} \circ \mathfrak{q}$ are at distance at most $K$ from the identity map on $X$. If $A, A^{\prime} \in \mathscr{A}$ are such that $\mathfrak{q}(A) \subset \mathscr{N}_{r}\left(A^{\prime}\right)$ or $A^{\prime} \subset \mathscr{N}_{r}(\mathfrak{q}(A))$ for some $r>0$ then $\mathfrak{q}(A) \subset \mathscr{N}_{M}\left(A^{\prime}\right), \overline{\mathfrak{q}}\left(A^{\prime}\right) \subset \mathscr{N}_{M}(A)$ and $\operatorname{hdist}\left(\mathfrak{q}(A), A^{\prime}\right), \operatorname{hdist}\left(\overline{\mathfrak{q}}\left(A^{\prime}\right), A\right) \leqslant L M+C+K$.

Proof. (1) follows from property $\left(\alpha_{1}\right)$ and hypothesis (2) of Theorem 5.13.
(2) Suppose $A^{\prime} \subset \mathscr{N}_{r}(\mathfrak{q}(A))$. By Proposition 5.6, there exists $\bar{A}$ such that $\mathfrak{q}(A) \subset \mathscr{N}_{M}(\bar{A})$. Then $A^{\prime} \subset \mathcal{N}_{r+M}(\bar{A})$, which implies that $A^{\prime}=\bar{A}$. We may therefore reduce the problem to the case when $\mathfrak{q}(A) \subset \mathscr{N}_{r}\left(A^{\prime}\right)$.

The set $\overline{\mathfrak{q}}\left(A^{\prime}\right)$ is contained in $\mathscr{N}_{M}\left(A^{\prime \prime}\right)$ for some $A^{\prime \prime} \in \mathscr{A}$. Also $\overline{\mathfrak{q}} \circ \mathfrak{q}(A) \subset \mathscr{N}_{L r+C}\left(\overline{\mathfrak{q}}\left(A^{\prime}\right)\right)$, which implies that $A \subset \mathscr{N}_{L r+C+M+K}\left(A^{\prime \prime}\right)$. This and (1) imply that $A=A^{\prime \prime}$. It follows that $\overline{\mathfrak{q}}\left(A^{\prime}\right) \subset \mathscr{N}_{M}(A)$, which implies that $A^{\prime} \subset \mathscr{N}_{L M+C+K}(\mathfrak{q}(A))$.

Proposition 5.6 implies that there exists $\tilde{A} \in A$ such that $\mathfrak{q}(A) \subset \mathscr{N}_{M}(\tilde{A})$. Hence $A^{\prime} \subset \mathscr{N}_{(L+1) M+C+K}(\tilde{A})$, so $A^{\prime}=\tilde{A}$. We conclude that $\mathfrak{q}(A) \subset \mathscr{N}_{M}\left(A^{\prime}\right)$ and

$$
\operatorname{hdist}\left(\mathfrak{q}(A), A^{\prime}\right), \operatorname{hdist}\left(\overline{\mathfrak{q}}\left(A^{\prime}\right), A\right) \leqslant L M+C+K .
$$

Notation. We denote the constant $L M+2 C+C_{0}$ by $D$.
Definition 5.16. For every $r>0$ and every $A \in \mathscr{A}$ we define the $r$-stabilizer of $A$ as

$$
\operatorname{St}_{r}(A)=\left\{g \in G \mid \operatorname{hdist}\left(\mathfrak{q}_{g}(A), A\right) \leqslant r\right\} .
$$

Corollary 5.17. (a) For every $g \in G$ and $A, A^{\prime} \in \mathscr{A}$ such that $\mathfrak{q}_{g}(A) \subset \mathscr{N}_{r}\left(A^{\prime}\right)$ or $A^{\prime} \subset \mathscr{N}_{r}\left(\mathfrak{q}_{g}(A)\right)$, where $r>0$, we have $\operatorname{hdist}\left(\mathfrak{q}_{g}(A), A^{\prime}\right) \leqslant D$.
(b) For every $A \in \mathscr{A}$ andfor every $r>D, \mathrm{St}_{r}(A)=\operatorname{St}_{D}(A)$. Consequently $\mathrm{St}_{D}(A)$ is a subgroup of $G$.
(c) Let $A, B \in \mathscr{A}$ and $g \in G$ be such that $\operatorname{hdist}\left(\mathfrak{q}_{g}(A), B\right)$ is finite. Then

$$
\operatorname{St}_{D}(A)=g^{-1} \operatorname{St}_{D}(B) g
$$

Proof. Statement (a) is a reformulation in this particular case of part 2 of Lemma 5.15, and (b) is a consequence of (a).
(c) For every $r>0$ there exists $R$ large enough so that we have $\mathrm{St}_{r}(B) \subset g \operatorname{St}_{R}(A) g^{-1}$.

Applying the previous result again for $g^{-1}, B, A$, together with (b), we obtain the desired equality.
Let $\mathscr{F}=\left\{A_{1}, \ldots, A_{k}\right\}$ be the collection of all the sets in $\mathscr{A}$ that intersect $B\left(x_{0}, M+C_{0}\right)$. We show that this set satisfies (I). Let $A$ be an arbitrary set in $\mathscr{A}$ and let $a \in A$. There exists $g \in G$ such that $\mathfrak{q}_{g}(a) \in B\left(x_{0}, C_{0}\right)$, by Lemma $5.14(4)$. On the other hand, there exists $A^{\prime} \in \mathscr{A}$ such that $\mathfrak{q}_{g}(A) \subset$ $\mathcal{N}_{M}\left(A^{\prime}\right)$. It follows that $A^{\prime}$ intersects $B\left(x_{0}, C_{0}+M\right)$; hence it is in $\mathscr{F}$. Corollary 5.17(a) implies that $\operatorname{hdist}\left(\mathfrak{q}_{g}(A), A^{\prime}\right) \leqslant D$; consequently $A$ is quasi-isometric to $A^{\prime}$.

For every $i \in\{1,2, \ldots, k\}$ define

$$
I\left(A_{i}\right)=\left\{j \in\{1,2, \ldots, k\} \mid \text { there exists } g \in G \text { such that } \operatorname{hdist}\left(\mathfrak{q}_{g}\left(A_{i}\right), A_{j}\right) \leqslant D\right\}
$$

For every $j \in I\left(A_{i}\right)$ we fix $g_{j} \in G$ such that $\operatorname{hdist}\left(\mathfrak{q}_{g_{j}} A_{i}, A_{j}\right) \leqslant D$. Let $\Gamma\left(A_{i}\right)=\left\{g_{j}\right\}_{j \in I\left(A_{i}\right)}$ and let $K\left(A_{i}\right)=\max _{j \in I\left(A_{i}\right)} \operatorname{dist}\left(g_{j \overline{\mathfrak{q}}}\left(x_{0}\right), \overline{\mathfrak{q}}\left(x_{0}\right)\right)$.

We define the constant $K=L_{0} \max _{i \in\{1,2, \ldots, k\}} K\left(A_{i}\right)+\left(2 L_{0}+1\right) \delta_{0}$, where $\delta_{0}=L_{0} C_{0}+2 C_{0}$.
The following argument uses an idea from [34, Section 5.1].
Lemma 5.18. For every $A \in \mathscr{A}$ the $D$-stabilizer of $A$ acts $K$-transitively on $A$, that is $A$ is contained in the $K$-tubular neighborhood of every orbit $\mathrm{St}_{D}(A) a$, where $a \in A$.

Proof. Let $a$ and $b$ be two arbitrary points in A. Lemma 5.14(4) implies that there exist $g, \gamma \in G$ such that $\mathfrak{q}_{g}(a), \mathfrak{q}_{\gamma}(b) \in B\left(x_{0}, C_{0}\right)$. This implies that

$$
\begin{equation*}
\operatorname{dist}\left(\mathbf{g} \circ \overline{\mathfrak{q}}(a), \overline{\mathfrak{q}}\left(x_{0}\right)\right) \leqslant \delta_{0}, \quad \operatorname{dist}\left(\gamma \circ \overline{\mathfrak{q}}(b), \overline{\mathfrak{q}}\left(x_{0}\right)\right) \leqslant \delta_{0} . \tag{10}
\end{equation*}
$$

There exist $i, j \in\{1,2, \ldots, k\}$ such that $\operatorname{hdist}\left(\mathfrak{q}_{g}(A), A_{i}\right)$, $\operatorname{hdist}\left(\mathfrak{q}_{\gamma}(A), A_{j}\right) \leqslant D$. Then $\mathfrak{q}_{\gamma g^{-1}}\left(A_{i}\right)$ is at finite Hausdorff distance from $A_{j}$, which implies that hdist $\left(\mathfrak{q}_{\gamma g-1}\left(A_{i}\right), A_{j}\right) \leqslant D$ and that $j \in I\left(A_{i}\right)$. Let $g_{j}$ be such that hdist $\left(\mathfrak{q}_{g_{j}}\left(A_{i}\right), A_{j}\right) \leqslant D$. It follows that $g \gamma^{-1} g_{j} \in \operatorname{St}_{D}\left(A_{i}\right)$. The relation $\operatorname{hdist}\left(\mathfrak{q}_{g}(A), A_{i}\right) \leqslant D$ and Corollary 5.17 (c) imply that $\gamma^{-1} g_{j} g \in \operatorname{St}_{D}(A)$. We have that

$$
\operatorname{dist}\left(\mathfrak{q}_{\gamma^{-1}} g_{j} g(a), b\right) \leqslant L_{0} \operatorname{dist}\left(\gamma^{-1} g_{j} g \overline{\mathfrak{q}}(a), \overline{\mathfrak{q}}(b)\right)+C_{0}+L_{0} C_{0} \leqslant L_{0} \operatorname{dist}\left(g_{j} g \overline{\mathfrak{q}}(a), \gamma \overline{\mathfrak{q}}(b)\right)+\delta_{0} .
$$

This and inequalities (10) imply that

$$
\operatorname{dist}\left(\mathfrak{q}_{\gamma^{-1} g_{j} g}(a), b\right) \leqslant L_{0} \operatorname{dist}\left(g_{j} \overline{\mathfrak{q}}\left(x_{0}\right), \overline{\mathfrak{q}}\left(x_{0}\right)\right)+\left(2 L_{0}+1\right) \delta_{0} \leqslant K
$$

Corollary 5.19. For every $A \in \mathscr{A}$ the normalizer of $\operatorname{St}_{D}(A)$ in $G$ is $\operatorname{St}_{D}(A)$.

Proof. Let $g \in G$ be such that $\operatorname{St}_{D}(A)=g^{-1} \operatorname{St}_{D}(A) g$. Let $B \in \mathscr{A}$ be such that hdist $\left(\mathfrak{q}_{g}(A), B\right) \leqslant D$. Corollary 5.17(c) implies that $\operatorname{St}_{D}(A)=\operatorname{St}_{D}(B)=S$. Let $a \in A$ and $b \in B$. We have hdist $(S a, S b) \leqslant$ $L \operatorname{dist}(a, b)+C$ and also $\operatorname{hdist}(A, S a) \leqslant K$ and $\operatorname{hdist}(B, S b) \leqslant K$; therefore $\operatorname{hdist}(A, B) \leqslant 2 K+$ $L \operatorname{dist}(a, b)+C$. Lemma 5.15(1) implies that $B=A$ and $g \in \operatorname{St}_{D}(A)$.

Lemma 5.20. For every $i \in\{1,2, \ldots, m\}$ we have
$\operatorname{hdist}\left(\overline{\mathfrak{q}}\left(A_{i}\right), \operatorname{St}_{D}\left(A_{i}\right)\right) \leqslant \kappa$,
where $\kappa$ is a constant depending on $L_{0}, C_{0}, M$ and $\operatorname{dist}\left(\mathfrak{q}(1), x_{0}\right)$.
Proof. Let $x_{i} \in A_{i} \cap B\left(x_{0}, M+C_{0}\right)$. For every $g \in \operatorname{St}_{D}\left(A_{i}\right)$ we have $\operatorname{dist}\left(\mathfrak{q}_{g}\left(x_{i}\right), A_{i}\right) \leqslant D$; hence $\operatorname{dist}\left(\mathbf{g} \circ \overline{\mathfrak{q}}\left(x_{i}\right), \overline{\mathfrak{q}}\left(A_{i}\right)\right) \leqslant L_{0} D+2 C_{0}$. It follows that $\operatorname{dist}\left(g, \overline{\mathfrak{q}}\left(A_{i}\right)\right) \leqslant L_{0} D+2 C_{0}+\operatorname{dist}\left(1, \bar{q}\left(x_{i}\right)\right)$. Or $\operatorname{dist}\left(1, \overline{\mathfrak{q}}\left(x_{i}\right)\right) \leqslant L_{0} \operatorname{dist}\left(\mathfrak{q}(1), x_{i}\right)+\left(L_{0}+1\right) C_{0} \leqslant L_{0} M+\left(2 L_{0}+1\right) C_{0}+L_{0} \operatorname{dist}\left(\mathfrak{q}(1), x_{0}\right)$.

Let $\overline{\mathfrak{q}}(b) \in \overline{\mathfrak{q}}\left(A_{i}\right)$. According to Lemma 5.18, there exists $g \in \operatorname{St}_{M}\left(A_{i}\right)$ such that

$$
\operatorname{dist}\left(b, \mathfrak{q}_{g}\left(x_{i}\right)\right) \leqslant K .
$$

Hence $\operatorname{dist}\left(\overline{\mathfrak{q}}(b), \mathbf{g} \circ \overline{\mathfrak{q}}\left(x_{i}\right)\right) \leqslant L_{0} K+2 C_{0}$ and $\operatorname{dist}(\overline{\mathfrak{q}}(b), g) \leqslant L_{0} K+2 C_{0}+\operatorname{dist}\left(1, \overline{\mathfrak{q}}\left(x_{i}\right)\right)$.
Corollary 5.21. Let $A \in \mathscr{A}$. There exists $g \in G$ and $i \in\{1,2, \ldots, m\}$ such that
$\operatorname{hdist}\left(\overline{\mathfrak{q}}(A), g \operatorname{St}_{D}\left(A_{i}\right)\right) \leqslant \kappa+L_{0} D+2 C_{0}$.
We continue the proof of Theorem 5.13. Consider the minimal subset $\left\{B_{1}, \ldots, B_{m}\right\}$ of $\left\{A_{1}, \ldots, A_{k}\right\}$ such that for each $A_{i}$ there exists $B_{j_{i}}$ and $\gamma_{i}$ such that $\operatorname{hdist}\left(A_{i}, \mathfrak{q}_{\gamma_{i}}\left(B_{j_{i}}\right)\right) \leqslant D$. Let $\mathscr{B}=\left\{B_{1}, \ldots, B_{m}\right\}$. We denote $S_{i}=\operatorname{St}_{D}\left(B_{i}\right), i \in\{1,2, \ldots, m\}$. Let us show that $G$ is asymptotically tree-graded with respect to $S_{1}, \ldots, S_{m}$.

Indeed, by Theorem 5.1, Cayley $(G)$ is asymptotically tree-graded with respect to $\{\bar{q}(A), A \in \mathscr{A}\}$. Corollary 5.21 implies that each $\overline{\mathfrak{q}}(A)$ is at uniformly bounded Hausdorff distance from $g \operatorname{St}_{D}\left(A_{i}\right)$ for some $i \in\{1,2, \ldots, k\}$ and $g \in G$. Corollary 5.17(c) implies that $\operatorname{St}_{D}\left(A_{i}\right)=\gamma_{i} S_{j_{i}} \gamma_{i}^{-1}$, with the notations introduced previously. It follows that $\operatorname{hdist}\left(g \operatorname{St}_{D}\left(A_{i}\right), g \gamma_{i} S_{j_{i}}\right) \leqslant \max _{i \in\{1, \ldots, k\}} \operatorname{dist}\left(1, \gamma_{i}^{-1}\right)$. We conclude that $\overline{\mathfrak{q}}(A)$ is at uniformly bounded Hausdorff distance from $g \gamma_{i} S_{j_{i}}$. Thus $G$ is asymptotically tree-graded with respect to $S_{1}, \ldots, S_{m}$.

Corollary 5.22. Let $G$ be a group that is asymptotically tree-graded with respect to the family of subgroups $\left\{H_{1}, H_{2}, \ldots, H_{k}\right\}$, where $H_{i}$ is an unconstricted infinite group for every $i \in\{1,2, \ldots, k\}$. Let $G^{\prime}$ be a finitely generated group which is quasi-isometric to $G$. Then $G^{\prime}$ is asymptotically tree-graded with respect to a finite collection of subgroups $\left\{S_{1}, \ldots, S_{m}\right\}$ such that each $S_{i}$ is quasi-isometric to one of the $H_{j}$.

Remark 5.23. If the groups $H_{i}$ in Corollary 5.22 are contained in classes of groups stable with respect to quasi-isometries (for instance the class of virtually nilpotent groups of a fixed degree, some classes of virtually solvable groups) then $S_{i}$ are in the same classes.

Corollary 5.24. If a group is asymptotically tree-graded with respect to a family of subsets $\mathscr{A}$ satisfying conditions (1), (2), (3) in Theorem 5.13, then it is asymptotically tree-graded with respect to subgroups $H_{1}, \ldots, H_{m}$ such that every $H_{i}$ is quasi-isometric to some $A \in \mathscr{A}$.

Remark 5.25. (a) If in Theorem 5.13 we have that the cardinality of $\mathscr{A}$ is at least two then for every $i \in\{1,2, \ldots, m\}, H_{i}$ has infinite index in $G$.
(b) If in Corollary 5.22 we have $\left\{H_{1}, \ldots, H_{k}\right\} \neq\{G\}$ then for every $j \in\{1,2, \ldots, m\}, S_{j}$ has infinite index in $G^{\prime}$.

Proof. (a) Suppose that $\left\{H_{1}, \ldots, H_{k}\right\}=\{G\}$. According to the proof of Theorem 5.13, it follows that $G=\operatorname{St}_{D}(B)$ for some $B \in \mathscr{A}$. Lemma 5.20 then implies that $\operatorname{hdist}(\overline{\mathfrak{q}}(B), G) \leqslant \kappa$, whence $\operatorname{hdist}(B, X) \leqslant$ $3 C_{0}+L_{0} \kappa$. This contradicts the property $\left(\alpha_{1}\right)$ satisfied by $\mathscr{A}$.

Therefore $\left\{H_{1}, \ldots, H_{k}\right\} \neq\{G\}$. Now the statement follows from Remark 5.10.
Statement (b) follows from (a).

## 6. Cut-points in asymptotic cones of groups

Theorem 5.13 shows that we need to study unconstricted groups. In this section we provide two classes of examples of such groups. We begin with some general remarks. Let $G$ be a finitely generated group such that an asymptotic cone $\operatorname{Con}^{\omega}(G ; e, d)$ has a cut-point, where $e=(1), d=\left(d_{n}\right)$. Lemma 2.31 implies that $\operatorname{Con}^{\omega}(G ; e, d)$ is a tree-graded space with respect to a set of pieces $\mathscr{P}$ such that each piece is either a point or a geodesic subset without cut-point. In particular, if all the pieces are points then the cone is a tree. By homogeneity in this case it can be either a line or a tree in which every point is a branching point with the same degree.

The case when one asymptotic cone is a line turns out to be quite particular. More precisely, we have the following general results.

Proposition 6.1. Let $\mathscr{G}$ be a family of finitely generated non-virtually cyclic groups. Then for any sequence of groups $G_{n} \in \mathscr{G}$ endowed with word metrics $\operatorname{dist}_{n}$, any sequence $\left(\lambda_{n}\right)$ of positive numbers with lim $\lambda_{n}=0$, any $e \in \Pi G_{n}$ and any ultrafilter $\omega$, the ultralimit $\lim ^{\omega}\left(G_{n}, \lambda_{n} \operatorname{dist}_{n}\right)_{e}$ is neither a point nor a (real) line.

Proof. We may assume without loss of generality that $e_{n}=1$ for every $n$. If an ultralimit $\lim ^{\omega}\left(G_{n}, \lambda_{n} \operatorname{dist}_{n}\right)_{e}$ is a point then $G_{n}$ are finite $\omega$-almost surely, which is a contradiction.

Suppose that an ultralimit $\lim ^{\omega}\left(G_{n}, \lambda_{n} \text { dist }_{n}\right)_{e}$ is a line. Since $G_{n}$ are all infinite, it follows that for any $n \in \mathbb{N}$, there exists in Cayley $\left(G_{n}\right)$ a geodesic line $\mathfrak{g}_{n}$ through 1. Then $\lim ^{\omega}\left(\mathfrak{g}_{n}\right)=\lim ^{\omega}\left(G_{n}\right)$. Suppose by contradiction that $\omega$-almost surely $G_{n} \not \subset \mathscr{N}_{1 / \lambda_{n}}\left(\mathfrak{g}_{n}\right)$. Then $\omega$-almost surely there exists $z_{n} \in G_{n}$ at distance at least $1 / \lambda_{n}$ of $\mathfrak{g}_{n}$. Let $\mathfrak{I}_{n}$ be a geodesic joining $z_{n}$ to $z_{n}^{\prime} \in \mathfrak{g}_{n}$ and of length dist ${ }_{n}\left(z_{n}, \mathfrak{g}_{n}\right)$. For every point $t \in \mathfrak{I}_{n}$ we have $\operatorname{dist}_{n}\left(t, z_{n}^{\prime}\right)=\operatorname{dist}_{n}\left(t, \mathfrak{g}_{n}\right)$. By homogeneity we may suppose that $z_{n}^{\prime}=1$.

In the ultralimit $\lim ^{\omega}\left(G_{n}, \lambda_{n} \operatorname{dist}_{n}\right)_{e}, \mathrm{I}_{\omega}=\lim ^{\omega}\left(\mathrm{I}_{n}\right)$ is either a geodesic segment of length at least 1 with one endpoint $\lim ^{\omega}(1)$, or a geodesic ray of origin $\lim ^{\omega}(1)$. If $\mathrm{I}_{\omega}$ has a point in common with $\lim ^{\omega}\left(\mathfrak{g}_{n}\right)$ that is different from $\lim ^{\omega}(1)$, then $\omega$-almost surely there exists $t_{n} \in \mathfrak{I}_{n}$ at distance of order $1 / \lambda_{n}$ of 1 and at distance $o\left(1 / \lambda_{n}\right)$ of $\mathfrak{g}_{n}$. This contradicts the equality $\operatorname{dist}_{n}\left(t_{n}, 1\right)=\operatorname{dist}_{n}\left(t_{n}, \mathfrak{g}_{n}\right)$. Hence $\mathfrak{l}_{\omega} \cap \lim ^{\omega}\left(\mathfrak{g}_{n}\right)=\left\{\lim ^{\omega}(1)\right\}$. But in this case $\lim ^{\omega}\left(G_{n}\right) \neq \lim ^{\omega}\left(\mathfrak{g}_{n}\right)$, a contradiction.

It follows that $\omega$-almost surely $G_{n} \subset \mathscr{N}_{1 / \lambda_{n}}\left(\mathfrak{g}_{n}\right)$, which implies that $G_{n}$ is hyperbolic with boundary of cardinality 2 , and consequently virtually cyclic. We have obtained a contradiction.

Corollary 6.2. A finitely generated group with one asymptotic cone a point or a line is virtually cyclic.

### 6.1. Groups with central infinite cyclic subgroups

Let $G$ be a finitely generated group containing a central infinite cyclic subgroup $H=\langle a\rangle$. We fix a finite set of generators $X$ of $G$ and the corresponding word metric dist on $G$.

Lemma 6.3. For every asymptotic cone $\operatorname{Con}^{\omega}(G ; e, d)$ of $G$ and every $\varepsilon>0$, there exists an element $h=\left(h_{n}\right)^{\omega}$ in $G_{e}^{\omega} \cap H^{\omega}$ which acts isometrically on $\operatorname{Con}^{\omega}(G ; e, d)$, such that for every $x \in \operatorname{Con}^{\omega}(G ; e, d)$, $\operatorname{dist}(h x, x)=\varepsilon$.

Proof. Let $w$ be a word in $X$ representing $a$ in $G$. It is obvious that for every $r>0$ there exists $h=$ $a^{n} \in H$ such that $|h|$ is in the interval $[r-|w|, r+|w|]$. For every $n \geqslant 1$ we consider $h_{n} \in H$ such that $\left|h_{n}\right| \in\left[\varepsilon d_{n}-|w|, \varepsilon d_{n}+|w|\right]$. According to Remark 3.17, the element $h=\left(h_{n}\right)^{\omega}$ in $G_{e}^{\omega}$ acts as an isometry on $\operatorname{Con}^{\omega}(G ; e, d)$. Moreover, for every $g=\lim ^{\omega}\left(g_{n}\right) \in \operatorname{Con}^{\omega}(G ; e, d)$ we have that $\operatorname{dist}(h g, g)=\lim _{\omega}\left(\operatorname{dist}\left(h_{n} g_{n}, g_{n}\right) / d_{n}\right)=\lim _{\omega}\left(\operatorname{dist}\left(g_{n} h_{n}, g_{n}\right) / d_{n}\right)=\lim _{\omega}\left(\left|h_{n}\right| / d_{n}\right)=\varepsilon$.

Lemma 6.4. If an asymptotic cone $C$ of $G$ has a cut-point then $C$ is isometric to a point or a (real) line.
Proof. Let $C=\operatorname{Con}^{\omega}(G ; e, d)$ be an asymptotic cone that has a cut-point, where $e=(1), d=\left(d_{n}\right)$. Then $C$ is tree-graded with respect to a collection $\mathscr{P}$ of pieces that are either points or geodesic sets without cut-points. Let $h$ in $G_{e}^{\omega} \cap H^{\omega}$ be as in Lemma 6.3 for $\varepsilon=1$.

If all sets in $\mathscr{P}$ are points then $C$ is an $\mathbb{R}$-tree. If this tree contains a vertex of degree $>2$, then it does not admit an isometry $h$ such that $\operatorname{dist}(h(x), x)=1$ for every $x$. Thus in this case $C$ is isometric to $\mathbb{R}$ or to a point.

So we may suppose that $\mathscr{P}$ contains pieces that are not points. Let $M$ be such a piece.
Case I. Suppose $h(M)=M$. Let $x$ be an arbitrary point in $M$. By Lemma 2.31(b), there exists $y \in C \backslash M$ such that $x$ is the projection of $y$ on $M$. Let $\delta=\operatorname{dist}(x, y)$. Since $h$ acts as an isometry, it follows that $y^{\prime}=h(y)$ projects on $M$ in $x^{\prime}=h(x)$ and that $\delta=\operatorname{dist}\left(x^{\prime}, y^{\prime}\right)$. We have $\operatorname{dist}\left(x, x^{\prime}\right)=\operatorname{dist}\left(y, y^{\prime}\right)=1$. On the other hand Lemma 2.28 implies that $[y, x] \cup\left[x, x^{\prime}\right] \cup\left[x^{\prime}, y^{\prime}\right]$ is a geodesic. Consequently $\operatorname{dist}\left(y, y^{\prime}\right)=1+2 \delta$, a contradiction.

Case II. Suppose $h(M) \neq M$. Then $h(M)$ is another piece of the tree-graded space $C$, by Proposition 2.16. Let $x$ be the projection of $h(M)$ on $M$ and let $y$ be the projection of $M$ on $h(M)$. Let $z \in M \backslash\{x\}$ and $z^{\prime}=h(z)$. By moving $z$ a little, for instance along the geodesic $[z, x]$, we can ensure that $z^{\prime} \neq y$. Every geodesic joining $z$ and $z^{\prime}$ contains $x$ and $y$, by Lemma 2.6. Let $t$ be a point in $C \backslash M$ that projects on $M$ in $z$ (it exists by Lemma 2.31(b)). The projection of $t^{\prime}=h(t)$ onto $h(M)$ is then $z^{\prime}$. Lemma 2.28 implies that $[t, z] \cup[z, x] \cup[x, y] \cup\left[y, z^{\prime}\right] \cup\left[z^{\prime}, t^{\prime}\right]$ is a geodesic, whence $\operatorname{dist}\left(t, t^{\prime}\right)=1+2 \operatorname{dist}(t, z)$. This contradicts the fact that $\operatorname{dist}\left(t, t^{\prime}\right)=1$.

Theorem 6.5. Let $G$ be a non-virtually cyclic finitely generated group that has a central infinite cyclic subgroup $H$. Then $G$ is wide.

Proof. By contradiction suppose that $G$ is not wide. Lemma 6.4 implies that one of the asymptotic cones of $G$ is a line or a point. Corollary 6.2 implies that $G$ is virtually cyclic, a contradiction.

Corollary 6.6. Let $G$ be a non-virtually cyclic group, that is asymptotically tree-graded with respect to certain proper subgroups. Then every finitely generated subgroup in the center $Z(G)$ is finite.

Theorem 6.5 has the following uniform version.
Theorem 6.7. Let $\mathscr{G}$ be the family of all finitely generated non-virtually cyclic groups with a central infinite cyclic subgroup. The family $\mathscr{G}$ is uniformly unconstricted.

Proof. Consider $G_{n}$ a sequence of groups in $\mathscr{G}$, dist ${ }_{n}$ a word metric on $G_{n}$ and $H_{n}=\left\langle a_{n}\right\rangle$ a central infinite cyclic subgroup of $G_{n}$. Let $d_{n} \geqslant n \operatorname{dist}_{n}\left(1, a_{n}\right)$ for all $n$. An argument as in the proof of Lemma 6.3 implies that for every sequence of observation points $e$ and for every $\varepsilon>0$, the ultralimit $\lim ^{\omega}\left(G_{n}, \operatorname{dist}_{n} / d_{n}\right)_{e}$ has as isometry $h$ moving every point by $\varepsilon$. With an argument analogous to the one in the proof of Lemma 6.4 we deduce that $\lim ^{\omega}\left(G_{n}, \operatorname{dist}_{n} / d_{n}\right)_{e}$ is a line or a point. This contradicts Proposition 6.1.

Corollary 6.8. Let X be a metric space asymptotically tree-graded with respect to a collection of subsets $\mathscr{A}$. For every $(L, C)$ there exists $M=M(L, C)$ such that for every $(L, C)$-quasi-isometric embedding $\mathrm{q}: G \rightarrow X$ of a finitely generated non-virtually cyclic group $G$ with a central infinite cyclic subgroup, there exists $A \in \mathscr{A}$ such that $\mathfrak{q}(G) \subset \mathscr{N}_{M}(A)$.

### 6.2. Groups satisfying a law

Proposition 6.9. Let space $\mathbb{F}$ be tree-graded with respect to a collection $\mathscr{P}$ of proper subsets. Suppose that $\mathbb{F}$ is not an $\mathbb{R}$-tree and let $G$ be a group acting transitively on $\mathbb{F}$. Then $G$ contains a non-abelian free subgroup.

Remark. If $\mathbb{F}$ is an $\mathbb{R}$-tree, $G$ may contain no non-abelian free subgroups even if it acts transitively on $\mathbb{F}$. Indeed let $G$ be the group of upper triangular $2 \times 2$-matrices with determinant 1 acting by isometries on the hyperbolic plane $\mathbb{H}^{2}$. The action is transitive.

Therefore the (solvable) group $G_{e}^{\omega}$ acts transitively on an asymptotic cone of $\mathbb{-}^{2}$ which is an $\mathbb{R}$-tree.
Proof of Proposition 6.9. By Lemma 2.31 we can assume that every piece in $\mathscr{P}$ is either a point or does not have a cut-point.

Since $\mathbb{F}$ is not an $\mathbb{R}$-tree.
Lemma 6.10. Let $a$ and $b$ be two distinct points in $M$. There exists an isometry $g \in G$ such that the following property holds:

- $a \neq g(b)$, the projection of $g(M)$ onto $M$ is $a$ and the projection of $M$ onto $g(M)$ is $g(b)$.

We shall denote this property of $g$ by $P(a, b, M)$.
Proof. There are two cases:
(A) There exist two distinct pieces in $\mathscr{P}$ that intersect.
(B) Any two distinct pieces in $\mathscr{P}$ are disjoint.

By homogeneity, in case (A), every point is contained in two distinct pieces. In case (B) let $x, y$ be two distinct points in $M$. There exists an isometry $g \in G$ such that $g(x)=y$. Since $g(M)$ intersects $M$ in $y$ it follows that $g(M)=M$. We conclude that in this case the stabilizer of $M$ in $G$ acts transitively on $M$.

Suppose we are in case (A). Then we can construct a geodesic $\mathfrak{g}:[0, s] \rightarrow \mathbb{F}$ such that $s=\sum_{i=1}^{\infty} s_{n}$ with $0<s_{n}<1 / n^{2}$ and $\mathfrak{g}\left[\sum_{i=0}^{n} s_{i}, \sum_{i=0}^{n+1} s_{i}\right] \subset M_{n}$ for some pieces $M_{n}$, where $M_{n} \neq M_{n+1}$ for all $n \in \mathbb{N} \cup\{0\}$. Here $s_{0}=0$. Such a geodesic exists by Lemma 2.28. We call such a geodesic fractal at the arrival point. By gluing together two geodesics fractal at their respective arrival points, $\mathfrak{g} \cup \mathfrak{g}^{\prime}$, and making sure that the two respective initial pieces, $M_{0}$ and $M_{0}^{\prime}$, are distinct, we obtain a geodesic fractal at the departure and arrival points or bifractal. By homogeneity, every point in $\mathbb{F}$ is the endpoint of a bifractal geodesic.

Let $[a, c]$ be a bifractal geodesic. Corollary 2.10(b) implies that $[a, c]$ can intersect $M$ in $a$ or in a non-trivial sub-geodesic $\left[a, c^{\prime}\right]$. Since $[a, c]$ is fractal at the departure point the latter case cannot occur. It follows that the intersection of $[a, c]$ and $M$ is $\{a\}$. There exists an isometry $g \in G$ such that $g(b)=c$. Since $[a, c]$ is fractal at the arrival point also, it follows that $[a, c] \cap g(M)=\{c\}$. For every $x \in g(M)$ we have that $[a, c] \cup[c, x]$ is a geodesic, by Lemma 2.28. In particular $a$ is the projection of $g(M)$ on M. A symmetric argument gives that $c=g(b)$ is the projection of $M$ on $g(M)$.

Now suppose that case (B) holds. Lemma 2.31(b) implies that $a$ is the projection of a point $x \in \mathbb{F} \backslash M$. Let $g$ be an isometry in $G$ such that $g(b)=x$. If $[a, x]$ intersects $g(M)$ in $x$ then we repeat the previous argument. Assume $[a, x] \cap g(M)=\left[x^{\prime}, x\right]$. By the hypothesis in case (B), $x^{\prime} \neq a$. We have $x^{\prime}=g\left(b^{\prime}\right)$ for some $b^{\prime} \in M$. Since the stabilizer of $M$ in $G$ acts transitively on $M$, there exists $g^{\prime}$ in it such that $g^{\prime}(b)=b^{\prime}$. We have that $g g^{\prime}(M)=g(M)$ projects onto $M$ in $a$ and $M$ projects onto $g g^{\prime}(M)$ in $x^{\prime}=g g^{\prime}(b)$.

Notation. For every $t \in M$ let $\Pi_{t}(M)$ be the set of points $x$ in $\mathbb{F} \backslash M$ that project onto $M$ in $t$.

Lemma 6.11. Let $g$ satisfy property $P(a, b, M)$. Then
(a) the isometry $g^{-1}$ satisfies property $P(b, a, M)$;
(b) for every $t \neq b$ we have $g\left(\Pi_{t}(M)\right) \subset \Pi_{a}(M)$.

Proof. (a) We apply the isometry $g^{-1}$ to the situation in $P(a, b, M)$.
(b) The set $g\left(\Pi_{t}(M)\right)$ projects on $g(M)$ in $g(t) \neq g(b)$. This, property $P(a, b, M)$ and Corollary 2.29 imply that $g\left(\Pi_{t}(M)\right)$ projects onto $M$ in $a$ and that $\operatorname{dist}\left(g\left(\Pi_{t}(M)\right), M\right) \geqslant \operatorname{dist}(g(M), M)>0$.

We now finish the proof of Proposition 6.9. Let $a, b, c, d$ be four pairwise distinct elements in $M$. Lemma 6.10 implies that there exist $g \in G$ satisfying $P(a, b, M)$ and $h$ satisfying $P(c, d, M)$.

Then $g^{-1}$ is satisfying $P(b, a, M)$ and $h^{-1}$ is satisfying $P(d, c, M)$ by Lemma 6.11. In particular $g(M) \subset \Pi_{a}(M), g^{-1}(M) \subset \Pi_{b}(M), h(M) \subset \Pi_{c}(M), h^{-1}(M) \subset \Pi_{d}(M)$ (Fig. 5).

Since $b \notin\{a, c, d\}$, Lemma 6.11(b) implies that $g\left(\Pi_{a}(M) \cup \Pi_{c}(M) \cup \Pi_{d}(M)\right) \subset \Pi_{a}(M)$. The isometries $g^{-1}, h, h^{-1}$ satisfy similar properties. The Tits ping-pong argument allows one to conclude that $g$ and $h$ generate a free group.

Theorem 6.12. Let $\mathscr{G}$ be a family of finitely generated non-virtually cyclic groups satisfying a law. Then $\mathscr{G}$ is uniformly wide.

Proof. Suppose that an ultralimit $\lim ^{\omega}\left(G_{n},\left(1 / d_{n}\right) \operatorname{dist}_{n}\right)_{e}$ has a cut-point, where $\lim _{\omega} d_{n}=\infty$. Then by Lemma 2.31 and Proposition 6.1, $\lim ^{\omega}\left(G_{n},\left(1 / d_{n}\right) \operatorname{dist}_{n}\right)_{e}$ is a tree-graded space, not reduced to a point


Fig. 5. Action of the elements $g, g^{-1}, h, h^{-1}$.
nor isometric to $\mathbb{R}$. The group $\mathscr{G}=\Pi_{e}\left(G_{n},\left(1 / d_{n}\right) \operatorname{dist}_{n}\right) / \omega$ acts transitively on $\mathscr{C} \lim ^{\omega}\left(G_{n},\left(1 / d_{n}\right) \operatorname{dist}_{n}\right)_{e}$. If $\mathscr{C}$ is not an $\mathbb{R}$-tree then Proposition 6.9 implies that $G=\Pi_{e}\left(G_{n},\left(1 / d_{n}\right)\right.$ dist $\left._{n}\right) / \omega$ contains a non-abelian free subgroup, and so it cannot satisfy a non-trivial law, a contradiction.

Suppose that $\mathscr{C}$ is an $\mathbb{R}$-tree. By [15, Proposition 3.7, p. 111], if $\mathscr{G}$ does not fix an end of $\mathscr{C}, \mathscr{G}$ contains a non-abelian free subgroup, a contradiction. Therefore we can assume that $\mathscr{G}$ fixes an end of $\mathscr{C}$. This means that $\mathscr{G}$ asymptotically fixes a ray $s(t), t \in[0, \infty)$, starting at $e$. We shall now show that this assumption leads to a contradiction.

Since the action of $\mathscr{G}$ on $\mathscr{C}$ is transitive, the ball of radius 1 in $\mathscr{C}$ around $e$ contains at least 9 disjoint isometric copies of the ball of radius $1 / 4$ (of course, here 9 can be replaced by any positive integer). This implies that $\omega$-almost surely for all $n$, the number of elements in the ball of radius $d_{n}$ in the Cayley graph of $G_{n}$ is at least 9 times bigger than the number of elements in the ball of radius $d_{n} / 4$.

For $x \in\{1,1.25,1.5,1.75\}$ let $s(x)=\left(u_{n}(x)\right)^{\omega}$, for some $u_{n}(x) \in G_{n}$. Take any $g=\left(g_{n}\right)^{\omega} \in \mathscr{G}$ such that $\operatorname{dist}_{n}\left(g_{n}, 1\right) \leqslant d_{n}$. Then $\operatorname{dist}(g \cdot 1, e) \leqslant 1$. Note that the image $g \cdot s$ is a ray which must be asymptotically equal to $s$. Therefore the intersection $g \cdot s$ and $s$ contains the subray $s(t), t \in[1, \infty)$. Since $g$ acts asymptotically on this ray by translation, either $g \cdot s(1)$ or $g^{-1} \cdot s(1)$ belongs to the interval $s(t), t \in[1,2]$ of this subray. Therefore either $g \cdot s(1)$ or $g^{-1} \cdot s(1)$ is within distance $1 / 4$ from $s(x)$ for some $x \in\{1,1.25,1.5,1.75\}$. This implies that $\omega$-almost surely for any $n$, and any $g_{n} \in G_{n}$ with $\operatorname{dist}_{n}\left(g_{n}, 1\right) \leqslant d_{n}$, for some $x \in\{1,1.25,1.5,1.75\}$, and a choice of $\varepsilon \in\{1,-1\}$, we have

$$
\operatorname{dist}_{n}\left(u_{n}(x)^{-1} g_{n}^{\varepsilon} u_{n}(1), 1\right) \leqslant d_{n} / 4
$$

This implies that $\omega$-almost surely for every $n$ the ball of radius $d_{n}$ in the Cayley graph of $G_{n}$ contains at most 8 times more elements than the ball of radius $d_{n} / 4$, a contradiction with the statement from the previous paragraph.

Examples. Solvable groups of a given degree, Burnside groups of a fixed exponent and uniformly amenable groups (see Corollary 6.16) are examples of groups satisfying a law.

Corollary 6.13. Let $G$ be a finitely generated non-virtually cyclic group satisfying a law. Then $G$ is wide.

Corollary 6.14. Let metric space $X$ be asymptotically tree-graded with respect to a collection of subsets $\mathscr{A}$. For every non-trivial group law and every $(L, C)$ there exists a constant $M$ depending on $(L, C)$ and on the law such that the following holds. Any ( $L, C$ )-quasi-isometric embedding of a finitely generated non-virtually cyclic group satisfying the law into $X$ has the image in $\mathcal{N}_{M}(A)$ for some $A \in \mathscr{A}$.

The following statement is probably well known but we did not find a proper reference.
Lemma 6.15. Let $\omega$ be any ultrafilter, $G$ any group. The group $G$ satisfies a law if and only if its ultrapower $\Pi G / \omega$ does not contain free non-abelian subgroups.

Proof. Clearly, if $\Pi G / \omega$ contains a free non-abelian subgroup then $G$ does not satisfy any law. Conversely assume that $G$ does not satisfy any law. Let us list all words in two variables: $u_{1}, u_{2}, \ldots$, and form a sequence of words $v_{1}=u_{1}, v_{2}=\left[u_{1}, u_{2}\right], v_{3}=\left[u_{1}, u_{2}, u_{3}\right], \ldots$ (iterated commutators). We can choose the sequence $u_{1}, u_{2}, \ldots$ in such a way that none of the words $v_{i}$ is equal to 1 in the free group. Since $G$ does not satisfy a law, for every $i$ there exists a pair $\left(x_{i}, y_{i}\right)$ in $G$ such that $v_{i}\left(x_{i}, y_{i}\right)$ is not 1 in $G$. Let $x=\left(x_{i}\right)^{\omega}, y=\left(y_{i}\right)^{\omega}$ be elements in the ultrapower. Suppose that the subgroup $\langle x, y\rangle$ of $\Pi G / \omega$ has a relation. That relation is some word $u_{i}$ in two variables. Hence $u_{i}\left(x_{j}, y_{j}\right)=1 \omega$-almost surely. In particular, since $\omega$ is a non-principal ultrafilter, for some $j>i, u_{i}\left(x_{j}, y_{j}\right)=1$. But then $v_{j}\left(x_{j}, y_{j}\right)=1$ since $u_{i}$ is a factor in the commutator $v_{j}$, a contradiction.

Recall that a discrete group $G$ is (Fölner) amenable if for every finite subset $K$ of $G$ and every $\varepsilon \in(0,1)$ there exists a finite subset $F \subset G$ satisfying

$$
|K F|<(1+\varepsilon)|F| .
$$

The group $G$ is uniformly amenable if, in addition, one can bound the size of $F$ in terms of $\varepsilon$ and $|K|$, i.e. there exists a function $\phi:(0,1) \times \mathbb{N} \rightarrow \mathbb{N}$ such that

$$
|F| \leqslant \phi(\varepsilon,|K|) .
$$

For details on the latter notion see $[36,9,55]$. The following result has also been obtained in [36, Corollary 5.9]; we give a proof here for the sake of completeness.

Corollary 6.16. A uniformly amenable finitely generated group satisfies a law and so it is wide if it is not virtually cyclic.

Proof. Indeed, by [55], if $G$ is uniformly amenable then any ultrapower $\Pi G / \omega$ is Fölner amenable. Hence we can apply Lemma 6.15 if we prove that any subgroup $S$ of an arbitrary Fölner amenable group $H$ is Fölner amenable.

The argument is fairly standard and well known; we present it here only for the sake of completeness. Take an arbitrary small $\varepsilon>0$. Take $K$ a finite subset in $S$. There exists a subset $F$ in $H$ such that $|K F|<(1+\varepsilon)|F|$. Consider a graph whose vertices are the elements of the set $F$, and whose edges correspond to the pairs of points $\left(f_{1}, f_{2}\right) \in F \times F$ such that $f_{2}=k f_{1}$, where $k \in K$. Let $C$ be a connected component of this graph with set of vertices $\mathscr{V}_{C}$. Then $K \mathscr{V}_{C}$ does not intersect the sets of vertices of other connected components. Hence there exists a connected component $C$ such that $\left|K \mathscr{V}_{C}\right|<(1+\varepsilon)\left|\mathscr{V}_{C}\right|$ (otherwise if all these inequalities have to be reversed, the sum of them gives a contradiction with the
choice of $F$ ). Without loss of generality, we can assume that $\mathscr{V}_{C}$ contains 1 . Otherwise we can shift it to 1 by multiplying on the right by $c^{-1}$ for some $c \in \mathscr{V}_{C}$. Then $\mathscr{V}_{C}$ can be identified with a finite subset of $S$. Therefore $S$ contains a subset $\mathscr{V}_{C}$ such that $\left|K \mathscr{V}_{C}\right|<(1+\varepsilon)\left|\mathscr{V}_{C}\right|$.

Remark 6.17. The amenability defined by the existence of a left invariant mean on the set of functions uniformly continuous to the left is not inherited by subgroups in general. If $\mathscr{H}$ is a separable infinite dimensional Hilbert space and $G=U(\mathscr{H})$ is the group of unitary operators on $\mathscr{H}$ endowed with the weak operator topology, then $G$ is amenable in the above sense [18]. On the other hand, if we take $\mathscr{H}=\ell^{2}\left(\mathbb{F}_{2}\right)$, with $\mathbb{F}_{2}$ the free group of two generators, then $G$ contains $\mathbb{F}_{2}$ [3, Remark G.3.7].

## 7. Fundamental groups of asymptotic cones

In [26], Erschler and Osin constructed (modifying an idea from [42]), for every "sufficiently good" metric space $M$, a two-generated group $G$ with the property that $M \pi_{1}$-embeds isometrically into an asymptotic cone $\operatorname{Con}^{\omega}(G)$. Thus any countable group is a subgroup of the fundamental group of some asymptotic cone of a finitely generated group. In this section we modify, in turn, the construction from [26] to show that the fundamental group of an asymptotic cone can be isomorphic to the uncountable free power of any countable group. Moreover, that asymptotic cone can be completely described as a treegraded space. In particular, if, say, $M$ is compact and locally contractible then there exists a 2 -generated group, one of whose asymptotic cones is tree-graded with respect to pieces isometric to $M$. We also construct a 2-generated recursively presented group with the maximal possible (under the continuum hypothesis) number of non-homeomorphic asymptotic cones.

### 7.1. Preliminaries on nets

Let ( $X$, dist) be a metric space. We recall some notions and results from [31].
Definition 7.1. A $\delta$-separated $\operatorname{set} A$ in $X$ is a set such that for every $x_{1}, x_{2} \in A, \operatorname{dist}\left(x_{1}, x_{2}\right) \geqslant \delta$. A $\delta$-net in $X$ is a set $B$ such that $X \in \mathscr{N}_{\delta}(B)$.

Remark 7.2. A maximal $\delta$-separated set in $X$ is a $\delta$-net in $X$.
Proof. Let $N$ be a maximal $\delta$-separated set in $X$. For every $x \in X \backslash N$, the set $N \cup\{x\}$ is no longer $\delta$-separated, by maximality of $N$. Hence there exists $y \in N$ such that $\operatorname{dist}(x, y)<\delta$.

Definition 7.3. We call a maximal $\delta$-separated set in $X$ a $\delta$-snet.
Note that if $X$ is compact then every snet is finite; hence every separated set is finite.
Remark 7.4. Let ( $X$, dist) be a metric space and let $\left(M_{n}\right)_{n \in \mathbb{N}}$ be an increasing sequence of subsets of $X$. Let $\left(\delta_{n}\right)_{n \in \mathbb{N}}$ be a decreasing sequence of positive numbers converging to zero. There exists an increasing sequence

$$
N_{1} \subset N_{2} \subset \cdots \subset N_{n} \subset \cdots,
$$

such that $N_{n}$ is a $\delta_{n}$-snet in $\left(M_{n}\right.$, dist $)$.

Proof. There exists a $\delta_{1}$-snet in $M_{1}$, which we denote $N_{1}$. It is a $\delta_{1}$-separated set in $M_{2}$. Let $N_{2}$ be a $\delta_{2}$-snet in $M_{2}$ containing $N_{1}$. Then $N_{2}$ is a $\delta_{2}$-separated set in $M_{3}$. Inductively we construct an increasing sequence $\left(N_{n}\right)_{n \in \mathbb{N}}$.

Notation. Let $A$ be a subset in a metric space. We denote by $\Gamma_{\kappa}(A)$ the metric graph with set of vertices $A$ and set of edges

$$
\left\{\left(a_{1}, a_{2}\right) \mid a_{1}, a_{2} \in A, 0<\operatorname{dist}\left(a_{1}, a_{2}\right) \leqslant \kappa\right\}
$$

such that the edge $\left(a_{1}, a_{2}\right)$ is of length $\operatorname{dist}\left(a_{1}, a_{2}\right)$. We shall denote the length of every edge $e$ by $|e|$. We endow $\Gamma_{\kappa}(A)$ with its length metric.

Notation. Let ( $X, \operatorname{dist}$ ) be a proper geodesic metric space, let $O$ be a fixed point in it and let $\zeta \in(0,1)$. We denote by $B_{n}=\overline{B(O, n)}$ the closed ball of radius $n$ around $O$. We consider an increasing sequence of subsets in $X$,

$$
\{O\} \subset N_{1} \subset N_{2} \subset \cdots \subset N_{n} \subset \cdots,
$$

such that $N_{n}$ is an $\zeta^{n}$-snet in $B_{n}$. Let $\Gamma_{n}$ be the finite graph $\Gamma_{\zeta^{[n / 2]}}\left(N_{n}\right)$, endowed with its length metric dist $_{n}$ (here $[n / 2]$ is the integer part of $n / 2$ ).

We recall that two metric spaces with fixed basepoints $\left(X, \operatorname{dist}_{X}, x\right)$ and $\left(Y, \operatorname{dist}_{Y}, y\right)$ are said to be isometric if there exists an isometry $\phi: X \rightarrow Y$ such that $\phi(x)=y$.

Lemma 7.5. In the notation as above:
(1) for every $n \geqslant 2$, for every $x, y \in N_{n}$ we have

$$
\begin{equation*}
\operatorname{dist}(x, y) \leqslant \operatorname{dist}_{n}(x, y) \leqslant\left(1+6 \zeta^{k}\right)\left(\operatorname{dist}(x, y)+2 \zeta^{k}\right)+2 \zeta^{k} \tag{11}
\end{equation*}
$$

where $k=[n / 2]$;
(2) for every observation point $e \in \Pi N_{n} / \omega$, the spaces $\lim ^{\omega}\left(N_{n}, \operatorname{dist}_{n}\right)_{e}, \lim ^{\omega}\left(\Gamma_{n}, \operatorname{dist}_{n}\right)_{e}$ and $\lim ^{\omega}\left(B_{n}, \text { dist }\right)_{e}$ with the basepoints $\lim ^{\omega}(e)$ are isometric;
(3) the spaces $\lim ^{\omega}\left(N_{n}, \operatorname{dist}_{n}\right), \lim ^{\omega}\left(\Gamma_{n}, \operatorname{dist}_{n}\right)$ with the basepoints $\lim ^{\omega}(O)$ and $(X$, dist) with the basepoint $O$ are isometric.

Proof. (1) Let $x, y$ be two fixed points in $N_{n}$. If $\operatorname{dist}(x, y) \leqslant \zeta^{[n / 2]}$ then by construction $\operatorname{dist}(x, y)=$ $\operatorname{dist}_{n}(x, y)$ and both inequalities in (11) are true. Let us suppose that dist $(x, y)>\zeta^{[n / 2]}$.

The distance $\operatorname{dist}_{n}(x, y)$ in $\Gamma_{n}$ is the length of some path composed of the edges $e_{1} e_{2} \ldots e_{s}$, where $x=\left(e_{1}\right)_{-}$and $y=\left(e_{s}\right)_{+}$. It follows that

$$
\operatorname{dist}_{n}(x, y)=\sum_{i=1}^{s}\left|e_{i}\right| \geqslant \operatorname{dist}(x, y)
$$

We conclude that

$$
\operatorname{dist}_{n}(x, y) \geqslant \operatorname{dist}(x, y) .
$$

We also note that

$$
\begin{equation*}
\operatorname{dist}_{n}(x, y) \geqslant \operatorname{dist}_{m}(x, y) \quad \text { for every } m \geqslant n, \tag{12}
\end{equation*}
$$

since $N_{n} \subseteq N_{m}$.
The distance $\operatorname{dist}(x, y)$ is the length of a geodesic $c:[0, \operatorname{dist}(x, y)] \rightarrow X$. Since $x, y \in N_{n} \subset \overline{B(O, n)}$, the image of this geodesic is entirely contained in $\overline{B(O, 2 n)}$. Let $t_{0}=0, t_{1}, t_{2}, \ldots, t_{m}=\operatorname{dist}(x, y)$ be a sequence of numbers in $[0, \operatorname{dist}(x, y)]$ such that $0<t_{i+1}-t_{i} \leqslant \zeta^{n} / 2$, for every $i \in\{1,2, \ldots, m-1\}$ and $m \leqslant 2 \operatorname{dist}(x, y) / \zeta^{n}+1$. Since dist $(x, y)>\zeta^{[n / 2]}>\zeta^{n}$, we can write $m \leqslant 3 \operatorname{dist}(x, y) / \zeta^{n}$. Let $x_{i}=\mathfrak{c}\left(t_{i}\right), i \in$ $\{0,1,2, \ldots, m\}$. For every $i \in\{0,1,2, \ldots, m\}$ there exists $w_{i} \in N_{2 n}$ such that dist $\left(x_{i}, w_{i}\right) \leqslant \zeta^{2 n}$. We note that $w_{0}=x, w_{m}=y$. We can write

$$
\begin{equation*}
\operatorname{dist}(x, y)=\sum_{i=0}^{m-1} \operatorname{dist}\left(x_{i}, x_{i+1}\right) \geqslant \sum_{i=0}^{m-1}\left[\operatorname{dist}\left(w_{i}, w_{i+1}\right)-2 \zeta^{2 n}\right] \sum_{i=0}^{m-1} \operatorname{dist}\left(w_{i}, w_{i+1}\right)-2 m \zeta^{2 n} \tag{13}
\end{equation*}
$$

We have $\operatorname{dist}\left(w_{i}, w_{i+1}\right) \leqslant \operatorname{dist}\left(x_{i}, w_{i}\right)+\operatorname{dist}\left(x_{i}, x_{i+1}\right)+\operatorname{dist}\left(x_{i+1}, w_{i+1}\right) \leqslant 2 \zeta^{2 n}+\zeta^{n} / 2 \leqslant \zeta^{n}$ for $n$ large enough. Therefore $w_{i}, w_{i+1}$ are connected in $\Gamma_{2 n}$ by an edge of length dist $\left(w_{i}, w_{i+1}\right)$. We conclude that

$$
\sum_{i=0}^{m-1} \operatorname{dist}\left(w_{i}, w_{i+1}\right)=\sum_{i=0}^{m-1} \operatorname{dist}_{2 n}\left(w_{i}, w_{i+1}\right) \geqslant \operatorname{dist}_{2 n}\left(w_{0}, w_{m}\right)=\operatorname{dist}_{2 n}(x, y)
$$

This and (13) implies that

$$
\operatorname{dist}(x, y) \geqslant \operatorname{dist}_{2 n}(x, y)-6 \operatorname{dist}(x, y) \zeta^{n} .
$$

We have obtained that

$$
\begin{equation*}
\frac{1}{1+6 \zeta^{n}} \operatorname{dist}_{2 n}(x, y) \leqslant \operatorname{dist}(x, y) \leqslant \operatorname{dist}_{n}(x, y) \quad \text { for all } x, y \in N_{n} \tag{14}
\end{equation*}
$$

Let again $x, y$ be two points in $N_{n}, k=[n / 2]$. There exist $x^{\prime}, y^{\prime} \in N_{k} \subset N_{n}$ such that dist $\left(x, x^{\prime}\right)$, $\operatorname{dist}\left(y, y^{\prime}\right) \leqslant \zeta^{k}$. This implies that dist $\left(x, x^{\prime}\right)=\operatorname{dist}_{n}\left(x, x^{\prime}\right) \leqslant \zeta^{k}$ and likewise $\operatorname{dist}\left(y, y^{\prime}\right)=\operatorname{dist}_{n}\left(y, y^{\prime}\right) \leqslant \zeta^{k}$. Hence $\operatorname{dist}_{n}(x, y) \leqslant \operatorname{dist}_{n}\left(x^{\prime}, y^{\prime}\right)+2 \zeta^{k}$.

Inequalities (12) and (14) imply

$$
\operatorname{dist}_{n}\left(x^{\prime}, y^{\prime}\right) \leqslant \operatorname{dist}_{2 k}\left(x^{\prime}, y^{\prime}\right) \leqslant\left(1+6 \zeta^{k}\right) \operatorname{dist}\left(x^{\prime}, y^{\prime}\right) \leqslant\left(1+6 \zeta^{k}\right)\left(\operatorname{dist}(x, y)+2 \zeta^{k}\right)
$$

This gives (11).
(2) We have $N_{n} \subset \Gamma_{n} \subset \mathscr{N}_{\zeta^{[n / 2]}}\left(N_{n}\right)$. Therefore $\lim ^{\omega}\left(\Gamma_{n}, \operatorname{dist}_{n}\right)_{e}=\lim ^{\omega}\left(N_{n}, \operatorname{dist}_{n}\right)_{e}$. Thus it is enough to prove that $\lim ^{\omega}\left(N_{n}, \operatorname{dist}_{n}\right)_{e}$ and $\lim ^{\omega}\left(B_{n}, \operatorname{dist}^{2}\right)_{e}$ with the basepoints $\lim ^{\omega}(e)$ are isometric.

We define the map

$$
\begin{equation*}
\Psi: \lim ^{\omega}\left(x_{n}\right) \mapsto \lim ^{\omega}\left(x_{n}\right) \tag{15}
\end{equation*}
$$

from $\lim ^{\omega}\left(N_{n}, \operatorname{dist}_{n}\right)_{e}$ to $\lim ^{\omega}\left(B_{n}, \text { dist }\right)_{e}$. Inequalities (11)imply that the map $\Psi$ is well defined and that it is an isometric embedding.

We prove that $\Psi$ is surjective. Let $\left(y_{n}\right)^{\omega} \in \Pi_{e} B_{n} / \omega$. For every $y_{n}$ there exists $x_{n} \in N_{n}$ such that $\operatorname{dist}\left(x_{n}, y_{n}\right) \leqslant \zeta^{n}$. Since the sequence $\left(\operatorname{dist}\left(y_{n}, e_{n}\right)\right)$ is bounded, the sequence $\left(\operatorname{dist}\left(x_{n}, e_{n}\right)\right)$ is also
bounded by the second inequality in (11), and so is the sequence $\left(\operatorname{dist}_{n}\left(x_{n}, e_{n}\right)\right.$ ). We have $\lim ^{\omega}\left(x_{n}\right) \in$ $\lim ^{\omega}\left(N_{n}, \operatorname{dist}_{n}\right)_{e}$ and $\Psi\left(\lim ^{\omega}\left(x_{n}\right)\right)=\lim ^{\omega}\left(x_{n}\right) . \operatorname{As} \lim _{\omega} \operatorname{dist}\left(x_{n}, y_{n}\right)=0$ we conclude that $\lim ^{\omega}\left(x_{n}\right)=$ $\lim ^{\omega}\left(y_{n}\right)$.
(3) According to (2) it suffices to prove that $\lim ^{\omega}\left(B_{n} \text {, dist) }\right)_{O}$ with the basepoint $\lim ^{\omega}(O)$ and $X$ with the basepoint $O$ are isometric. Let $x \in X$. For $n$ large enough, $x \in \overline{B(O, n)}$. We define the map

$$
\begin{equation*}
\Phi: x \mapsto \lim ^{\omega}(x) \tag{16}
\end{equation*}
$$

from $X$ to $\lim ^{\omega}\left(B_{n}\right)_{O}$.
The map $\Phi$ is clearly an isometric embedding. Let us show that $\Phi$ is surjective. Let $\left(x_{n}\right)_{n \in \mathbb{N}}$ be such that $x_{n} \in B_{n}$ and such that $\operatorname{dist}\left(O, x_{n}\right)$ is uniformly bounded by a constant $C$. It follows that $x_{n} \in \overline{B(O, C)}$ for all $n \in \mathbb{N}$. Since the space $X$ is proper, $\overline{B(O, C)}$ is compact and there exists an $\omega$-limit $x$ of $\left(x_{n}\right)$. It follows that $\lim _{\omega} \operatorname{dist}\left(x_{n}, x\right)=0$, which implies that $\lim ^{\omega}\left(x_{n}\right)=\lim ^{\omega}(x)=\Phi(x)$.

Notation. We shall denote the point $\lim ^{\omega}(O)$ also by $O$. This should not cause any confusion.
Remark 7.6. The hypothesis that $X$ is proper is essential for the surjectivity of $\Phi$ in the proof of part (3) of Lemma 7.5.

Definition 7.7. For every proper geodesic metric space ( $X$, dist) with a fixed basepoint $O$, and every sequence of points $e=\left(e_{n}\right)^{\omega}, e_{n} \in B_{n}=\overline{B(O, n)}$, we shall call the limit $\lim ^{\omega}\left(B_{n}\right)_{e}$ an ultraball of $X$ with center $O$ and observation point $e$.

Remark 7.8. Notice that the ultraballs $\lim ^{\omega}\left(B_{n}\right)_{e}$ and $\lim ^{\omega}\left(B_{n}\right)_{e^{\prime}}$ with observation points $e=\left(e_{n}\right)^{\omega}$ and $e^{\prime}=\left(e_{n}^{\prime}\right)^{\omega}$, such that $\operatorname{dist}\left(e_{n}, e_{n}^{\prime}\right)$ is uniformly bounded $\omega$-almost surely, are the same spaces with different basepoints (see Remark 3.7).

Remark 7.9. It is easy to prove, using results from [2, Section I.3]; [33], that an ultraball of a complete homogeneous locally compact CAT(0)-space is either the whole space or a horoball in it (for a definition see [11]). In particular the ultraballs of the Euclidean space $\mathbb{R}^{n}$ are $\mathbb{R}^{n}$ itself and all its half-spaces.

We are now going to construct a proper geodesic metric space with basepoint ( $Y_{C}$, dist, $O$ ) whose fundamental group is any prescribed countable group $C$, and such that every ultraball with center $O$ of $Y_{C}$ either is isometric to the space $Y_{C}$ itself or is simply connected.

Let $C=\langle S \mid R\rangle$ be a countable group. We assume that $S=\left\{s_{n} \mid n \in \mathbb{N}\right\}=C$, and that $R$ is just the multiplication table of $C$, i.e. that all relations in $R$ are triangular. For every $n \in \mathbb{N}$, consider $X_{n}$ the part of the cone $z^{2}=x^{2}+y^{2}$ in $\mathbb{R}^{3}$ which is above the plane $z=n-1$. The intersection of this (truncated) cone with the plane $z=n-1$ will be called its base. Cut a slit in $X_{n}$ of length $n \pi$, in the intersection of $X_{n}$ with the plane $z=2 n$. This slit has simple closed curve boundary of length $2 n \pi$, same as the length of the base of $X_{n+1}$. The resulting space is denoted by $Y_{n}$. The vertex of $Y_{1}$ is denoted by $O$.

Now consider the following construction. We start with the space $Y_{1}$, glue in the space $Y_{2}$ so that the base hole of $Y_{2}$ is isometrically identified with the boundary of the slit cut in $Y_{1}$, glue in $Y_{3}$ so that the base hole of $Y_{3}$ is identified with the boundary of the slit in $Y_{2}$, etc. The resulting space with the natural gluing metric is denoted by $Y$. Now enumerate all relations in $R=\left\{r_{1}, r_{2}, \ldots\right\}$. For every $m=1,2, \ldots$, $r_{m}$ has the form $x_{i} x_{j} x_{k}^{-1}$. Choose a natural number $k=k(m)$ such that the base holes of $Y_{i}, Y_{j}, Y_{k}$ are at the distance $\leqslant k$ in $Y$ and such that $k(m)>k(m-1)$. Consider the circles $y_{i}, y_{j}, y_{k}$ obtained by cutting
$Y_{i}, Y_{j}, Y_{k}$ by planes parallel to the base hole at distance $k$ from $O$, and connect these circles with $O$ by geodesics. Glue in a Euclidean disc $D_{n}$ to the circles $y_{i}, y_{j}, y_{k}$ and connecting geodesics such that the boundary of $D_{n}$ is glued, locally isometrically, according to the relation $r_{m}$. We supply the resulting space $Y_{C}$ with the natural geodesic metric dist.

We keep the above notation for balls $B_{n}=\overline{B(O, n)}$, and metric spaces $N_{n}$ and $\Gamma_{n}$ for this space $Y_{C}$.
The following properties of the space ( $Y_{C}$, dist) are obvious.
Lemma 7.10. (1) The space $Y_{C}$ is geodesic and proper.
(2) For every $d>0$ there exists a number $r>0$ such that every ball of radius $d$ in $Y_{C}$, whose center is outside $B(O, r)$, is contractible.
(3) The fundamental group of $Y_{C}$ is isomorphic to $C$.

Lemma 7.11. The ultraball $\lim ^{\omega}\left(B_{n}\right)_{e}$ of $Y_{C}$ with center $O$ is simply connected if dist $\left(e_{n}, O\right)$ is unbounded $\omega$-almost surely, otherwise it is isometric to $Y_{C}$.

Proof. Indeed, if a point $e=\left(e_{n}\right)$ from $X^{\omega}$ is such that $\operatorname{dist}\left(e_{n}, O\right)$ is bounded $\omega$-almost surely then the corresponding ultraball is isometric to $Y_{C}$ by Remark 7.8. Suppose that

$$
\lim _{\omega} \operatorname{dist}\left(e_{n}, O\right)=\infty
$$

Let $U$ be the corresponding ultraball. Then every closed ball $\overline{B_{U}(e, r)}$ in $U$ is the $\omega$-limit of $B_{Y_{C}}\left(e_{n}, r\right) \cap B_{n}$. By Lemma 7.10, the balls $B_{Y_{C}}\left(e_{n}, r\right)$ are contractible $\omega$-almost surely. Therefore $\overline{B_{U}(e, r)}$ is contractible. Since every loop in $U$ is contained in one of the balls $\overline{B_{U}(e, r)}, U$ is simply connected.

### 7.2. Construction of the group

Let $A$ be an alphabet and $\mathbb{F}_{A}$ a free group generated by $A$. For every $w \in \mathbb{F}_{A}$ we denote by $|w|$ the length of the word $w$.

Definition 7.12 (property $C^{*}(\lambda)$ ). A set $\mathscr{W}$ of reduced words in $\mathbb{F}_{A}$, that is closed under cyclic permutations and taking inverses, is said to satisfy property $C^{*}(\lambda)$ if the following hold.
(1) If $u$ is a subword in a word $w \in \mathscr{W}$ so that $|u| \geqslant \lambda|w|$ then $u$ occurs only once in $w$.
(2) If $u$ is a subword in two distinct words $w_{1}, w_{2} \in \mathscr{W}$ then $|u| \leqslant \lambda \min \left(\left|w_{1}\right|,\left|w_{2}\right|\right)$.

We need the following result from [26].
Proposition 7.13 (Erschler and Osin [26]). Let $A=\{a, b\}$. For every $\lambda>0$ there exists a set $\mathscr{W}$ of reduced words in $\mathbb{F}_{A}$, closed with respect to cyclic permutations and taking inverses, satisfying the following properties:
(1) $\mathscr{W}$ satisfies $C^{*}(\lambda)$;
(2) for every $n \in \mathbb{N}$, the set $\left\{w \in \mathscr{W}||w| \geqslant n\}\right.$ satisfies $C^{*}\left(\lambda_{n}\right)$ with $\lim _{n \rightarrow \infty} \lambda_{n}=0$;
(3) $\lim _{n \rightarrow \infty} \operatorname{card}\{w \in \mathscr{W}| | w \mid=n\}=\infty$.

Notation. Let us fix $\lambda=\frac{1}{500}$, and a set of words $\mathscr{W}$ provided by Proposition 7.13.

Let $\kappa(n)=\operatorname{card}\{w \in \mathscr{W}| | w \mid=n\}$. We have that $\lim _{n \rightarrow \infty} \kappa(n)=\infty$.
Fix a number $\zeta \in(0,1)$. For every $n \in \mathbb{N}$, let $\Gamma_{n}$ be a finite metric graph with edges of length at least $\zeta^{n}$ and at most $\zeta^{[n / 2]}$ and diameter at most $10 n$ for $n$ large enough. We endow $\Gamma_{n}$ with the length metric dist $_{n}$. Let $N_{n}$ be the set of vertices of $\Gamma_{n}$ and let $O_{n}$ be a fixed vertex in $N_{n}$. Let $E_{n}$ be the number of edges of $\Gamma_{n}$.

Definition 7.14 (fast increasing sequences). An increasing sequence ( $d_{n}$ ) of positive numbers is called fast increasing with respect to the sequence of $\operatorname{graphs}\left(\Gamma_{n}\right)$ if it satisfies the following:
(1) for every $i \geqslant\left[\zeta^{n} d_{n}\right], \kappa(i) \geqslant E_{n}$;
(2) $\lim _{n \rightarrow \infty} \frac{\zeta^{n} d_{n}}{d_{n-1}}=\infty$;
(3) $\lim _{n \rightarrow \infty} \frac{E_{n}}{\zeta^{n} d_{n}}=0$.

Fast increasing sequences of numbers clearly exist.
Let us fix a fast increasing sequence $d=\left(d_{n}\right)$ with respect to the sequence of graphs $\left(\Gamma_{n}\right)$.
To every edge $e=(x, y)$ in $\Gamma_{n}$ we attach a word $w_{n}(e)$ in $\mathscr{W}$ of length $\left[d_{n}|e|\right]$ such that
(1) $w_{n}\left(e^{-1}\right)=w_{n}(e)^{-1}$;
(2) $w_{n}(e) \neq w_{n}\left(e^{\prime}\right)$ if $e \neq e^{\prime}$.

We can choose these words because for every edge $e=(x, y)$ in $\Gamma_{n}$, we have $\left[d_{n} \operatorname{dist}(x, y)\right] \geqslant\left[\zeta^{n} d_{n}\right]$ and because we have enough words in $\mathscr{W}$ of any given length (part (1) of Definition 7.14).

Definition 7.15 (the presentation of the group $G$ ). We define the set of relations $R_{n}$ as follows: for every loop $p=e_{1} e_{2} \ldots e_{s}$ in $\Gamma_{n}$ we include in $R_{n}$ the free reduction of the word

$$
w_{n}(p)=w_{n}\left(e_{1}\right) w_{n}\left(e_{2}\right) \cdots w_{n}\left(e_{s}\right)
$$

Let $R=\bigcup_{n \in \mathbb{N}} R_{n}$ and let $G=\langle a, b \mid R\rangle$.
Notation. We denote by Cayley $(G)$ the left invariant Cayley graph of $G$ with respect to the presentation $G=\langle a, b \mid R\rangle$, that is the vertices are elements of $G$ and the (oriented) edges are ( $g, g x$ ) for every $x \in\left\{a, b, a^{-1}, b^{-1}\right\}$. The edge $(g, g x)$ in Cayley $(G)$ is usually labelled by $x$, so Cayley $(G)$ can be viewed as a labelled graph. Every path in Cayley $(G)$ is labelled by a word in $a$ and $b$. The length of a path $p$ in Cayley $(G)$ is denoted by $|p|$. The distance function in Cayley $(G)$ is denoted by dist; it coincides with the word metric on $G$.

Notation. For every word $w$ in the free group $F_{\{a, b\}}$ we denote by $g_{w}$ the element in $G$ represented by $w$.

As in $[26,41]$, we introduce the following types of words.
Definitions 7.16 (words of rank n). Every freely reduced product

$$
\begin{equation*}
w=w_{n}\left(e_{1}\right) w_{n}\left(e_{2}\right) \cdots w_{n}\left(e_{m}\right) \tag{17}
\end{equation*}
$$

where $e_{1}, \ldots, e_{m}$ are edges in $\Gamma_{n}$, is called a word of rank $n$. The words $w_{n}\left(e_{i}\right)$ will be called the blocks of $w$.

Every freely reduced product

$$
w_{n}(p)=w_{n}\left(e_{1}\right) w_{n}\left(e_{2}\right) \cdots w_{n}\left(e_{m}\right)
$$

where $p=e_{1} e_{2} \ldots e_{m}$ is a path in $\Gamma_{n}$, is called a net word of rank $n$.
Remark 7.17. The words $w_{n}(e)$ have length at least $\left[\zeta^{n} d_{n}\right] \geqslant\left[d_{n-1}\right] \geqslant d_{1} / \zeta^{n-1}-1 \geqslant n$ for $n$ large enough. This and the small cancellation assumptions from Proposition 7.13 imply that at most $2 \lambda_{n}$ of the length of the block $w_{n}(e)$ can cancel in the product (17) provided none of its neighbor factors is $w_{n}\left(e^{-1}\right)$. In particular, if a path $p$ in $\Gamma_{n}$ has no backtracking, at most $2 \lambda_{n}$ of the length of any factor $w_{n}(e)$ cancels in the word $w_{n}(p)$.

Notation. For every path $p$ in $\Gamma_{n}$ starting at $O_{n}$ let $\bar{p}$ be the path in Cayley $(G)$ labelled by $w_{n}(p)$ starting at 1 . We denote by $\mathfrak{R}_{n} \subset \operatorname{Cayley}(G)$ the union of all these paths $\bar{p}$. It is easy to see that $\mathfrak{R}_{n}$ consists of all prefixes of all net words $w_{n}(p)$, where $p$ is a path in $\Gamma_{n}$ starting at $O_{n}$.

Definition 7.18 (cells of rank n). By definition of the set of relations $R$, the boundary label of every cell in a van Kampen diagram $\Delta$ over $R$ is a net word. Therefore a cell in $\Delta$ is called a cell of rank $n$ if its boundary label is a net word of rank $n$.

Definition 7.19 (minimal diagrams). A van Kampen diagram over $R$ is called minimal if it contains the minimal number of cells among all van Kampen diagrams over $R$ with the same boundary label, and the sum of perimeters of the cells is minimal among all diagrams with the same number of cells and the same boundary label.

Notation. The boundary of any van Kampen diagram (cell) $\Delta$ is denoted by $\partial \Delta$.
Lemma 7.20. (1) Every minimal van Kampen diagram $\Delta$ over $R$ satisfies the small cancellation property $C^{\prime}(1 / 10)$ (that is, the length of any path contained in the boundaries of any two distinct cells in $\Delta$ cannot be bigger than $1 / 10$ of the length of the boundary of any of these cells).
(2) Every cell $\pi$ in a minimal van Kampen diagram $\Delta$ over $R$ satisfies $|\partial \pi| \leqslant 2|\partial \Delta|$.

Proof. (1) is Lemma 4.2 in [26].
(2) We prove the statement by induction on the number $n$ of cells in $\Delta$. If $n=1$ then the statement is obviously true. Suppose it is true for some $n$. We consider a minimal van Kampen diagram $\Delta$ with $n+1$ cells. By Greendlinger's lemma [40] and Part (1) there exists a cell $\pi$ and a common path $p$ of $\partial \pi$ and $\partial \Delta$ whose length is bigger than $\frac{7}{10}|\partial \pi|$. It follows that $|\partial \pi| \leqslant 2|\partial \Delta|$. Removing $p$ and the interior of $\pi$, we obtain a minimal diagram $\Delta^{\prime}$ with boundary length smaller than $|\partial \Delta|$ and with fewer cells than $\Delta$. It remains to apply the induction assumption to $\Delta^{\prime}$.

Notation. We shall denote the graphical equality of words by $\equiv$.
Lemma 7.21. Let $u \equiv u_{1} u_{2} u_{3}$ be a word of rank $n$ and $u^{\prime} \equiv u_{1}^{\prime} u_{2} u_{3}^{\prime}$ be a word of rank $m, n \geqslant m$. Suppose $\left|u_{2}\right|$ is at least $5 \lambda$ times the maximal length of a block in $u^{\prime}$. Then $m=n$. In addition, if $u=w_{n}(p)$ and
$u^{\prime}=w_{n}(q)$ are net words then the paths $p$ and $q$ in $\Gamma_{n}$ have a common edge e: $p=p_{1} e p_{2}, q=q_{1} e q_{2}$, and $u_{1}\left(\right.$ resp. $\left.u_{1}^{\prime}\right)$ is a prefix of $w_{n}\left(p_{1} e\right)\left(\right.$ resp. $\left.w_{n}\left(q_{1} e\right)\right), u_{3}\left(\right.$ resp. $\left.u_{3}^{\prime}\right)$ is a suffix of $w_{n}\left(e p_{2}\right)\left(r e s p . w_{n}\left(e q_{2}\right)\right)$.

Proof. Indeed, the conditions of the lemma imply that one of the blocks of $u$ that either contains $u_{2}$ or is contained in $u_{2}$ has in common with one of the blocks of $u^{\prime}$ at least $\lambda$ of its length. The small cancellation condition $C^{*}(\lambda)$ implies that the blocks coincide, so $m=n$. The rest of the statement follows immediately from the definition of net words and Remark 7.17.

Lemma 7.22. Let $u$ and $v$ be two words in $\{a, b\}$ that are equal in $G$. Suppose that $u$ is $a$ (net) word of rank $n$ and $v$ is a shortest word that is equal to $u$ in $G$. Then $v$ is also a (net) word of rank $n$. In addition, if $u$ is a net word, $u=w_{n}(p)$, then $v=w_{n}(q)$ for some simple path $q$ in $\Gamma_{n}$ having the same initial and terminal vertices as $p$.

Proof. Consider a van Kampen diagram $\Delta$ over $R$ with boundary $\partial \Delta=s t$ where $u$ labels $s, v^{-1}$ labels $t$.
By the Greendlinger lemma, property $C^{\prime}(1 / 10)$ implies that there exists a cell $\pi$ in $\Delta$ such that $\partial \pi$ and $\partial \Delta$ have a common sub-path $r$ of length $\frac{7}{10}|\partial \pi|$. Since $v$ is a shortest word that is equal to $u$ in $G$, no more than $\frac{1}{2}$ of $\partial \pi$ is a sub-path of $t$. Therefore $|r \cap s| \geqslant \frac{1}{5}|\partial \pi|$. Notice that the label of $\partial \pi$ is the reduced form of a product of at least two blocks. Therefore the label of $r \cap s$ contains at least $(1-4 \lambda) / 5$ of a block in $\partial \pi$. Lemma 7.21 implies that $\pi$ is a cell of rank $n$. After we remove the cell $\pi$ from $\Delta$ we obtain a diagram $\Delta^{\prime}$ corresponding to an equality $u^{\prime}=v$ of the same type as $u=v$, that is $u^{\prime}$ is a word of rank $n$ representing the same element in $G$ as $u$ and $v$, and if $u=w_{n}(p)$ then $u^{\prime}=w_{n}\left(p^{\prime}\right)$, where $p^{\prime}$ is a path in $\Gamma_{n}$ with $p_{-}^{\prime}=p_{-}, p_{+}^{\prime}=p_{+}$. Since $\Delta^{\prime}$ has fewer cells than $\Delta$, it remains to use induction on the number of cells in $\Delta$.

### 7.3. Tree-graded asymptotic cones

Recall that we consider any sequence of metric graphs $\Gamma_{n}, n \geqslant 1$, satisfying the properties listed before Definition 7.14, that the set of vertices of $\Gamma_{n}$ is denoted by $N_{n}$, and that we fix basepoints $O_{n}$ in $N_{n}$. For every $x \in N_{n}$ let $p_{x}$ be a path from $O_{n}$ to $x$ in $\Gamma_{n}$. We define

$$
\Phi_{n}: N_{n} \rightarrow \mathfrak{R}_{n}, \quad \Phi_{n}(x)=w_{n}\left(p_{x}\right) \quad \text { in } G
$$

(see notation before Definition 7.18).
The value $\Phi_{n}(x)$ does not depend on the choice of the path $p_{x}$, because $w_{n}(q)$ is equal to 1 in $G$ for every loop $q$ in $\Gamma_{n}$ by the definition of the presentation of $G$. Hence $\Phi_{n}$ is a map.

Remark 7.23. Notice that every point in $\mathfrak{R}_{n}$ is at distance at most $\zeta^{〔 n / 2]} d_{n}\left(1+\lambda_{n}\right)$ from $\Phi_{n}\left(N_{n}\right)$.
The sequence of maps ( $\Phi_{n}$ ) clearly defines a map

$$
\left(x_{n}\right)^{\omega} \mapsto\left(\Phi_{n}\left(x_{n}\right)\right)^{\omega}
$$

from $\Pi N_{n} / \omega$ to $\Pi \Re_{n} / \omega$.
Remark 7.24. Let $a=\Phi_{n}(x), x \in N_{n}$, and let $b \in G$ be such that $a$ and $b$ can be joined in Cayley $(G)$ by a path labelled by $w_{n}(q)$, where $q$ is a path in $\Gamma_{n}$ with $q_{-}=x$ and $q_{+}=y$. Then $b=\Phi_{n}(y) \in \Phi_{n}\left(N_{n}\right)$.

Lemma 7.25. Lete $=\left(e_{n}\right)^{\omega} \in \Pi N_{n} / \omega, e^{\prime}=\left(\Phi_{n}\left(e_{n}\right)\right)^{\omega}$.The map $\Phi_{\omega}: \lim ^{\omega}\left(N_{n} \text {, } \operatorname{dist}_{n}\right)_{e} \rightarrow \lim ^{\omega}\left(\Re_{n}, \text { dist } / d_{n}\right)_{e^{\prime}}$ such that

$$
\Phi_{\omega}\left(\lim ^{\omega}\left(x_{n}\right)\right)=\lim ^{\omega}\left(\Phi_{n}\left(x_{n}\right)\right)
$$

is a surjective isometry.
Proof. For every $x, y \in N_{n}$, let $p=e_{1} e_{2} \ldots e_{s}$ be a shortest path from $x$ to $y$ in $\Gamma_{n}$. Then $\Phi_{n}(x)$ and $\Phi_{n}(y)$ are joined in Cayley $(G)$ by a path labelled by $w_{n}(p)$. It follows that

$$
\operatorname{dist}\left(\Phi_{n}(x), \Phi_{n}(y)\right) \leqslant \sum_{i=1}^{s}\left|w_{n}\left(e_{i}\right)\right| \leqslant d_{n} \sum_{i=1}^{s}\left|e_{i}\right|=d_{n} \operatorname{dist}_{n}(x, y)
$$

By Lemma 7.22, for every $x, y \in N_{n}$ there exists a geodesic joining $\Phi_{n}(x)$ to $\Phi_{n}(y)$ labelled by a net word $w_{n}(q)$ of rank $n$. If $q=e_{1} e_{2} \ldots e_{t}$ then

$$
w_{n}(q)=w_{n}\left(e_{1}\right) \cdots w_{n}\left(e_{t}\right)
$$

Therefore

$$
\begin{aligned}
\operatorname{dist}\left(\Phi_{n}(x), \Phi_{n}(y)\right) & =\left|w_{n}(q)\right| \geqslant \sum_{i=1}^{t}\left(1-2 \lambda_{n}\right)\left|w_{n}\left(e_{i}\right)\right| \\
& \geqslant\left(1-2 \lambda_{n}\right) \sum_{i=1}^{t}\left(d_{n}\left|e_{i}\right|-1\right) \geqslant\left(1-2 \lambda_{n}\right)\left(d_{n} \operatorname{dist}_{n}(x, y)-t\right) \\
& \geqslant\left(1-2 \lambda_{n}\right)\left(d_{n} \operatorname{dist}_{n}(x, y)-E_{n}\right)
\end{aligned}
$$

Thus for every $x, y \in N_{n}$,

$$
\begin{equation*}
\left(1-2 \lambda_{n}\right)\left(d_{n} \operatorname{dist}_{n}(x, y)-E_{n}\right) \leqslant \operatorname{dist}\left(\Phi_{n}(x), \Phi_{n}(y)\right) \leqslant d_{n} \operatorname{dist}_{n}(x, y) \tag{18}
\end{equation*}
$$

According to (18), for every $\lim ^{\omega}\left(x_{n}\right), \lim ^{\omega}\left(y_{n}\right) \in \lim ^{\omega}\left(N_{n}, \operatorname{dist}_{n}\right)_{e}$ we have that

$$
\begin{equation*}
\lim _{\omega} \operatorname{dist}_{n}\left(x_{n}, y_{n}\right)-\lim _{\omega} \frac{E_{n}}{d_{n}} \leqslant \lim _{\omega} \frac{\operatorname{dist}\left(\Phi_{n}\left(x_{n}\right), \Phi_{n}\left(y_{n}\right)\right)}{d_{n}} \leqslant \lim _{\omega} \operatorname{dist}_{n}\left(x_{n}, y_{n}\right) \tag{19}
\end{equation*}
$$

Since $\left(d_{n}\right)_{n \in \mathbb{N}}$ is a fast increasing sequence we have that $\lim _{\omega}\left(E_{n} / d_{n}\right)=0$. This implies that $\Phi_{\omega}$ is well defined and that it is an isometry.

Remark 7.23 implies the surjectivity of the map $\Phi_{\omega}$.
Notation. We denote by $e$ the element $(1)^{\omega} \in G^{\omega}$.
Proposition 7.26. Let $\left(\Gamma_{n}\right)_{n \in \mathbb{N}}$ be a sequence of metric graphs satisfying the properties listed before Definition 7.14, let $\left(d_{n}\right)_{n \in \mathbb{N}}$ be a fast increasing sequence with respect to $\left(\Gamma_{n}\right)_{n \in \mathbb{N}}$ and let $G=\langle a, b \mid R\rangle$ be the group constructed as above. For every ultrafilter $\omega$ the asymptotic cone $\operatorname{Con}^{\omega}(G ; e, d)$ is treegraded with respect to the set of pieces:

$$
\begin{equation*}
\mathscr{P}=\left\{\lim ^{\omega}\left(g_{n} \Re_{n}\right) \mid\left(g_{n}\right)^{\omega} \in G^{\omega} \text { such that } \lim _{\omega} \frac{\operatorname{dist}\left(e, g_{n} \mathfrak{R}_{n}\right)}{d_{n}}<\infty\right\} \tag{20}
\end{equation*}
$$

in particular different elements $\left(g_{n}\right)^{\omega}$ correspond to different pieces from $\mathscr{P}$.


Fig. 6. Diagram $\Delta_{n}$.

Proof. Property $\left(T_{1}\right)$. Suppose that $\lim ^{\omega}\left(g_{n} \mathfrak{R}_{n}\right) \cap \lim ^{\omega}\left(g_{n}^{\prime} \mathfrak{R}_{n}\right)$ contains at least two distinct points, where $\left(g_{n}\right)^{\omega},\left(g_{n}^{\prime}\right)^{\omega} \in G^{\omega}$. We may suppose that $\left(g_{n}^{\prime}\right)^{\omega}=(1)^{\omega}$. Let

$$
\lim ^{\omega}\left(a_{n}\right), \lim ^{\omega}\left(b_{n}\right) \in \lim ^{\omega}\left(g_{n} \Re_{n}\right) \cap \lim ^{\omega}\left(\Re_{n}\right), \quad \lim ^{\omega}\left(a_{n}\right) \neq \lim ^{\omega}\left(b_{n}\right)
$$

The inclusion $\lim ^{\omega}\left(a_{n}\right), \lim ^{\omega}\left(b_{n}\right) \in \lim ^{\omega}\left(\Re_{n}\right)$ implies that

$$
\lim ^{\omega}\left(a_{n}\right)=\lim ^{\omega}\left(\Phi_{n}\left(x_{n}\right)\right), \quad \lim ^{\omega}\left(b_{n}\right)=\lim ^{\omega}\left(\Phi_{n}\left(y_{n}\right)\right),
$$

where $x_{n}, y_{n} \in N_{n}, \lim ^{\omega}\left(x_{n}\right) \neq \lim ^{\omega}\left(y_{n}\right)$. The inclusion $\lim ^{\omega}\left(a_{n}\right), \lim ^{\omega}\left(b_{n}\right) \in \lim ^{\omega}\left(g_{n} \Re_{n}\right)$ implies that $\lim ^{\omega}\left(a_{n}\right)=\lim ^{\omega}\left(g_{n} \Phi_{n}\left(x_{n}^{\prime}\right)\right), \lim ^{\omega}\left(b_{n}\right)=\lim ^{\omega}\left(g_{n} \Phi_{n}\left(y_{n}^{\prime}\right)\right)$, where $x_{n}^{\prime}, y_{n}^{\prime} \in N_{n}, \lim ^{\omega}\left(x_{n}^{\prime}\right) \neq \lim ^{\omega}\left(y_{n}^{\prime}\right)$.

By Lemma 7.22, for every $n \geqslant 1$, there exists a geodesic $\mathfrak{p}_{1}^{(n)}$ in Cayley $(G)$ joining $\Phi_{n}\left(x_{n}\right)$ with $\Phi_{n}\left(y_{n}\right)$ labelled by a net word $w_{n}\left(p_{1}^{(n)}\right)$, where $p_{1}^{(n)}$ is a simple path from $x_{n}$ to $y_{n}$ in $\Gamma_{n}$. It follows that $\mathfrak{p}_{1}^{(n)} \subset \mathfrak{\Re}_{n}$. Similarly, there exists a geodesic $\mathfrak{p}_{2}^{(n)}$ joining $g_{n} \Phi_{n}\left(x_{n}^{\prime}\right)$ to $g_{n} \Phi_{n}\left(y_{n}^{\prime}\right)$ contained in $g_{n} \mathfrak{R}_{n}$. The label of this geodesic is a net word $w_{n}\left(p_{2}^{(n)}\right)$. Let $\mathfrak{q}_{n}$ be a geodesic joining $\Phi_{n}\left(x_{n}\right)$ to $g_{n} \Phi_{n}\left(x_{n}^{\prime}\right)$ and $\mathfrak{q}_{n}^{\prime}$ a geodesic joining $\Phi_{n}\left(y_{n}\right)$ to $g_{n} \Phi_{n}\left(y_{n}^{\prime}\right)$ in Cayley $(G)$. Both $\mathfrak{q}_{n}$ and $\mathfrak{q}_{n}^{\prime}$ have length $o\left(d_{n}\right)$. The geodesics $\mathfrak{p}_{1}^{(n)}$ and $\mathfrak{p}_{2}^{(n)}$ on the other hand have length $O\left(d_{n}\right)$. We consider the geodesic quadrilateral composed of $\mathfrak{p}_{1}^{(n)}, \mathfrak{q}_{n}, \mathfrak{p}_{2}^{(n)}, \mathfrak{q}_{n}^{\prime}$ and a minimal van Kampen diagram $\Delta_{n}$ whose boundary label coincides with the label of this quadrangle. Then $\partial \Delta_{n}$ is a product of four segments which we shall denote $s_{n}, t_{n}, s_{n}^{\prime}, t_{n}^{\prime}$ (the labels of these paths coincide with the labels of the paths $\mathfrak{p}_{1}^{(n)}, \mathfrak{q}_{n}, \mathfrak{p}_{2}^{(n)}, \mathfrak{q}_{n}^{\prime}$, respectively).

There exists a unique (covering) map $\gamma$ from $\Delta$ to Cayley $(G)$ that maps the initial vertex of $s_{n}$ to 1 and preserves the labels of the edges. The map $\gamma$ maps $s_{n}$ to $\mathfrak{p}_{1}^{(n)} \subseteq \mathfrak{R}_{n}$ and $s_{n}^{\prime}$ to $\mathfrak{p}_{2}^{(n)} \subseteq g \mathfrak{R}_{n}$.

Let $\Delta_{n}^{1}$ be the maximal (connected) sub-diagram of $\Delta_{n}$ that contains $s_{n}$ and whose $\gamma$-image is contained in $\mathfrak{R}_{n}$. Likewise, let $\Delta_{n}^{2}$ be the maximal sub-diagram of $\Delta_{n}$ that contains $s_{n}^{\prime}$ and whose $\gamma$-image is contained in $g \mathfrak{R}_{n}$. The complement $\Delta_{n} \backslash\left(\Delta_{n}^{1} \cup \Delta_{n}^{2}\right)$ has several connected components.

Suppose that the complement contains cells, and let $\Theta_{n}$ be one of the non-trivial components of the complement. The boundary of $\Theta_{n}$ is contained in $\partial \Delta_{n}^{1} \cup t_{n} \cup \partial \Delta_{n}^{2} \cup t_{n}^{\prime}$. By Greendlinger's lemma, there exists a cell $\pi$ in $\Theta_{n}$ such that $\partial \pi \cap \partial \Theta_{n}$ contains a path $u_{n}$ of length at least $\frac{7}{10}|\partial \pi|$. Suppose that $u_{n}$ has more than $15 \lambda$ of its length in common with $\partial \Delta_{n}^{1}$. Then the labels of $\partial \pi$ and $\partial \Delta_{n}^{1}$ contain a common sub-word of length at least $5 \lambda$ of the length of a block participating in the label of $\partial \pi$. By Lemma 7.21, $\pi$ has rank $n$ and the $\gamma$-image of $\Delta_{n}^{1} \cup \pi$ is in $\mathfrak{R}_{n}$, a contradiction with the maximality of $\Delta_{n}^{1}$. Hence $\left|u_{n} \cap \partial \Delta_{n}^{1}\right| \leqslant 15 \lambda\left|u_{n}\right|$.A similar argument applies to $\Delta_{n}^{2}$ (Fig. 6).

Therefore $\left|u_{n} \cap\left(\partial \Delta_{n}^{1} \cup \partial \Delta_{n}^{2}\right)\right| \leqslant 30 \lambda\left|u_{n}\right|$. It follows that $u_{n}$ has more than $\frac{6}{10}|\partial \pi|$ in common with $t_{n} \cup t_{n}^{\prime}$. Since $\gamma\left(t_{n}\right)$ and $\gamma\left(t_{n}^{\prime}\right)$ are both geodesics, $u_{n}$ must intersect both of them. We have $\left|u_{n}\right| \leqslant 30 \lambda\left|u_{n}\right|+\left|t_{n}\right|+\left|t_{n}^{\prime}\right|$; hence $\left|u_{n}\right|=o\left(d_{n}\right)$. Therefore

$$
\operatorname{dist}\left(\Phi_{n}\left(x_{n}\right), \Phi_{n}\left(y_{n}\right)\right) \leqslant\left|u_{n}\right|+\left|t_{n}\right|+\left|t_{n}^{\prime}\right|=o\left(d_{n}\right)
$$

a contradiction.
Property $\left(T_{2}\right)$. According to Proposition 3.29, it suffices to study sequences of geodesic $k$-gons $P_{n}$ in Cayley $(G)$ with all lengths of edges of order $d_{n}, k$ fixed and $\lim ^{\omega}\left(P_{n}\right)$ a simple geodesic triangle. We need to show that $\lim ^{\omega}\left(P_{n}\right)$ is contained in one piece.

We fix such a sequence $\left(P_{n}\right)_{n \in \mathbb{N}}$ of $k$-gons in Cayley $(G)$. Let $\mathscr{V}_{n}$ be the set of vertices of $P_{n}$. We consider minimal van Kampen diagrams $\Delta^{(n)}$ and covering maps $\gamma_{n}: \Delta^{(n)} \rightarrow$ Cayley $(G)$ such that $\gamma_{n}\left(\partial \Delta^{(n)}\right)$ is $P_{n}$. We can consider the boundary of $\Delta^{(n)}$ also as a $k$-gon whose vertices and sides correspond to the vertices and sides of $P_{n}$.
(a) Properties of the diagrams $\Delta^{(n)}$. By Lemma 7.20, each cell from $\Delta^{(n)}$ has boundary length $\leqslant O\left(d_{n}\right)$. On the other hand, the cells of rank $k \geqslant n+1$ have boundary of length at least [ $\zeta^{n+1} d_{n+1}$ ]. Property (2) of the fast increasing sequence $\left(d_{n}\right)$ implies that for $n$ large enough all cells from the diagram $\Delta^{(n)}$ are of rank $k \leqslant n$.

Suppose that $\omega$-almost surely there exists a cell $\pi$ of rank $m \leqslant n-1$ in $\Delta^{(n)}$, the boundary of which intersects two edges $[x, y],[z, t]$ without a common endpoint. Recall that the diameter of a cell of rank $m$ is at most $10 m d_{m} \leqslant 10(n-1) d_{n-1}$. Then there exist two points in $\gamma_{n}[x, y]$ and in $\gamma_{n}[z, t]$, respectively, which are at distance at most $10(n-1) d_{n-1}$ of each other. In the $\omega$-limit of $P_{n}$ we obtain that two edges without a common endpoint intersect in a point. This contradicts the fact that $\lim ^{\omega}\left(P_{n}\right)$ is a simple loop. We conclude that $\omega$-almost surely all cells whose boundaries intersect two edges without a common endpoint are of rank $n$.

Suppose that the boundary of one of the cells $\pi$ of rank $m$ in $\Delta^{(n)}$ is not a simple path. Then by applying the Greendlinger lemma to any hole formed by $\partial \pi$, we get a cell $\pi^{\prime}$ whose boundary has a common subpath $u$ with $\partial \pi$ such that $|u| \geqslant \frac{7}{10}\left|\partial \pi^{\prime}\right|$. Then there exists a block $w$ in $\partial \pi^{\prime}$ such that $|w \cap \partial \pi| \geqslant \frac{7}{20}|w|$. We apply Lemma 7.21 to $\partial \pi$ and $\partial \pi^{\prime}$ and we obtain that the ranks of $\pi$ and $\pi^{\prime}$ coincide and that the boundary label of the union $\pi \cup \pi^{\prime}$ is a net word of rank $m$ corresponding to a loop in $\Gamma_{m}$. Hence the union of the cells $\pi$ and $\pi^{\prime}$ can be replaced by one cell corresponding to a relation from $R$, a contradiction with the minimality of $\Delta^{(n)}$. Hence the boundary of each cell in $\Delta^{(n)}$ is a simple path.

Suppose that the boundaries of two cells $\pi_{1}, \pi_{2}$, in $\Delta^{(n)}$, of rank $m_{1}$ and $m_{2}$, respectively, intersect in several connected components. We apply the Greendlinger lemma to a hole formed by $\partial \pi_{1} \cup \partial \pi_{2}$ and we get a cell $\pi^{\prime}$ whose boundary has a common sub-path, of length at least $\frac{7}{10}\left|\partial \pi^{\prime}\right|$, with $\partial \pi_{1} \cup \partial \pi_{2}$. Therefore $\partial \pi^{\prime}$ has a common sub-path with one $\partial \pi_{i}, i \in\{1,2\}$, of length at least $\frac{7}{20}\left|\partial \pi^{\prime}\right|$. Lemma 7.21 implies that the ranks of $\pi_{i}$ and $\pi^{\prime}$ coincide and that the boundary label of $\pi_{i} \cup \pi^{\prime}$ is a net word of rank $m_{i}$ corresponding to a loop in $\Gamma_{m_{i}}$. Hence $\pi_{i} \cup \pi^{\prime}$ can be replaced by one cell, a contradiction with the minimality of $\Delta^{(n)}$. Weconclude that the intersection of the boundaries of two cells, if non-empty, is connected.

Suppose that the boundary of a cell $\pi$ in $\Delta^{(n)}$ of rank $m$ intersects one side $[x, y]$ of $\partial \Delta^{(n)}$ in several connected components. We consider a hole formed by $\partial \tau \cup[x, y]$ and we apply the Greendlinger lemma to it. We obtain a cell $\pi^{\prime}$ whose boundary has a common sub-path $u$ with $\partial \pi \cup[x, y]$, such that $|u| \geqslant \frac{7}{10}\left|\partial \pi^{\prime}\right|$.

Since $\gamma_{n}[x, y]$ is a geodesic, $u$ cannot have more than $\frac{5}{7}|u|$ in common with $[x, y]$. Hence $|u \cap \partial \pi| \geqslant \frac{1}{5}\left|\partial \pi^{\prime}\right|$, which implies that there exists a block $w$ in $\partial \pi^{\prime}$ such that $|w \cap \partial \pi| \geqslant \frac{1}{10}|w|$. We apply Lemma 7.21 to $\pi$ and $\pi^{\prime}$ and as previously we obtain a contradiction of the minimality of $\Delta^{(n)}$. Consequently, the intersection of the boundary of a cell in $\Delta^{(n)}$ with a side of $\partial \Delta^{(n)}$, if non-empty, is connected.
(b) Existence of a cell $\pi_{n}$ of rank $n$ in $\Delta^{(n)}$ such that $\operatorname{dist}\left(P_{n}, \gamma_{n}\left(\partial \pi_{n}\right)\right)=o\left(d_{n}\right)$. Take any vertex $v=v_{n}$ of the $k$-gon $\partial \Delta^{(n)}$. Let $[x, v],[v, y]$ be the two consecutive sides of the $k$-gon $\partial \Delta^{(n)}$. Let $x_{n}^{\prime} \in[x, v]$ be such that $\gamma_{n}\left(x_{n}^{\prime}\right)$ is the last point on $\left[\gamma_{n}(v), \gamma_{n}(x)\right]$ (counting from $\left.\gamma_{n}(v)\right)$ for which there exists a point $z$ on $\left[\gamma_{n}(v), \gamma_{n}(y)\right]$ with $\operatorname{dist}\left(\gamma_{n}\left(x_{n}^{\prime}\right), z\right)$ not exceeding $\zeta^{n / 2} d_{n}$. Since $\zeta^{n / 2} d_{n}=o\left(d_{n}\right), \lim ^{\omega}\left(x_{n}^{\prime}\right)=\lim ^{\omega}\left(\gamma_{n} v\right)$ (recall that the triangle $\lim ^{\omega}\left(P_{n}\right)$ is simple). Therefore $\operatorname{dist}\left(x_{n}^{\prime}, \gamma_{n} v\right)=o\left(d_{n}\right)$.

Similarly let $y_{n}^{\prime} \in[y, v]$ be such that $\gamma_{n}\left(y_{n}^{\prime}\right)$ is the last point on $\left[\gamma_{n}(v), \gamma_{n}(y)\right]$ for which there exists a point $z$ on $\left[\gamma_{n}(v), \gamma_{n}(x)\right]$ with $\operatorname{dist}\left(\gamma_{n}\left(y_{n}^{\prime}\right), z\right) \leqslant \zeta^{n / 2} d_{n}$. Then $\operatorname{dist}\left(y_{n}^{\prime}, \gamma_{n} v\right)=o\left(d_{n}\right)$.

Consider the set $\Pi_{v}$ of cells $\pi$ in $\Delta^{(n)}$ whose boundaries have common points with both $[x, v]$ and $[v, y]$. The boundary of $\pi$ naturally splits into four parts: a sub-arc of $[x, v]$, a sub-arc of $[v, y]$, and two $\operatorname{arcs} c(\pi), c^{\prime}(\pi)$ which connect points on $[x, v]$ with points on $[v, y]$ and such that $c(\pi)$ and $c^{\prime}(\pi)$ do not have any common points with $[x, v] \cup[v, y]$ other than their respective endpoints. We assume that $c^{\prime}(\pi)$ is closer to $v$ than $c(\pi)$.

The cells from $\Pi_{v}$ are ordered in a natural way by their distance from $v$. Take the cell $\pi \in \Pi_{v}$ which is the farthest from $v$ among all cells in $\Pi_{v}$ satisfying

$$
\operatorname{dist}\left(\gamma_{n}\left(c(\pi)_{-}\right), \gamma_{n}\left(c(\pi)_{+}\right)\right) \leqslant\left[\zeta^{n / 2} d_{n}\right] .
$$

Let us cut off the corner of $\Delta^{(n)}$ bounded by the triangle $\Theta_{v}=c(\pi) \cup\left[c(\pi)_{-}, v\right] \cup\left[v, c(\pi)_{+}\right]$. Notice that by the definition of $x_{n}^{\prime}, y_{n}^{\prime}$, we have $c(\pi)_{-} \in\left[x_{n}^{\prime}, v\right], c(\pi)_{+} \in\left[v, y_{n}^{\prime}\right]$. Therefore the lengths of the sides of $\Theta_{v}$ are $o\left(d_{n}\right)$. Also notice that $\omega$-almost surely $\Theta_{v}$ contains all cells of rank $\leqslant n-1$ from $\Pi_{v}$. This follows from the fact that the diameter of $\mathfrak{\Re}_{k}, k \leqslant n-1$, does not exceed $10(n-1) d_{n-1}$; hence for $n$ large enough it does not exceed $\left[\zeta^{n / 2} d_{n}\right]$ by property (2) of the definition of a fast increasing sequence.

Let us do this operation for every vertex $v$ of the $k$-gon $\Delta^{(n)}$. As a result, we get a minimal diagram $\Delta_{1}^{(n)}$ such that $\gamma_{n}\left(\Delta_{1}^{(n)}\right)$ is a $2 k$-gon $P_{n}^{\prime}$ with $k$ sides which are sub-arcs of the sides of $P_{n}$ (we shall call them long sides) and $k$ sides which are curves of type $c(\pi)$ whose lengths are $o\left(d_{n}\right)$ (short sides). Some of the short sides may have length 0 . The $\omega$ - $\operatorname{limit} \lim ^{\omega}\left(P_{n}^{\prime}\right)$ coincides with $\lim ^{\omega}\left(P_{n}\right)$. We shall consider $\partial \Delta_{1}^{(n)}$ as a $2 k$-gon with long and short sides corresponding to the sides of $P_{n}^{\prime}$.

Notice that by construction $\Delta_{1}^{(n)}$ does not have cells of rank $\leqslant n-1$ which have common points with two long sides of the $2 k$-gon $\partial \Delta_{1}^{(n)}$ (Fig. 7).

Let $\pi_{1}, \pi_{2}, \ldots, \pi_{m}$ be all Greendlinger $\frac{6}{10}$-cells in $\Delta_{1}^{(n)}$, i.e. for every $i=1, \ldots, m$, the intersection $\partial \pi_{i} \cap \partial \Delta_{1}^{(n)}$ contains a sub-path $u_{i}$ of length at least $\frac{6}{10}\left|\partial \pi_{i}\right|$. Let $r_{i}$ be the rank of the cell $\pi_{i}, i=1, \ldots, m$. The path $u_{i}$ cannot have more than $\frac{5}{6}$ of its length in common with a long side of the $2 k$-gon $\partial \Delta_{1}^{(n)}$ because the $\gamma_{n}$-images of these sides are geodesics. By Lemma 7.21, $u_{i}$ cannot have a sub-path of length bigger than $5 \lambda$ times the length of a block of rank $r_{i}$ in common with a short side of $\partial \Delta_{1}^{(n)}$. Since short sides and long sides in $\partial \Delta_{1}^{(n)}$ alternate $\omega$-almost surely, $u_{i}$ must have points in common with two long sides of $\partial \Delta_{1}^{(n)}$. Therefore the number $m$ is at most $k$ and the rank $r_{i}$ is $n$ for every $i=1, \ldots, m$ ( $\omega$-almost surely).

Let us cut off all cells $\pi_{1}, \ldots, \pi_{m}$ from the diagram $\Delta_{1}^{(n)}$. The resulting diagram $\Delta_{2}^{(n)}$ has a form of a polygon where each side is either a part of a long side of $\Delta_{1}^{(n)}$ (we call it again long) or a part of $\partial \pi_{i}$ (we


Fig. 7. Diagram $\Delta^{(n)}$.
call it special) or a part of a short side of $\Delta_{1}^{(n)}$ (we call it short). Notice that by the definition of $\Delta_{1}^{(n)}$, the length of any special side of $\Delta_{2}^{(n)}$ cannot be smaller than [ $\left.\zeta^{n / 2} d_{n}\right] \omega$-almost surely.

Suppose that the diagram $\Delta_{2}^{(n)}$ contains cells $\omega$-almost surely. Consider a Greendlinger $\frac{7}{10}$-cell $\pi$ of rank $m$ in $\Delta_{2}^{(n)}$ and the corresponding path $u \subset \partial \pi \cap \partial \Delta_{2}^{(n)}$. This path cannot have more than $\frac{5}{7}$ of its length in common with a long side of $\Delta_{2}^{(n)}$, more than $5 \lambda$ times the length of a block of $\partial \pi$ in common with a special or short side. Therefore $u$ cannot contain a whole special side of $\Delta_{2}^{(n)}$. Hence $u$ has a sub-path $u^{\prime}$ of length at least $\left(\frac{7}{10}-10 \lambda\right)|\partial \pi|$ that intersects only long and short sides of $\Delta_{2}^{(n)}$. Hence $\pi$ is a Greendlinger $\frac{6}{10}$-cell in $\Delta_{1}^{(n)}$. This contradicts the fact that all such cells were removed when we constructed $\Delta_{2}^{(n)}$.

Thus $\Delta_{2}^{(n)}$ contains no cells $\omega$-almost surely. In particular, all cells in $\Delta_{1}^{(n)}$ are of rank $n$ and all of them are Greendlinger $\frac{6}{10}$-cells. For each cell $\pi_{i}, i=1, \ldots, m$, consider the decomposition $\partial \pi_{i}=u_{i} u_{i}^{\prime}$. Any two arcs $u_{i}^{\prime}, u_{j}^{\prime}(i \neq j)$ have at most one maximal sub-arc in common. The length of this sub-arc is at most $5 \lambda$ times the length of a maximal block of rank $n$ (by Lemma 7.21 and the minimality of $\Delta^{(n)}$ ). Hence ( $\omega$-almost surely) the length of any arc $u_{i}^{\prime}$ is at most $5 k \lambda\left[\zeta^{n / 2} d_{n}\right]$. Therefore $\lim _{\omega}\left(\left|u_{i}^{\prime}\right| / d_{n}\right)=0$. Since $\lim ^{\omega}\left(P_{n}^{\prime}\right)$ is a simple triangle, we can conclude that $\omega$-almost surely for all but one $i \in\{1, \ldots, m\}$ the length of $\partial \pi_{i}$ is $o\left(d_{n}\right)$. Indeed otherwise we would have two points on $P_{n}^{\prime}$ at distance $O\left(d_{n}\right)$ along the boundary of $P_{n}^{\prime}$ but at distance $o\left(d_{n}\right)$ in Cayley $(G)$. The $\omega$-limits of these two points would give us a self-intersection point of $\lim ^{\omega}\left(P_{n}^{\prime}\right)$.

Let us call this exceptional $i$ by $i_{n}$. Then $\lim ^{\omega}\left(P_{n}^{\prime}\right)$ coincides with $\lim ^{\omega}\left(\gamma_{n}\left(\partial \pi_{i_{n}}\right)\right)$. Since $\gamma_{n}\left(\pi_{i_{n}}\right)$ is contained in $g_{n} \Re_{n}$ for some $g_{n}, \lim ^{\omega}\left(P_{n}^{\prime}\right)$ is contained in one piece $\lim ^{\omega}\left(g_{n} \Re_{n}\right)$.

Proposition 7.27 (description of the set of pieces). Consider the following two collections of metric spaces:

$$
\begin{equation*}
\left\{\lim ^{\omega}\left(g_{n} \Re_{n}\right)_{e} \mid\left(g_{n}\right)^{\omega} \in G^{\omega}, \lim _{\omega} \frac{\operatorname{dist}\left(e, g_{n} \Re_{n}\right)}{d_{n}}<\infty\right\} \tag{21}
\end{equation*}
$$

and

$$
\begin{equation*}
\left\{\lim ^{\omega}\left(N_{n}, \operatorname{dist}_{n}\right)_{x} \mid x \in \Pi N_{n} / \omega\right\} . \tag{22}
\end{equation*}
$$

We consider each $\lim ^{\omega}\left(N_{n}, \text { dist }_{n}\right)_{x}$ as a space with basepoint $\lim ^{\omega}\left(x_{n}\right)$ and each $\lim ^{\omega}\left(g_{n} \mathfrak{R}_{n}\right)_{e}$ as a space with basepoint $\lim ^{\omega}\left(y_{n}\right)$, where $\lim ^{\omega}\left(y_{n}\right)$ is the projection of $\lim ^{\omega}(e)$ onto $\lim ^{\omega}\left(g_{n} \Re_{n}\right)$.

Then every space in one of these collections is isometric, as a metric space with basepoint, to a space in the other collection. Moreover every space in the second collection is isometric to continuously many spaces in the first collection.

Proof. Let $t_{n}=g_{n}^{-1} y_{n}, n \geqslant 1$. Let $y=\left(y_{n}\right)^{\omega}$ and $t=\left(t_{n}\right)^{\omega}$. Then $\lim ^{\omega}\left(g_{n} \Re_{n}\right)_{e}$ is isometric to $\lim ^{\omega}\left(g_{n} \Re_{n}\right)_{y}$ which, in turn, is isometric to $\lim ^{\omega}\left(\mathfrak{R}_{n}\right)_{t}$. Notice that $t_{n} \in \mathfrak{R}_{n}, \omega$-almost surely. Remark 7.23 implies that there exists a $u_{n} \in \Phi_{n}\left(N_{n}\right)$ such that $\lim _{\omega}\left(\operatorname{dist}\left(u_{n}, t_{n}\right) / d_{n}\right)=0$. Let $u=\left(u_{n}\right)^{\omega}$. For every $n \geqslant 1$, let $x_{n} \in N_{n}$ be such that $u_{n}=\Phi_{n}\left(x_{n}\right), x=\left(x_{n}\right)^{\omega}$. Then by Lemma $7.25, \lim ^{\omega}\left(g_{n} \Re_{n}\right)_{e}$ is isometric to $\lim ^{\omega}\left(N_{n}\right)_{x}$.

The fact that every limit set $\lim ^{\omega}\left(N_{n}, \text { dist }_{n}\right)_{x}$ is isometric to a set $\lim ^{\omega}\left(\Re_{n} \text {, dist } / d_{n}\right)_{g}$ follows from Lemma 7.25. We write $g$ as $\lim ^{\omega}\left(g_{n}^{-1}\right)$ for some $g_{n}^{-1} \in \Phi_{n}\left(N_{n}\right)$. The set $\lim ^{\omega}\left(g_{n} \Re_{n} \text {, dist } / d_{n}\right)_{e}$ contains $\lim ^{\omega}(1)$ and with respect to this basepoint it is isometric to $\lim ^{\omega}\left(N_{n}, \operatorname{dist}_{n}\right)_{x}$.

We consider an arbitrary element $\left(\gamma_{n}\right)^{\omega}$ in $G_{e}^{\omega}$ such that $\lim _{\omega}\left(\operatorname{dist}\left(1, \gamma_{n}\right) / d_{n}\right)=0$. The set $\lim ^{\omega}\left(\gamma_{n} g_{n} \Re_{n}\right)_{e}$ is distinct from the set $\lim ^{\omega}\left(g_{n} \Re_{n}\right)_{e}$, as the argument in Proposition 7.26 shows. On the other hand, the metric space $\lim ^{\omega}\left(\gamma_{n} g_{n} \Re_{n}\right)_{e}$ with basepoint $\lim ^{\omega}\left(\gamma_{n}\right)=\lim ^{\omega}(1)$ is isometric to the metric space $\lim ^{\omega}\left(g_{n} \Re_{n}\right)_{e}$ with basepoint $\lim ^{\omega}(1)$, and hence to $\lim ^{\omega}\left(N_{n}, \operatorname{dist}_{n}\right)_{x}$ with basepoint $\lim ^{\omega}\left(x_{n}\right)$. We complete the proof by noting that there are continuously many elements $\left(\gamma_{n}\right)^{\omega}$ with $\lim _{\omega}\left(\operatorname{dist}\left(1, \gamma_{n}\right) / d_{n}\right)=0$.

### 7.4. Free products appearing as fundamental groups of asymptotic cones

The following lemma is obvious.
Lemma 7.28. The collection of sets $\left\{2^{k} \mathbb{N}+2^{k-1} \mid k \in \mathbb{N}\right\}$ is a partition of $\mathbb{N}$.
Notation. We denote the set $2^{k} \mathbb{N}+2^{k-1}$ by $\mathbb{N}_{k}$, for every $k \in \mathbb{N}$. We denote by $k(n)$ the element $2^{k} n+2^{k-1}$ of $\mathbb{N}_{k}$.

Let $\left(M_{k}, \operatorname{dist}_{k}\right)_{k \in \mathbb{N}}$ be a sequence of proper geodesic locally uniformly contractible spaces, let $O_{k}$ be a point in $M_{k}$ and let $\zeta$ be a real number in $(0,1)$. Fix $k \in \mathbb{N}$. We apply Remark 7.4 to the sequence of sets $\left(B_{n}^{(k)}\right)_{n \in \mathbb{N} \cup\{0\}}$, where $B_{0}^{(k)}=\left\{O_{k}\right\}$ and $B_{n}^{(k)}=\overline{B\left(O_{k}, n\right)}, n \in \mathbb{N}$, and to the sequence of numbers $\left(\zeta^{n}\right)_{n \in \mathbb{N}}$. We obtain an increasing sequence

$$
\begin{equation*}
\left\{O_{k}\right\} \subset N_{1}^{(k)} \subset N_{2}^{(k)} \subset \cdots \subset N_{n}^{(k)} \subset \cdots, \tag{23}
\end{equation*}
$$

such that $N_{n}^{(k)}$ is a $\zeta^{n}$-snet in $\left(B_{n}^{(k)}\right.$, dist $\left.{ }_{k}\right)$. We consider the sequence of graphs $\Gamma_{\zeta^{[n / 2]}}\left(N_{n}^{(k)}\right)$ endowed with the length metric $\operatorname{dist}_{n}^{(k)}$. We denote $\Gamma_{\zeta^{[n / 2]}}\left(N_{n}^{(k)}\right)$ by $\Gamma_{n}^{(k)}$.

Remark 7.29. Note that the diameter of $\left(N_{n}^{(k)}, \operatorname{dist}_{k}\right)$ is at most $2 n$, so by (11) the diameter of $\left(\Gamma_{n}^{(k)}, \operatorname{dist}_{n}^{(k)}\right)$ is at most $10 n$, for $n$ large enough. Hence the graphs $\Gamma_{n}^{(k)}$ satisfy the conditions listed before Definition 7.14.

Now consider the sequence $\left(\Gamma_{n}, \operatorname{dist}_{n}, O_{n}\right)$ of finite metric graphs endowed with length metrics and with distinguished basepoints defined as follows: $\left(\Gamma_{n}, \operatorname{dist}_{n}, O_{n}\right) \equiv\left(\Gamma_{n}^{(k)}\right.$, $\left.\operatorname{dist}_{n}^{(k)}, O_{k}\right)$ when $n \in \mathbb{N}_{k}$. We consider a sequence $\left(d_{n}\right)$ of positive numbers which is fast increasing with respect to the sequence of graphs $\left(\Gamma_{n}\right)$. We construct a group $G=\langle a, b \mid R\rangle$ as in Section 7.2, associated to the sequences $\left(\Gamma_{n}\right)$ and $\left(d_{n}\right)$.

For every $k \in \mathbb{N}$ let $\mu_{k}$ be an ultrafilter with the property that $\mu_{k}\left(\mathbb{N}_{k}\right)=1$.
Proposition 7.30. The asymptotic cone $\operatorname{Con}^{\mu_{k}}(G ; e, d)$ is tree-graded with respect to a set of pieces $\mathscr{P}_{k}$ that are isometric to ultraballs of $M_{k}$ with center $O_{k}$. Ultraballs with different observation points correspond to different pieces from $\mathscr{P}_{k}$.

Proof. By Proposition 7.26, $\operatorname{Con}^{\mu_{k}}(G ; e, d)$ is tree-graded with respect to

$$
\begin{equation*}
\mathscr{P}_{k}=\left\{\lim ^{\mu_{k}}\left(g_{n} \Re_{n}\right) \mid\left(g_{n}\right)^{\mu_{k}} \in G^{\mu_{k}} \text { such that } \lim _{\mu_{k}} \frac{\operatorname{dist}\left(e, g_{n} \Re_{n}\right)}{d_{n}}<\infty\right\} . \tag{24}
\end{equation*}
$$

By Proposition 7.27, the collection of representatives up to isometry of the set of pieces (24) coincides with the collection of representatives up to isometry of the set of ultralimits $\lim ^{\mu_{k}}\left(N_{n}, \operatorname{dist}_{n}\right)_{x}$, $x \in \Pi N_{n} / \mu_{k}$. The hypothesis that $\mu_{k}\left(\mathbb{N}_{k}\right)=1$ and the definition of the sequence of graphs $\left(\Gamma_{n}\right)$ implies that $\lim ^{\mu_{k}}\left(N_{n}, \operatorname{dist}_{n}\right)_{x}=\lim ^{\mu_{k}}\left(N_{n}^{(k)}, \operatorname{dist}_{n}^{(k)}\right)_{x^{(k)}}$ for some $x^{(k)} \in \Pi N_{n}^{(k)} / \mu_{k}$. It remains to apply Lemma 7.5.

Corollary 7.31. Suppose that the space $M_{k}$ is compact and locally uniformly contractible. Then the asymptotic cone $\operatorname{Con}^{\mu_{k}}(G ; e, d)$ is tree-graded with respect to pieces isometric to $M_{k}$, and the fundamental group of this asymptotic cone is the free product of continuously many copies of $\pi_{1}\left(M_{k}\right)$.

Proof. It is a consequence of Propositions 7.30 and 2.22.
Corollary 7.32. There exists a 2-generated group $\Gamma$ such that for every finitely presented group $G$, the free product of continuously many copies of $G$ is the fundamental group of an asymptotic cone of $\Gamma$.

Theorem 7.33. For every countable group $C$, there exists a finitely generated group $G$ and an asymptotic cone $T$ of $G$ such that $\pi_{1}(T)$ is isomorphic to an uncountable free power of $C$. Moreover, $T$ is tree-graded and each piece in it is isometric either to a fixed proper metric space $Y_{C}$ with $\pi_{1}\left(Y_{C}\right)=C$ or to a simply connected ultraball of $Y_{C}$.

Proof. Let $C$ be a countable group. By Lemma 7.10, $C$ is the fundamental group of a geodesic, proper, and locally uniformly contractible space $Y_{C}$. Moreover, by Lemma 7.11, there exists a point $O$ in $Y_{C}$ such that every ultraball of $Y_{C}$ with center $O$ either is isometric to $Y_{C}$ or is simply connected. It is easy to see that the cardinality of the set of different ultraballs of $Y_{C}$ with center $O$, that are isometric to $Y_{C}$, is continuum. Consider the 2-generated group $G=G\left(Y_{C}\right)$ obtained by applying the above construction to $M_{k}=Y_{C}$ and $O_{k}=O, k \geqslant 1$. Then by Proposition 7.30 there exists an asymptotic cone of $G$ that is tree-graded with respect to a set of pieces $\mathscr{P}$ such that the collection of representatives up to isometry of the pieces in $\mathscr{P}$ coincides with the collection of representatives up to isometry of the set of ultraballs of $Y_{C}$ with center $O$. By Proposition 2.22, the fundamental group of that asymptotic cone is isomorphic to the free power of $C$ of cardinality continuum.

### 7.5. Groups with continuously many non-homeomorphic asymptotic cones

We use the construction in Section 7.2 to obtain a 2-generated recursively presented group which has continuously many non- $\pi_{1}$-equivalent (and thus non-homeomorphic) asymptotic cones. Let us enumerate the set of non-empty finite subsets of $\mathbb{N}$ starting with $\{1\}$ and $\{1,2\}$, then listing all subsets of $\{1,2,3\}$ containing 3 , all subsets of $\{1,2,3,4\}$ containing 4 , etc. Let $F_{k}, k \in \mathbb{N}$, be the $k$ th set in the sequence of subsets.

For every $n \geqslant 1$ let $\mathscr{T}^{n}$ be the $n$-dimensional torus $\mathbb{R}^{n} / \mathbb{Z}^{n}$ with its natural geodesic metric and a basepoint $O=(0,0, \ldots, 0)$.

For every $k \geqslant 1$ consider the bouquet of tori $\mathscr{B}_{k}=\bigvee_{n \in F_{k}}\left(\mathscr{T}^{n}, O\right)$. This is a compact locally uniformly contractible geodesic metric space with a metric dist $_{k}$ induced by the canonical metrics on the tori and with the basepoint $O_{k}=O$.

We repeat the construction of a group $G=\langle a, b \mid R\rangle$ in Section 7.4 for the sequence of proper geodesic spaces with basepoints $\left(\mathscr{B}_{k} \text {, } \text { dist }_{k}, O_{k}\right)_{k \in \mathbb{N}}$.

Since all $\mathscr{B}_{k}$ are bouquets of tori, we can choose the snets $N_{n}^{(k)}$ coming from the same regular tilings of the tori of different dimensions, and from their regular sub-divisions. There is a recursive way to enumerate the snets $N_{k(n)}^{(k)}$. For an appropriate choice of the set of words $\mathscr{W}$ in Proposition 7.13, we obtain a recursively presented group $G$. The group has the following property.

Proposition 7.34. The asymptotic cone $\operatorname{Con}^{\mu_{k}}(G ; e, d)$ is tree-graded with respect to a set of pieces $\widetilde{\mathscr{P}}_{k}$ such that every piece is isometric to one of the tori $\mathscr{T}^{n}, n \in F_{k}$.

Proof. Proposition 7.30 implies that the asymptotic cone $\operatorname{Con}^{\mu_{k}}(G ; e, d)$ is tree-graded with respect to a set of pieces $\mathscr{P}_{k}$ such that all pieces are isometric to $\mathscr{B}_{k}$. It remains to use Lemma 2.26.

Notation. We denote $\operatorname{Con}^{\mu_{k}}(G ; e, d)$ by $\mathscr{C}_{k}$ and $\lim ^{\mu_{k}}(e)$ by $e_{k}$.
Let $I$ be an arbitrary infinite subset of $\mathbb{N}, I=\left\{i_{1}, i_{2}, \ldots, i_{n}, \ldots\right\}$. We consider the increasing sequence of finite sets

$$
F_{k_{1}} \subset F_{k_{2}} \subset \cdots \subset F_{k_{n}} \subset \cdots
$$

defined by $F_{k_{n}}=\left\{i_{1}, i_{2}, \ldots, i_{n}\right\}$. Correspondingly we consider the sequence of asymptotic cones $\left(\mathscr{C}_{k_{n}}\right)_{n \in \mathbb{N}}$. We consider an ultrafilter $\omega$. The ultralimit $\lim ^{\omega}\left(\mathscr{C}_{k_{n}}\right)_{\left(e_{k_{n}}\right)_{n \in \mathbb{N}}}$ is also an asymptotic cone of $G$, according to Corollary 3.24 . We denote it by $\mathscr{C}_{\omega}(I)$.

Lemma 7.35. Let $\left(\mathscr{T}^{k_{i}}\right)$ be a sequence of tori $\mathscr{T}^{k_{i}}=\mathbb{R}^{k_{i}} / \mathbb{Z}^{k_{i}}$ with canonical flat metrics. Suppose that $\lim ^{\omega}\left(k_{i}\right)=\infty$ for some ultrafilter $\omega$. Let $\mathscr{T}=\lim ^{\omega}\left(\mathscr{T}^{k_{i}}\right)_{e}$ for some e. Then $\mathscr{T}$ contains isometric $\pi_{1}$-embedded copies of all tori $\mathscr{T}^{n}, n \geqslant 1$.

Proof. Since tori are homogeneous spaces, we can assume that $e$ is the sequence of points $(0,0, \ldots)$. For every $n \geqslant 1$ the torus $\mathscr{T}^{n}$ isometrically embeds into $\mathscr{T}^{k_{i}}$ for $\omega$-almost all $i$ by the map $\phi_{i}:\left(x_{1}, \ldots, x_{n}\right) \mapsto$ $\left(x_{1}, \ldots, x_{n}, 0,0, \ldots\right)$. Consequently $\mathscr{T}^{n}$ isometrically embeds into $\mathscr{T}$ by $\phi_{\omega}: \bar{x} \mapsto \lim ^{\omega}\left(\phi_{i}(\bar{x})\right)$.Let c be a non-0-homotopic loop in $\mathscr{T}^{n}$. Suppose that $\phi_{\omega}(\mathfrak{c})$ is 0 -homotopic in $\mathscr{T}$. Then there exists a continuous map $\psi: \mathbb{D}^{2} \rightarrow \mathscr{T}$ with $\psi\left(\partial \mathbb{D}^{2}\right)=\phi_{\omega}(\mathfrak{c})$. For every small positive $\varepsilon$, there exists a triangulation of $\mathbb{D}^{2}$ such
that if $e$ is an edge in the triangulation, the images by $\psi$ of the endpoints of $e$ are at distance at most $\varepsilon$. Let $\mathscr{V}_{\varepsilon}$ be the set of vertices of such a triangulation. The restricted map $\psi_{\varepsilon} \psi_{\mathscr{V}_{\varepsilon}}$ is an $\omega$-limit of maps $\psi_{i}: \mathscr{V}_{\varepsilon} \rightarrow \mathscr{T}^{k_{i}}$. For every $i$ and for every edge $e$ in the considered triangulation of $\mathbb{D}^{2}$ we join with a geodesic in $T^{k_{i}}$ the images by $\psi_{i}$ of the endpoints of $e$. The length of this geodesic is $\omega$-almost surely less than $2 \varepsilon$. To each triangle of the triangulation thus corresponds a geodesic triangle in $T^{k_{i}}$ of perimeter smaller than $6 \varepsilon, \omega$-almost surely. For $\varepsilon$ small enough all these geodesic triangles are 0 -homotopic in some $T^{k_{i}}$. But then c is 0 -homotopic in $T^{k_{i}}$, a contradiction.

Lemma 7.36. The asymptotic cone $\mathscr{C}_{\omega}(I)$ is tree-graded with respect to a set of pieces $\widetilde{\mathscr{P}}_{\omega}(I)$ such that:
(1) All pieces are either isometric to one of the tori $\mathscr{T}^{i}, i \in I$, or they have the property that for every $n \in \mathbb{N}$ they contain an isometric $\pi_{1}$-embedded copy of $\mathscr{T}^{n}$.
(2) The fundamental group of every piece is Abelian.

Proof. Proposition 7.34 implies that for every $n \in \mathbb{N}, \mathscr{C}_{k_{n}}$ is tree-graded with respect to a set of pieces $\widetilde{\mathscr{P}}_{k_{n}}$ such that every piece is isometric to one of the tori $\left\{\mathscr{T}^{i_{1}}, \mathscr{T}^{i_{2}}, \ldots, \mathscr{T}^{i_{n}}\right\}$. Theorem 3.30 implies that $\mathscr{C}_{\omega}(I)=\lim ^{\omega}\left(\mathscr{C}_{k_{n}}\right)_{\left(e_{k_{n}}\right)_{n \in \mathbb{N}}}$ is tree-graded with respect to the set of pieces

$$
\begin{equation*}
\widetilde{\mathscr{P}}_{\omega}(I)=\left\{\lim ^{\omega}\left(M_{n}\right) \mid M_{n} \in \widetilde{\mathscr{P}}_{k_{n}}, \operatorname{dist}\left(e_{k_{n}}, M_{n}\right) \text { bounded uniformly in } n\right\} . \tag{25}
\end{equation*}
$$

Let $\lim ^{\omega}\left(M_{n}\right)$ be one of these pieces. Since $M_{n} \in \widetilde{\mathscr{P}}_{k_{n}}$, it follows that $M_{n}$ is isometric to one of the tori $\left\{\mathscr{T}^{i_{1}}, \mathscr{T}^{i_{2}}, \ldots, \mathscr{T}^{i_{n}}\right\}$. Let $i\left(M_{n}\right)$ be the dimension of the torus $M_{n}$ and let dist ${ }_{n}$ be the geodesic metric on $M_{n}$.
(1) We have two possibilities.
I. $\lim ^{\omega}\left(i\left(M_{n}\right)\right)=\infty$. In this case we can imply Lemma 7.35 and conclude that $\lim ^{\omega}\left(M_{n}\right)$ contains isometric and $\pi_{1}$-injective copies of tori $\mathscr{T}^{N}$ for every $N$.
II. $\lim ^{\omega}\left(i\left(M_{n}\right)\right)<\infty$. It follows that there exists a finite $m$ such that $i\left(M_{n}\right) \in\left\{i_{1}, i_{2}, \ldots, i_{m}\right\} \omega$-almost surely. Remark 3.2 implies that there exists $j \in\{1,2, \ldots, m\}$ such that $i\left(M_{n}\right)=i_{j} \omega$-almost surely. Hence $\omega$-almost surely $M_{n}$ is isometric to $\mathscr{T}^{i j}$ and $\lim ^{\omega}\left(M_{n}\right)$ is isometric to $\mathscr{T}^{i j}$.
(2) Every torus $\mathscr{T}^{n}$ is a topological group, so it admits a continuous binary operation and a continuous unary operation satisfying the standard group axioms. It is not difficult to see that $\omega$-limits of tori also are topological groups. Now the statement follows from the fact that the fundamental group of every topological group is Abelian [32].

Theorem 7.37. The 2-generated recursively presented group $G$ has continuously many non $\pi_{1}$-equivalent (and in particular non-homeomorphic) asymptotic cones.

Proof. Indeed, by Lemma 7.36 and Proposition 2.22 the fundamental group of $\mathscr{C}_{\omega}(I)$ is a free product of $\mathbb{Z}^{i}, i \in I$, and infinite dimensional Abelian groups. By Kurosh's theorem [40], if $j \notin I$ then $\mathbb{Z}^{j}$ cannot be a free factor of that fundamental group. Hence the asymptotic cones $\mathscr{C}_{\omega}(I)$ for different subsets $I$ of $\mathbb{N}$ have different fundamental groups.

Remark 7.38. Each of the continuously many asymptotic cones from Theorem 7.37 is a restrictive asymptotic cone in the sense of Section 3.3. Indeed by Remark 3.25, each of the cones $\operatorname{Con}^{\mu_{k}}(G ; e, d)$ is isometric to a restrictive asymptotic cone $\operatorname{Con}^{v_{k}}(G ; e,(n))$. The map $\phi$ defined in Section 3.3 just before

Remark 3.25 is in this case injective. The images of the sets $\mathbb{N}_{k}$ under this map are pairwise disjoint and $v_{k}\left(\phi\left(\mathbb{N}_{k}\right)\right)=1$. It remains to use Proposition 3.26.

## 8. Asymptotically tree-graded groups are relatively hyperbolic

Let $G$ be a finitely generated group and let $\left\{H_{1}, \ldots, H_{m}\right\}$ be a collection of subgroups of $G$. Let $S$ be a finite generating set of $G$ closed with respect to taking inverses.

We denote by $\mathscr{H}$ the set $\bigsqcup_{i=1}^{m}\left(H_{i} \backslash\{e\}\right)$. We note that Cayley $(G, S)$ is a subgraph of Cayley $(G, S \cup \mathscr{H})$, with the same set of vertices but a smaller set of edges. We have that dist $S_{\mathscr{H}}(u, v) \leqslant \operatorname{dist}_{S}(u, v)$, for every two vertices $u, v$.

For every continuous path $\mathfrak{p}$ in a metric space $X$ we endow the image of $\mathfrak{p}$ with a pseudo-order $\leqslant_{\mathfrak{p}}$ (possibly not anti-symmetric, but transitive and reflexive relation) induced by the order on the interval of definition of $\mathfrak{p}$. For every two points $x, y$ we denote by $\mathfrak{p}[x, y]$ the sub-path of $\mathfrak{p}$ composed of points $z$ such that $x \leqslant_{\mathfrak{p}} z \leqslant_{\mathfrak{p}} y$.

Definition 8.1. Let $\mathfrak{p}$ be a path in Cayley $(G, S \cup \mathscr{H})$. An $\mathscr{H}$-component of $\mathfrak{p}$ is a maximal sub-path of $\mathfrak{p}$ contained in a left coset $g H_{i}, i \in\{1,2, \ldots, m\}, g \in G$ (i.e. this is a maximal sub-path with all labels of edges belonging to $H_{i}$ for some $i$ ).

The path $\mathfrak{p}$ is said to be without backtracking if it does not have two distinct $\mathscr{H}$-components in the same left coset $g H_{i}$.

There are two notions of relative hyperbolicity. The weak relative hyperbolicity has been introduced by Farb in [27]. We use a slightly different but equivalent definition. The proof of the equivalence can be found in [43].

Definition 8.2. The group $G$ is weakly hyperbolic relative to $\left\{H_{1}, \ldots, H_{m}\right\}$ if and only if the graph $\operatorname{Cayley}(G, S \cup \mathscr{H})$ is hyperbolic.

The strong relative hyperbolicity has several equivalent definitions provided by several authors. The definition that we consider here uses the following property.

Definition 8.3. The pair $\left(G,\left\{H_{1}, \ldots, H_{m}\right\}\right)$ satisfies the Bounded Coset Penetration (BCP) property if for every $\lambda \geqslant 1$ there exists $a=a(\lambda)$ such that the following holds. Let $\mathfrak{p}$ and $\mathfrak{q}$ be two $\lambda$-bi-Lipschitz paths without backtracking in $\operatorname{Cayley}(G, S \cup \mathscr{H})$ such that $\mathfrak{p}_{-}=\mathfrak{q}_{-}$and dist ${ }_{S}\left(\mathfrak{p}_{+}, \mathfrak{q}_{+}\right) \leqslant 1$.
(1) Suppose that $s$ is an $\mathscr{H}$-component of $\mathfrak{p}$ such that $\operatorname{dist}_{S}\left(s_{-}, s_{+}\right) \geqslant a$. Then $\mathfrak{q}$ has an $\mathscr{H}$-component contained in the same left coset as $s$.
(2) Suppose that $s$ and $t$ are two $\mathscr{H}$-components of $\mathfrak{p}$ and $\mathfrak{q}$, respectively, contained in the same left coset. Then $\operatorname{dist}_{S}\left(s_{-}, t_{-}\right) \leqslant a$ and dist $S_{S}\left(s_{+}, t_{+}\right) \leqslant a$.

Definition 8.4. The group $G$ is (strongly) hyperbolic relative to $\left\{H_{1}, \ldots, H_{m}\right\}$ if it is weakly hyperbolic relative to $\left\{H_{1}, \ldots, H_{m}\right\}$ and if ( $G,\left\{H_{1}, \ldots, H_{m}\right\}$ ) satisfies the BCP property.

We are going to prove the following theorem.
Theorem 8.5. A finitely generated group $G$ is asymptotically tree-graded with respect to subgroups $\left\{H_{1}, \ldots, H_{m}\right\}$ if and only if $G$ is (strongly) hyperbolic relative to $\left\{H_{1}, \ldots, H_{m}\right\}$ and each $H_{i}$ is finitely generated.

This section is devoted to the proof of the "only if" statement. Note that the fact that each $H_{i}$ is finitely generated has been proved before (Proposition 5.11).

The "if" statement is proved in the Appendix.

### 8.1. Weak relative hyperbolicity

The most difficult part of Theorem 8.5 is the following statement.
Theorem 8.6. If $G$ is asymptotically tree-graded with respect to $\left\{H_{1}, \ldots, H_{m}\right\}$ then $G$ is weakly hyperbolic relative to $\left\{H_{1}, \ldots, H_{m}\right\}$.

The main tool is a characterization of hyperbolicity due to Bowditch [7, Section 3]. For the sake of completeness we recall the results of Bowditch here.

### 8.1.1. A characterization of hyperbolicity

Let $\mathscr{G}$ be a connected graph, with vertex set $\mathscr{V}$ and distance function dist, such that every edge has length 1.

We assume that to every pair $u, v \in \mathscr{V}$ we have associated a subset $\Lambda_{u v}$ of $\mathscr{V}$. Assume that each $\Lambda_{u v}$ is endowed with a relation $\leqslant u v$ such that the following properties are satisfied.
$\left(l_{1}\right) \leqslant u v$ is reflexive and transitive;
$\left(l_{2}\right)$ for every $x, y \in \Lambda_{u v}$ either $x \leqslant{ }_{u v} y$ or $y \leqslant{ }_{u v} x$;
( $l_{3}$ ) for every $u, v \in \mathscr{V}$ we have $\Lambda_{u v}=\Lambda_{v u}$ and $\leqslant u v=\geqslant_{v u}$.
We note that the relations $\leqslant u v$ may not be anti-symmetric.
Notation. For $x, y \in \Lambda_{u v}$ with $x \leqslant u v y$, we write

$$
\Lambda_{u v}[x, y]=\Lambda_{u v}[y, x]=\left\{z \in \Lambda_{u v} \mid x \leqslant u v z \leqslant u v y\right\} .
$$

We also assume that we have a function $\phi: \mathscr{V} \times \mathscr{V} \times \mathscr{V} \rightarrow \mathscr{V}$ with the following properties.
( $c_{1}$ ) (symmetry) $\phi \circ \sigma=\phi$ for every 3-permutation $\sigma$;
(c2) $\phi(u, u, v)=u$ for all $u, v \in \mathscr{V}$;
(c3) $\phi(u, v, w) \in \Lambda_{u v} \cap \Lambda_{v w} \cap \Lambda_{u w}$.
Suppose moreover that there exists a constant $K>0$ such that the following conditions are satisfied.
(I) For every $u, v, w \in \mathscr{V}$, the Hausdorff distance between the sets $\Lambda_{u v}[u, \phi(u, v, w)]$ and $\Lambda_{u w}[u, \phi(u, v, w)]$ is at most $K$.
(II) If $p, q \in \mathscr{V}$ are such that $\operatorname{dist}(p, q) \leqslant 1$ then $\operatorname{diam} \Lambda_{u v}[\phi(u, v, p), \phi(u, v, q)]$ is at most $K$.
(III) If $w \in \Lambda_{u v}$ then $\operatorname{diam} \Lambda_{u v}[w, \phi(u, v, w)]$ is at most $K$.

We call $\left(\Lambda_{u v}, \leqslant u v\right)$ a line from $u$ to $v$. We call $\phi(u, v, w)$ the center of $u, v, w$.
Proposition 8.7 (Bowditch [7, Proposition 3.1]). If the graph $\mathscr{G}$ admits a system of lines and centers satisfying the conditions above then $\mathscr{G}$ is hyperbolic with the hyperbolicity constant depending only on $K$. Moreover, for every $u, v \in \mathscr{V}$, the line $\Lambda_{u v}$ is at uniformly bounded Hausdorff distance from any geodesic joining $u$ to $v$, where the previous bound depends only on $K$.

### 8.1.2. Generalizations of already proven results and new results

Lemma 8.8. Let $\mathfrak{q}:[0, t] \rightarrow X$ be an (L, C)-quasi-geodesic. Let $x$ be a point in its image and let $a, b$ be its endpoints. Then

$$
\begin{equation*}
\operatorname{dist}(a, b) \geqslant \frac{1}{L_{1}}[\operatorname{dist}(a, x)+\operatorname{dist}(x, b)]-C_{1}, \tag{26}
\end{equation*}
$$

where $L_{1}=L^{2}$ and $C_{1}=C\left(\frac{2}{L}+1\right)$.
Proof. Let $s \in[0, t]$ be such that $\mathrm{q}(s)=x$. We have that $\operatorname{dist}(a, b) \geqslant \frac{1}{L} t-C$. On the other hand $s \geqslant \frac{1}{L} \operatorname{dist}(a, x)-C$ and $t-s \geqslant \frac{1}{L} \operatorname{dist}(x, b)-C$ imply that $t \geqslant \frac{1}{L}[\operatorname{dist}(a, x)+\operatorname{dist}(x, b)]-2 C$.

Let ( $X$, dist) be a metric space asymptotically tree-graded with respect to a collection of subsets $\mathscr{A}$. Given $L \geqslant 1$ and $C \geqslant 0$ we denote by $M(L, C)$ the constant given by $\left(\alpha_{2}^{\prime}\right)$ for $\theta=\frac{1}{3}$.

Definition 8.9 (parameterized saturations). Given $\mathfrak{q}$ an ( $L, C$ )-quasi-geodesic and $\mu \geqslant 0$, we define the $\mu$-saturation $\mathrm{Sat}^{\mu}(\mathfrak{q})$ as the union of $\mathfrak{q}$ and all $A \in \mathscr{A}$ with $\mathscr{N}_{\mu}(A) \cap \mathfrak{q} \neq \emptyset$.

Notice that if a metric space $X$ is asymptotically tree-graded with respect to a collection $\mathscr{A}=\left\{A_{i} \mid i \in I\right\}$ then $X$ is also asymptotically tree-graded with respect to $\mathscr{N}_{\mu}(\mathscr{A})=\left\{\mathcal{N}_{\mu}\left(A_{i}\right) \mid i \in I\right\}$ for every number $\mu>0$. This immediately follows from the definition of asymptotically tree-graded spaces. One can also easily see that properties $\left(\alpha_{1}\right),\left(\alpha_{2}\right),\left(\alpha_{3}\right)$ are preserved. Hence the following two lemmas follow from Lemmas 4.21, 4.26 and 4.28.

Lemma 8.10 (uniform quasi-convexity of parameterized saturations). For every $L \geqslant 1, C \geqslant 0$ and $\mu \geqslant$ $M(L, C)$, and for every $\lambda \geqslant 1, \kappa \geqslant 0$, there exists $\tau=\tau(L, C, \mu, \lambda, \kappa)$ such that for every $R \geqslant 1$, for every (L,C)-quasi-geodesic $\mathfrak{q}$, the saturation $\mathrm{Sat}^{\mu}(\mathfrak{q})$ has the property that every $(\lambda, \kappa)$-quasi-geodesic cjoining two points in its $R$-tubular neighborhood is entirely contained in its $\tau R$-tubular neighborhood.

Lemma 8.11 (parameterized saturations of polygonal lines). The statements in Lemmas 4.26 and 4.28 remain true if we replace the saturations by $\mu$-saturations, for every $\mu>0$.

Lemma 8.12. Let $\mathfrak{q}=\mathfrak{q}_{1} \cup \mathfrak{q}_{2} \cup \cdots \cup \mathfrak{q}_{n}$ be such that
(1) $\mathfrak{q}_{i}$ is an (L,C)-almost-geodesic in $X$ for $i=1,2, \ldots, n$;
(2) $\mathfrak{q}_{i} \cap \mathfrak{q}_{i+1}=\left\{x_{i}\right\}$ is an endpoint of $\mathfrak{q}_{i}$ and of $\mathfrak{q}_{i+1}$ for $i=1, \ldots, n-1$;
(3) $x_{i-1}$ and $x_{i}$ are the two endpoints of $\mathfrak{q}_{i}$ for $i=2, \ldots, n-1$;
(4) each $\mathfrak{q}_{i}$ satisfies one of the following two properties:
(i) the endpoints of $\mathfrak{q}_{i}$ are in a set $A_{i} \in \mathscr{A}$ or
(ii) $\mathfrak{q}_{i}$ has length at most $\ell$, where $\ell$ is a fixed constant;
(5) $A_{i} \neq A_{j}$ if $i \neq j$.

Then there exists $L_{n} \geqslant L, C_{n} \geqslant C$ depending on $n, \ell$ and $(L, C)$, such that $\mathfrak{q}$ is an $\left(L_{n}, C_{n}\right)$-almostgeodesic.

Proof. Clearly $\mathfrak{q}$ is an L-Lipschitz map. We prove by induction on $n$ that $\operatorname{dist}(\mathfrak{q}(t), \mathfrak{q}(s)) \geqslant$ $\left(1 / L_{n}\right)|t-s|-C_{n}$ for some $L_{n} \geqslant L$ and $C_{n} \geqslant C$.

The statement is true for $n=1$. Assume it is true for some $n$. Let $\mathfrak{q}=\mathfrak{q}_{1} \cup \mathfrak{q}_{2} \cup \ldots \cup \mathfrak{q}_{n} \cup \mathfrak{q}_{n+1}$ be as in the statement of the lemma. Let $\mathfrak{q}^{\prime}=\mathfrak{q}_{1} \cup \mathfrak{q}_{2} \cup \cdots \cup \mathfrak{q}_{n}$ which, by the induction hypothesis, is an ( $L_{n}, C_{n}$ )-almost-geodesic.

Suppose that $\mathfrak{q}_{n+1}$ satisfies (4)(ii). Then $\mathfrak{q}$ is an $\left(L_{n}, 2\left(\ell+C_{n}\right)\right)$-almost-geodesic.
Suppose that $\mathfrak{q}_{n+1}$ satisfies (4)(i). Let $A=A_{n+1}$. We take $M_{n}=M\left(L_{n}, C_{n}\right)$. Let $y$ be the farthest point from $x_{n}$ in the intersection $\overline{\mathcal{N}}_{M_{n}}(A) \cap \mathfrak{q}^{\prime}$. Consider $\mathfrak{q}_{y}$ a sub-almost-geodesic of $\mathfrak{q}^{\prime}$ of endpoints $y$ and $x_{n}$. By Lemma 4.15, $\mathfrak{q}_{y}$ is contained in the $\tau_{n} M_{n}$-tubular neighborhood of $A$. On the other hand, $\mathfrak{q}_{y}=\mathfrak{q}_{i}^{\prime} \cup \mathfrak{q}_{i+1} \cup \cdots \cup \mathfrak{q}_{n}$, where $\mathfrak{q}_{i}^{\prime}$ is a sub-almost-geodesic of $\mathfrak{q}_{i}$. Again Lemma 4.15 implies that every $\mathfrak{q}_{j}$ satisfying (4)(i) is contained in $\mathscr{N}_{\tau}\left(A_{i}\right)$ for some uniform constant $\tau$. Therefore, every such $\mathfrak{q}_{j}$ composing $\mathfrak{q}_{y}$ has endpoints at distance at most the diameter of $\mathscr{N}_{\tau}\left(A_{i}\right) \cap \mathcal{N}_{\tau_{n} M_{n}}(A)$, hence at most $D_{n}$, for some $D_{n}=D_{n}\left(\tau_{n} M_{n}\right)$. It follows that the distance $\operatorname{dist}\left(y, x_{n}\right)$ is at most $n\left(\ell+D_{n}\right)$. Lemma 4.19 implies that if the endpoints of $\mathfrak{q}_{n+1}$ are at distance at least $D^{\prime}=D^{\prime}\left(L_{n}, C_{n}, D_{n}\right)$, then $\mathfrak{q}$ is an ( $L_{n}+1,2 D^{\prime}$ )-almost-geodesic.

If the endpoints of $\mathfrak{q}_{n+1}$ are at distance at most $D^{\prime}$ then the length of $\mathfrak{q}_{n+1}$ is at most $L D^{\prime}+C$ and $\mathfrak{q}$ is an $\left(L_{n}, 2\left(L D^{\prime}+C+C_{n}\right)\right.$ )-almost-geodesic.

Lemma 8.13. For every $L \geqslant 1, C \geqslant 0, M \geqslant M(L, C)$ and $\delta>0$ there exists $D_{0}>0$ such that the following holds. Let $A \in \mathscr{A}$ and let $\mathfrak{q}_{i}:\left[0, \ell_{i}\right] \rightarrow X, i=1,2$, be two $(L, C)$-quasi-geodesics with one common endpoint $b$ and the other two respective endpoints $a_{i} \in \mathcal{N}_{M}(A)$, such that the diameter of $\mathfrak{q}_{i} \cap \overline{\mathcal{N}}_{M}(A)$ does not exceed $\delta$ for $i=1,2$. Then one of two situations occurs:
(a) either $\operatorname{dist}\left(a_{1}, a_{2}\right) \leqslant D_{0}$ or
(b) $b \in \mathscr{N}_{M}(A)$ and $\ell_{i} \leqslant L \delta+C$.

Proof. Let dist $\left(a_{1}, a_{2}\right)=D$. We show that if $D$ is large enough then we are in situation (b). Remark 4.14 implies that we may suppose that $\mathfrak{q}_{i}$ are $(L+C, C)$-almost geodesics.

According to Lemma 4.19, there exists $D^{\prime}$ such that if $D \geqslant D^{\prime}$ then $\mathfrak{q}_{1} \sqcup\left[a_{1}, a_{2}\right]$ is an $\left(L+C+1,2 D^{\prime}\right)$ -quasi-geodesic. Suppose that $D \geqslant D^{\prime}$.

Suppose that $b$ is not contained in $\mathscr{N}_{M}(A)$. Let $t \in\left[0, \ell_{2}\right]$ be such that $\mathfrak{q}_{2}(t) \in \bar{N}_{M}(A)$ and $\left.\mathfrak{q}_{2}\right|_{[0, t]}$ does not intersect $\mathcal{N}_{M}(A)$. The sub-arc $\left.\mathfrak{q}_{2}\right|_{\left[t, \ell_{2}\right]}$ has endpoints at distance at most $\delta$; hence it has length at most $L \delta+C$. It follows that $\left.\mathfrak{q}_{1} \sqcup\left[a_{1}, a_{2}\right] \sqcup \mathfrak{q}_{2}\right|_{\left[t, \ell_{2}\right]}$ is an $\left(L+C+1, C_{1}\right)$-quasi-geodesic, where $C_{1}=C_{1}\left(D^{\prime}, \delta\right)$. Lemma 4.25 implies that $\left.\mathfrak{q}_{1} \sqcup\left[a_{1}, a_{2}\right] \sqcup \mathfrak{q}_{2}\right|_{\left[t, \ell_{2}\right]}$ is contained in the $\tau$-tubular neighborhood of $\operatorname{Sat}\left(\left.\mathfrak{q}_{2}\right|_{[0, t]}\right)$,


Fig. 8. Corollary 8.14 and Lemma 8.15.
where $\tau=\tau\left(L, C, D^{\prime}, \delta\right)$. This implies that $\mathscr{N}_{M}(A) \cap \mathscr{N}_{\tau}\left(\operatorname{Sat}\left(\left.\mathfrak{q}_{2}\right|_{[0, t]}\right)\right)$ has diameter at least $D$. By Lemma 4.22, for $D$ large enough we must have that $A \subset \operatorname{Sat}\left(\left.\mathfrak{q}_{2}\right|_{[0, t]}\right)$. This contradicts the choice of $t$.

It follows that $b$ is contained in $\mathscr{N}_{M}(A)$, which implies that $\ell_{i} \leqslant L \operatorname{dist}\left(a_{i}, b\right)+C \leqslant L \delta+C$.
Corollary 8.14. For every $L \geqslant 1, C \geqslant 0, M \geqslant M(L, C)$ and $\delta>0$ there exists $D_{1}>0$ such that the following holds. Let $A \in \mathscr{A}$ and let $\mathfrak{q}_{i}:\left[0, \ell_{i}\right] \rightarrow X, i=1,2$, be two $(L, C)$-quasi-geodesics with one common endpoint $b$ and the other two respective endpoints $a_{i} \in \mathscr{N}_{M}(A)$, such that the diameter of $\mathfrak{q}_{i} \cap \overline{\mathcal{N}}_{M}(A)$ does not exceed $\delta$. Then $\operatorname{dist}\left(a_{1}, a_{2}\right) \leqslant D_{1}$ (Fig. 8).

Lemma 8.15. For every $L \geqslant 1, C \geqslant 0$ and $M \geqslant M(L, C)$ there exists $\mathfrak{D}=\mathfrak{D}(L, C, M)>0$ such that the following holds. Let $A \in \mathscr{A}$ and let $\mathfrak{q}:[0, \ell] \rightarrow X$ be an (L,C)-almost-geodesic with endpoints $x$ and $y \in \mathscr{N}_{M}(A)$. There exists a sub-arc $\mathfrak{q}^{\prime}$ of $\mathfrak{q}$ with one endpoint $x$ and the second endpoint in $\mathscr{N}_{M}(A)$ such that the diameter of $\mathfrak{q}^{\prime} \cap \overline{\mathscr{N}}_{M}(A)$ is at most $\mathfrak{D}$.

Proof. If $x \in \mathscr{N}_{M}(A)$ then we take $\mathfrak{q}^{\prime}=\{x\}$. Suppose that $x \notin \mathscr{N}_{M}(A)$. Let $t=\inf \left\{t^{\prime} \in[0, \ell] \mid\right.$ $\left.t^{\prime} \in \mathfrak{q}^{-1}\left(\mathscr{N}_{M}(A)\right)\right\}$. Then $\mathfrak{q}(t) \in \bar{N}_{M}(A)$. Let $s_{i} \in[0, t]$ be such that $\mathfrak{q}\left(s_{i}\right) \in \bar{N}_{M}(A), i=1,2$. If $\left|s_{1}-s_{2}\right| \geqslant 3 L(M+1)$ then property $\left(\alpha_{2}^{\prime}\right)$ implies that $\mathfrak{q}\left(\left[s_{1}, s_{2}\right]\right) \cap \mathcal{N}_{M}(A) \neq \emptyset$. This contradicts the choice of $t$. Therefore $\left|s_{1}-s_{2}\right| \leqslant 3 L(M+1)$. We deduce that $\mathfrak{q}([0, t]) \cap \overline{\mathscr{N}}_{M}(A)$ has diameter at most $3 L^{2}(M+1)$.

The definition of $t$ implies that there exists $t_{1}>t$ with $t_{1}-t \leqslant \frac{1}{L}$ and $\mathfrak{q}\left(t_{1}\right) \in \mathcal{N}_{M}(A)$. We take $\mathfrak{q}^{\prime}=\left.\mathfrak{q}\right|_{\left[0, t_{1}\right]}$. The diameter of $\mathfrak{q}^{\prime} \cap \overline{\mathcal{N}}_{M}(A)$ is at most $\mathfrak{b}=3 L^{2}(M+1)+1$.

### 8.1.3. Hyperbolicity of Cayley( $G, S \cup \mathscr{H}$ )

Let $G$ be a finitely generated group that is asymptotically tree-graded with respect to the finite collection of subgroups $\left\{H_{1}, \ldots, H_{m}\right\}$. This means that Cayley $(G, S)$ is asymptotically tree-graded with respect to the collection of subsets $\mathscr{A}=\left\{g H_{i} \mid g \in G, i=1,2, \ldots, m\right\}$. We prove that Cayley $(G, S \cup \mathscr{H})$ is hyperbolic, using Proposition 8.7. The following result is central in the argument.

Proposition 8.16. Let $L \geqslant 1, C \geqslant 0$, let $\mu \geqslant M(L, C)$ and let $\mathfrak{q}_{1}, \mathfrak{q}_{2}, \mathfrak{q}_{3}$ be three ( $L, C$ )-almost-geodesics composing a triangle in Cayley $(G, S)$. We consider the set

$$
\mathscr{C}_{\kappa}^{\mu}\left(\mathfrak{q}_{1}, \mathfrak{q}_{2}, \mathfrak{q}_{3}\right)=\mathscr{N}_{\kappa}\left(\operatorname{Sat}^{\mu}\left(\mathfrak{q}_{1}\right)\right) \cap \mathscr{N}_{\kappa}\left(\operatorname{Sat}^{\mu}\left(\mathfrak{q}_{2}\right)\right) \cap \mathscr{N}_{\kappa}\left(\operatorname{Sat}^{\mu}\left(\mathfrak{q}_{3}\right)\right) .
$$

(1) There exists $\kappa_{0}=\kappa_{0}(L, C, \mu)$ such that for every $\kappa \geqslant \kappa_{0}$ the set $\mathscr{C}_{\kappa}^{\mu}\left(\mathfrak{q}_{1}, \mathfrak{q}_{2}, \mathfrak{q}_{3}\right)$ intersects each of the almost-geodesics $\mathfrak{q}_{1}, \mathfrak{q}_{2}, \mathfrak{q}_{3}$. In particular it is non-empty.
(2) For every $\kappa \geqslant \kappa_{0}$ there exists $D_{\kappa}$ such that the set $\mathscr{C}_{\kappa}^{\mu}\left(\mathfrak{q}_{1}, \mathfrak{q}_{2}, \mathfrak{q}_{3}\right)$ has diameter at most $D_{\kappa}$ in Cayley $(G, S \cup \mathscr{H})$.

Proof of (1). Let $\{i, j, k\}=\{1,2,3\}$. According to Lemma 8.11, the result in Lemma 4.25 is true if we replace $\operatorname{Sat}(\mathfrak{q})$ by $\operatorname{Sat}^{\mu}\left(\mathfrak{q}_{i}\right) \cup \operatorname{Sat}^{\mu}\left(\mathfrak{q}_{j}\right)$. In particular there exists $\tau=\tau(L, C, \mu)$ such that $\mathfrak{q}_{k} \subset$ $\mathscr{N}_{\tau}\left(\mathrm{Sat}^{\mu}\left(\mathfrak{q}_{i}\right)\right) \cup \mathscr{N}_{\tau}\left(\mathrm{Sat}^{\mu}\left(\mathfrak{q}_{j}\right)\right)$. The traces on $\mathfrak{q}_{k}$ of the two sets $\mathscr{N}_{\tau}\left(\operatorname{Sat}^{\mu}\left(\mathfrak{q}_{i}\right)\right)$ and $\mathscr{N}_{\tau}\left(\operatorname{Sat}^{\mu}\left(\mathfrak{q}_{j}\right)\right)$ compose a cover of two open sets, none of them empty. Since $\mathfrak{q}_{k}$ is an almost geodesic, it is connected; hence $\mathfrak{q}_{k} \cap \mathscr{N}_{\tau}\left(\operatorname{Sat}{ }^{\mu}\left(\mathfrak{q}_{i}\right)\right)$ and $\mathfrak{q}_{k} \cap \mathscr{N}_{\tau}\left(\operatorname{Sat}^{\mu}\left(\mathfrak{q}_{j}\right)\right)$ intersect. The intersection is in $\mathscr{C}_{k}^{\mu}\left(\mathfrak{q}_{1}, \mathfrak{q}_{2}, \mathfrak{q}_{3}\right)$ for every $\kappa \geqslant \tau$.

We need several intermediate results before proving (2). In the sequel we work with the data given in the statement of Proposition 8.16, without mentioning it anymore.

Lemma 8.17. There exist positive constants $\alpha, \beta$ depending only on $L, C, \mu$ and $\kappa$ such that every point $x \in \mathscr{C}_{\kappa}^{\mu}\left(\mathfrak{q}_{1}, \mathfrak{q}_{2}, \mathfrak{q}_{3}\right)$ is in one of two situations:
(i) the ball $B(x, \alpha)$ intersects each of the three almost-geodesics $\mathfrak{q}_{1}, \mathfrak{q}_{2}, \mathfrak{q}_{3}$;
(ii) $x \in \mathscr{N}_{\kappa}(A)$ and $\mathscr{N}_{\beta}(A)$ intersects each of the three almost-geodesics $\mathfrak{q}_{1}, \mathfrak{q}_{2}, \mathfrak{q}_{3}$.

Proof. Let $x$ be an arbitrary point in $\mathscr{C}_{\kappa}^{\mu}\left(\mathfrak{q}_{1}, \mathfrak{q}_{2}, \mathfrak{q}_{3}\right)$. The inclusion $x \in \mathcal{N}_{\kappa}\left(\operatorname{Sat}^{\mu}\left(\mathfrak{q}_{i}\right)\right), i \in\{1,2,3\}$, implies that there are two possibilities:

```
(I}\mp@subsup{I}{i}{})x\in\mp@subsup{\mathscr{N}}{\kappa}{}(\mp@subsup{\mathfrak{q}}{i}{})\mathrm{ or
(II i) }x\in\mp@subsup{\mathscr{N}}{\kappa}{}(A)\mathrm{ , where }A\in\mathscr{A},\mp@subsup{\mathscr{N}}{\mu}{}(A)\cap\mp@subsup{\mathfrak{q}}{i}{}\not=\emptyset
```

If we are in case (I) for the three edges then this means that (i) is satisfied with $\beta=\kappa$.
Suppose that only one edge is in case (II). Suppose it is $\mathfrak{q}_{3}$. Then $x \in \mathcal{N}_{\kappa}\left(\mathfrak{q}_{1}\right) \cap \mathscr{N}_{\kappa}\left(\mathfrak{q}_{2}\right)$ and there exists $A \in \mathscr{A}$ with $\mathscr{N}_{\mu}(A) \cap \mathfrak{q}_{3} \neq \emptyset$ such that $x \in \mathscr{N}_{\kappa}(A)$. It follows that $\mathscr{N}_{\beta}(A)$ intersects the three edges for $\beta=\max (\mu, 2 \kappa)$, so (ii) is satisfied.

Suppose that two edges are in case (II), for instance $\mathfrak{q}_{2}$ and $\mathfrak{q}_{3}$. Consequently, $x \in \mathscr{N}_{\kappa}\left(\mathfrak{q}_{1}\right)$ and $x \in$ $\mathscr{N}_{\kappa}\left(A_{2}\right) \cap \mathscr{N}_{\kappa}\left(A_{3}\right)$, with $\mathscr{N}_{\mu}\left(A_{i}\right) \cap \mathfrak{q}_{i} \neq \emptyset$, where $i=2$, 3. If $A_{2}=A_{3}=A$ then $\mathcal{N}_{\beta}(A)$ intersects the three edges for $\beta=\max (\mu, 2 \kappa)$, so (ii) is satisfied. If $A_{2} \neq A_{3}$ then, according to Lemma 8.11 (more precisely to Lemma 4.28 which also holds for $\mu$-saturations); we have that $x \in \mathcal{N} \mathcal{N}_{\chi}\left(\mathfrak{q}_{2} \cup \mathfrak{q}_{3}\right)$, where $\chi=\chi(\mu, \kappa)$. Suppose that $x \in \mathscr{N}_{\chi}\left(\mathfrak{q}_{2}\right)$. Then $\mathscr{N}_{\beta}\left(A_{3}\right)$ intersects the three edges for $\beta=\max (\mu, 2 \kappa, \kappa+\chi)$, so (ii) is satisfied.

Suppose that the three edges are in case (II). It follows that $x \in \mathscr{N}_{\kappa}\left(A_{1}\right) \cap \mathscr{N}_{\kappa}\left(A_{2}\right) \cap \mathscr{N}_{\kappa}\left(A_{3}\right)$, with $\mathscr{N}_{\mu}\left(A_{i}\right) \cap \mathfrak{q}_{i} \neq \emptyset$, where $i=1,2,3$.

If the cardinality of the set $\left\{A_{1}, A_{2}, A_{3}\right\}$ is 1 then we are in situation (ii) with $\beta=\mu$. Suppose the cardinality of the set is 2 . Suppose that $A_{1}=A_{2} \neq A_{3}$. Lemma 4.28 for $\mu$-saturations implies that $x \in \mathscr{N}_{x}\left(\mathfrak{q}_{2} \cup \mathfrak{q}_{3}\right) \cap \mathscr{N}_{x}\left(\mathfrak{q}_{1} \cup \mathfrak{q}_{3}\right)$. If $x \in \mathscr{N}_{x}\left(\mathfrak{q}_{3}\right)$ then $A=A_{1}=A_{2}$ has the property that $\mathscr{N}_{\beta}(A)$ intersects the three edges for $\beta=\max (\mu, \kappa+\chi)$, and we are in case (ii). Otherwise $x \in \mathscr{N}_{\chi}\left(\mathfrak{q}_{1}\right) \cap \mathcal{N}_{\chi}\left(\mathfrak{q}_{2}\right)$; hence $\mathscr{N}_{\beta}\left(A_{3}\right)$ intersects the three edges for $\beta=\max (\mu, \kappa+\chi)$.

Assume that the cardinality of the set $\left\{A_{1}, A_{2}, A_{3}\right\}$ is 3 . Then $x \in \mathcal{N}_{x}\left(\mathfrak{q}_{1} \cup \mathfrak{q}_{2}\right) \cap \mathcal{N}_{x}\left(\mathfrak{q}_{2} \cup \mathfrak{q}_{3}\right) \cap$ $\mathcal{N}_{x}\left(\mathfrak{q}_{1} \cup \mathfrak{q}_{3}\right)$. It follows that $x$ is in the $x$-tubular neighborhood of at least two edges. Suppose these edges are $\mathfrak{q}_{1}$ and $\mathfrak{q}_{2}$. Then $\mathscr{N}_{\beta}\left(A_{3}\right)$ intersects the three edges for $\beta=\max (\mu, \kappa+\chi)$.

Lemma 8.18. For every $r>0$ there exists $\varrho=\varrho(r, L, C)$ such that the following holds. Let $A \neq B$ be such that $A, B \in \mathscr{A}$, and both $\mathscr{N}_{r}(A)$ and $\mathscr{N}_{r}(B)$ intersect each of the three almost-geodesic edges of the triangle. Then there exists $x$ such that $B(x, \varrho)$ intersects each of the edges of the triangle.

Proof. Let $y \in \mathscr{N}_{r}(A)$ and $z \in \mathscr{N}_{r}(B)$. Lemma 8.15 implies that up to taking a sub-segment of $[y, z]$, we may suppose that the diameters of $[y, z] \cap \mathscr{N}_{r}(A)$ and of $[y, z] \cap \mathscr{N}_{r}(B)$ are at most $\mathfrak{D}$, where $\mathfrak{D}=\mathfrak{D}(r)$. We apply Lemma 4.28 for $r$-saturations and for each $\mathfrak{q}_{i}, i \in\{1,2,3\}$, and we obtain that both $B(y, \varrho)$ and $B(z, \varrho)$ intersect $\mathfrak{q}_{i}$, where $\varrho=\varrho(r)$.

Lemma 8.19. There exists $R=R(L, C)$ such that for every triangle with ( $L, C$ )-almost-geodesic edges, one of the following two situations holds.
(C) There exists $x$ such that $B(x, R)$ intersects each of the three edges of the triangle.
(P) There exists a unique $A \in \mathscr{A}$ such that $\mathscr{N}_{R}(A)$ intersects each of the three edges of the triangle.

Proof. Let $\mathfrak{q}_{1}, \mathfrak{q}_{2}, \mathfrak{q}_{3}$ be the three edges. For $\mu=M(L, C)$ and $\kappa_{0}=\kappa_{0}(L, C)$ we have that $\mathscr{C}_{\kappa}^{\mu}\left(\mathfrak{q}_{1}, \mathfrak{q}_{2}, \mathfrak{q}_{3}\right)$ is non-empty. It remains to apply Lemmas 8.17 and 8.18.

Notation. We denote the vertices of the triangle by $O_{1}, O_{2}, O_{3}$, such that $\mathfrak{q}_{i}$ is opposite to $O_{i}$.

Lemma 8.20. For every $r>0$ there exists $D=D(r, L, C)$ such that the following holds. Let $x$ be such that $B(x, r)$ intersects the three edges of the triangle.
(a) If $y$ is such that $B(y, r)$ intersects the three edges then dist $_{S \cup \mathscr{H}}(x, y) \leqslant D$.
(b) If $A \in \mathscr{A}$ is such that $\mathscr{N}_{r}(A)$ intersects the three edges then dist $S \cup \mathscr{H}(x, A) \leqslant D$.

Proof. Let $x_{i}$ be nearest points to $x$ in $\mathfrak{q}_{i}, i=1,2,3$.
(a) We denote dist ${ }_{S \cup \mathscr{H}}(x, y)$ by $D$. Let $y_{i}$ be nearest points to $y$ in $\mathfrak{q}_{i}, i=1,2,3$. Then dist ${ }_{S \cup \mathscr{H}}\left(x_{i}, y_{j}\right) \geqslant$ $D-2 r$ for every $i, j \in\{1,2,3\}$. Suppose that $D>2 r$. Without loss of generality we may assume that $y_{1} \in$ $\mathfrak{q}_{1}\left[x_{1}, O_{3}\right]$. We have dist $\operatorname{din}_{( }\left(x_{1}, x_{2}\right) \leqslant 2 r$, hence $\mathfrak{q}_{1}\left[x_{1}, O_{3}\right] \subset \mathcal{N}_{2 \tau r}\left(\operatorname{Sat}^{\left(q_{2}\right.}\left[x_{2}, O_{3}\right]\right)$, where $\tau=\tau(L, C)$. In particular $y_{1}$ is contained either in $\mathscr{N}_{2 \tau r}\left(\mathfrak{q}_{2}\left[x_{2}, O_{3}\right]\right)$ or in $\mathscr{N}_{2 \tau r}(B)$ for $B \in \mathscr{A}$ such that $\mathscr{N}_{M}(B)$ intersects $\mathfrak{q}_{2}\left[x_{2}, O_{3}\right]$.

Case (a)I. Suppose that $y_{2} \in \mathfrak{q}_{2}\left[x_{2}, O_{1}\right]$.
Case (a)I.1. Suppose that $y_{1} \in \mathcal{N}_{2 \tau r}\left(\mathfrak{q}_{2}\left[x_{2}, O_{3}\right]\right)$. Then there exists $u \in \mathfrak{q}_{2}\left[x_{2}, O_{3}\right]$ such that $\operatorname{dist}_{S}\left(y_{1}, u\right) \leqslant 2 \tau r$. It follows that $\operatorname{dist}_{S}\left(u, x_{2}\right) \geqslant \operatorname{dist}_{S \cup \mathscr{H}}\left(u, x_{2}\right) \geqslant D-2 r-2 \tau r$. Inequality (26) implies that

$$
\operatorname{dist}_{S}\left(u, y_{2}\right) \geqslant \frac{1}{L_{1}}\left[\operatorname{dist}\left(u, x_{2}\right)+\operatorname{dist}\left(x_{2}, y_{2}\right)\right]-C_{1} \geqslant \frac{1}{L_{1}}(2 D-4 r-2 \tau r)-C_{1} .
$$

On the other hand dist $\left(u, y_{2}\right) \leqslant 2 \tau r+2 r$. Hence $D \leqslant 2 r+\tau r+L_{1}\left(r+\tau r+C_{1} / 2\right)$.
Case (a)I.2. Assume that $y_{1} \in \mathscr{N}_{2 \tau r}(B)$, where $B \in \mathscr{A}$ is such that $\mathscr{N}_{M}(B)$ intersects $\mathfrak{q}_{2}\left[x_{2}, O_{3}\right]$. Let $w_{2}$ be a point in $\mathscr{N}_{M}(B) \cap \mathfrak{q}_{2}\left[x_{2}, O_{3}\right]$.

Suppose that $\mathfrak{q}_{2}\left[x_{2}, y_{2}\right] \cap \overline{\mathcal{N}}_{2 \tau r}(B) \neq \emptyset$. Let $z_{2}$ be a point in the previous intersection. Then $\mathfrak{q}_{2}\left[w_{2}, z_{2}\right]$ has its endpoints in $\mathcal{N}_{\chi}(B)$, with $\chi=\max (M, 2 \tau r+1)$. Consequently $\mathfrak{q}_{2}\left[w_{2}, z_{2}\right] \subset \mathscr{N}_{\tau \chi}(B)$. In particular $x_{2}$ is contained in $\mathscr{N}_{\tau \chi}(B)$ and $\operatorname{dist}_{S \cup \mathscr{H}}\left(y_{1}, x_{2}\right) \leqslant \tau(2 r+\chi)+1$; hence $D \leqslant \tau(2 r+\chi)+$ $2 r+1$.

Suppose that $\mathfrak{q}_{2}\left[x_{2}, y_{2}\right] \cap \overline{\mathcal{N}}_{2 \tau r}(B)=\emptyset$. We have that $x_{2}$ is in $\mathfrak{q}_{2}\left[w_{2}, y_{2}\right]$. Also, $\mathfrak{q}_{2}\left[w_{2}, y_{2}\right]$ has its endpoints in $\mathscr{N}_{\chi}(B)$, with $\chi=\max (M, 2 r(\tau+1))$. Consequently $\mathfrak{q}_{2}\left[w_{2}, y_{2}\right] \subset \mathscr{N}_{\tau \chi}(B)$. In particular $x_{2}$ is contained in $\mathscr{N}_{\tau \chi}(B)$ and $\operatorname{dist}_{S \cup \mathscr{H}}\left(y_{1}, x_{2}\right) \leqslant \tau(2 r+\chi)+1$; hence $D \leqslant \tau(2 r+\chi)+$ $2 r+1$.

Case (a)II. Suppose that $y_{2} \in \mathfrak{q}_{2}\left[x_{2}, O_{3}\right]$. If $y_{3} \in \mathfrak{q}_{3}\left[x_{3}, O_{1}\right]$ then we repeat the previous argument with $y_{1}$ replaced by $y_{3}$. If $y_{3} \in \mathfrak{q}_{3}\left[x_{3}, O_{2}\right]$ then we repeat the previous argument with $\left(y_{1}, y_{2}\right)$ replaced by $\left(y_{3}, y_{1}\right)$.
(b) We denote $\operatorname{dist}_{S \cup \mathscr{H}}(x, A)$ by $D$. We note that for every point $y$ in $\mathcal{N}_{r}(A) \cap\left(\mathfrak{q}_{1} \cup \mathfrak{q}_{2} \cup \mathfrak{q}_{3}\right)$ we have that $\operatorname{dist}_{S}\left(x_{i}, y\right) \geqslant \operatorname{dist}_{S \cup \mathscr{H}}\left(x_{i}, y\right) \geqslant D-2 r$ for $i=1,2,3$. We choose $y_{i} \in \mathcal{N}_{r}(A) \cap \mathfrak{q}_{i}, i=1,2,3$. Suppose $y_{1} \in \mathfrak{q}_{1}\left[x_{1}, O_{3}\right]$. Like in case (a), we have that $y_{1}$ is contained either in $\mathscr{N}_{2 \tau r}\left(\mathfrak{q}_{2}\left[x_{2}, O_{3}\right]\right)$ or in $\mathscr{N}_{2 \tau r}(B)$ for some $B \in \mathscr{A}$ such that $\mathscr{N}_{M}(B)$ intersects $\mathfrak{q}_{2}\left[x_{2}, O_{3}\right]$.

Case (b)I. Suppose that $y_{2} \in \mathfrak{q}_{2}\left[x_{2}, O_{1}\right]$.
Case (b)I.1. Assume that $y_{1} \in \mathcal{N}_{2 \pi r}\left(\mathfrak{q}_{2}\left[x_{2}, O_{3}\right]\right)$. Then there exists $u \in \mathfrak{q}_{2}\left[x_{2}, O_{3}\right]$ such that $\operatorname{dist}_{S}\left(y_{1}, u\right) \leqslant 2 \tau r$. It follows that $u \in \mathcal{N}_{r(1+2 \tau)}(A)$, which together with $y_{2} \in \mathscr{N}_{r}(A)$ implies that $\mathfrak{q}_{2}\left[u, y_{2}\right] \in \mathscr{N}_{\tau r(1+2 \tau)}(A)$. In particular $x_{2} \in \mathscr{N}_{\tau r(1+2 \tau)}(A)$; therefore $D \leqslant r+\tau r(1+2 \tau)$.

Case (b)I.2. Suppose $y_{1} \in \mathscr{N}_{2 \tau r}(B)$, with $B \in \mathscr{A}$ such that $\mathscr{N}_{M}(B)$ intersects $\mathfrak{q}_{2}\left[x_{2}, O_{3}\right]$. Let $w_{2}$ be a point in $\mathscr{N}_{M}(B) \cap \mathfrak{q}_{2}\left[x_{2}, O_{3}\right]$.

Suppose that $\mathfrak{q}_{2}\left[x_{2}, y_{2}\right] \cap \overline{\mathcal{N}}_{2 \tau r}(B) \neq \emptyset$. As in the proof of part (a), Case I.2, we obtain that dist $S \cup \mathscr{H}\left(y_{1}, x_{2}\right) \leqslant \tau(2 r+\chi)+1$, whence $D \leqslant \tau(2 r+\chi)+2 r+1$.

Suppose that $\mathfrak{q}_{2}\left[x_{2}, y_{2}\right] \cap \overline{\mathcal{N}}_{2 \tau r}(B)=\emptyset$. Then $x_{2}$ is in $\mathfrak{q}_{2}\left[w_{2}, y_{2}\right]$. On the other hand, $\mathfrak{q}_{2}\left[w_{2}, y_{2}\right]$ has its endpoints in the $M$-tubular neighborhood of $\operatorname{Sat}^{2 \tau r}\left(\left[y_{1}, y_{2}\right]\right)$. It follows that $\mathrm{q}_{2}\left[w_{2}, y_{2}\right]$, in particular $x_{2}$, is in the $t M$-tubular neighborhood of $\operatorname{Sat}^{2 \tau r}\left(\left[y_{1}, y_{2}\right]\right)$. In Cayley $(G, S \cup \mathscr{H})$, $\operatorname{Sat}^{2 \tau r}\left(\left[y_{1}, y_{2}\right]\right)$ is contained in the $(2 \tau r+1)$-tubular neighborhood of $\left[y_{1}, y_{2}\right]$. Since in Cayley $(G, S)$ we have that $\left[y_{1}, y_{2}\right] \subset \mathscr{N}_{\tau r}(A)$, we deduce that in Cayley $(G, S \cup \mathscr{H}), x_{2}$ is in the $(t M+3 \tau r+1)$-tubular neighborhood of $A$. Hence $D \leqslant t M+(3 \tau+1) r+1$.

Case (b)II. Suppose that $y_{2} \in \mathfrak{q}_{2}\left[x_{2}, O_{3}\right]$. Then we can use the same argument as in Case II of part (a).

Proof of Proposition 8.16(2). By Lemma 8.19 we are either in case (C) or in case (P).
Case (C). Let $y \in \mathscr{C}_{\kappa}^{\mu}\left(\mathfrak{q}_{1}, \mathfrak{q}_{2}, \mathfrak{q}_{3}\right)$. According to Lemma 8.17 we have either (i) or (ii). Suppose that (i) is satisfied. Then, by Lemma $8.20(\mathrm{a})$, dist ${ }_{S \cup \mathscr{H}}(x, y) \leqslant D$, where $D=D(\alpha, R, L, C)$.

Suppose that (ii) is satisfied, that is $y \in \mathscr{N}_{\kappa}(B)$ and $\mathscr{N}_{\beta}(B)$ intersects each of the three almostgeodesics $\mathfrak{q}_{1}, \mathfrak{q}_{2}, \mathfrak{q}_{3}$. Lemma $8.20(\mathrm{~b})$ implies that dist $\mathcal{S}_{\cup \mathscr{H}}(x, B) \leqslant D$, where $D=D(\beta, R, L, C)$. Therefore $\operatorname{dist}_{S \cup \mathscr{H}}(x, y) \leqslant D+\kappa+1$.

Case (P). Let $y \in \mathscr{C}_{\kappa}^{\mu}\left(\mathfrak{q}_{1}, \mathfrak{q}_{2}, \mathfrak{q}_{3}\right)$. Suppose that $y$ satisfies (i). Lemma 8.20(b) implies that $\operatorname{dist}_{S \cup \mathscr{H}}(y, A) \leqslant D$, with $D=D(\alpha, R, L, C)$.

If $y$ satisfies (ii) of Lemma 8.17, then the unicity stated in (P) implies that $y \in \mathscr{N}_{\kappa}(A)$, and hence that $\operatorname{dist}_{S \cup \mathscr{H}}(y, A) \leqslant \kappa$.

We may conclude that in all cases the diameter of the set $\mathscr{C}_{\kappa}^{\mu}\left(\mathfrak{q}_{1}, \mathfrak{q}_{2}, \mathfrak{q}_{3}\right)$ in the metric dist $S \cup \mathscr{H}$ is uniformly bounded.


Fig. 9. Projection of a point onto the saturation.

We now define a system of lines and centers in Cayley ( $G, S \cup \mathscr{H}$ ) such that the properties in Section 8.1.1 are satisfied.

First of all, for every pair of vertices $u, v$ in $\operatorname{Cayley}(G, S \cup \mathscr{H})$ we choose and fix a geodesic $[u, v]$ in Cayley $(G, S)$ joining the two points. Let $M_{0}=M(1,0)$ and let $\kappa_{0}$ be the constant given by Proposition 8.16 for $\mu=M_{0}$. We may suppose that $\kappa_{0} \geqslant M_{0}$. For every pair of vertices $u$, $v$ in Cayley ( $G, S \cup \mathscr{H}$ ), we define $\Lambda_{u v}$ as $\mathscr{N}_{\kappa_{0}}(\operatorname{Sat}([u, v]))$. The relation on it is defined as follows: to every $x \in \mathscr{N}_{\kappa_{0}}(\operatorname{Sat}([u, v]))$ we associate one nearest point (projection) $x^{\prime} \in[u, v]$ and we put $x \leqslant u v y$ if $x^{\prime}$ is between $u$ and $y^{\prime}$. Properties $\left(l_{1}\right),\left(l_{2}\right),\left(l_{3}\right)$ are obviously satisfied.

We define the function $\phi$ by choosing, for every three vertices $u, v, w$ in Cayley $(G, S)$ a point $C_{u v w}$ in $\mathscr{C}_{\kappa_{0}}^{M_{0}}([u, v],[u, w],[v, w])$ and defining $\phi(u, v, w)=\phi \circ \sigma(u, v, w)=C_{u v w}$ for every 3-permutation $\sigma$. We choose $C_{u u v}=u$.

Properties $\left(c_{1}\right),\left(c_{2}\right),\left(c_{3}\right)$ are satisfied. Before proceeding further, we prove some intermediate results.
Lemma 8.21. For every $\alpha>0$ there exists $\lambda=\lambda(\alpha)$ such that the following holds. Let $[u, v]$ be a geodesic and let $A \in \mathscr{A}$ be such that $\mathscr{N}_{\alpha}(A) \cap[u, v] \neq \emptyset$. Let $x$ be a point in $\mathscr{N}_{\alpha}(A)$ and let $x^{\prime} \in[u, v]$ be a projection of $x$. Then $x^{\prime} \in \mathcal{N}_{\lambda}(A)$ (Fig. 9).

Proof. Suppose that $x^{\prime} \notin \mathscr{N}_{\alpha}(A)$. Lemma 8.15 implies that there exist $t \in[u, v] \cap \mathscr{N}_{\alpha}(A)$ and $s \in$ $\left[x^{\prime}, x\right] \cap \mathscr{N}_{\alpha}(A)$ such that the sets $\left[x^{\prime}, t\right] \cap \overline{\mathscr{N}}_{\alpha}(A)$ and $\left[x^{\prime}, s\right] \cap \overline{\mathscr{N}}_{\alpha}(A)$ have diameters at most $\mathfrak{D}$, where $\mathfrak{D}=\mathfrak{d}(\alpha)$. Corollary 8.14 implies that $\operatorname{dist}(s, t) \leqslant D_{1}$. On the other hand, since $\operatorname{dist}\left(x, x^{\prime}\right) \leqslant \operatorname{dist}(x, t)$, it follows that $\operatorname{dist}\left(s, x^{\prime}\right) \leqslant \operatorname{dist}(s, t) \leqslant D_{1}$. We conclude that $\operatorname{dist}_{S}\left(x^{\prime}, A\right) \leqslant D_{1}+\alpha$.

Corollary 8.22. Let $x$ be a point in $\mathscr{N}_{\kappa}\left(\operatorname{Sat}^{\mu}([u, v])\right)$ and let $x^{\prime} \in[u, v]$ be a projection of $x$. Then $\operatorname{dist}_{S \cup \mathscr{H}}\left(x, x^{\prime}\right) \leqslant \chi$, where $\chi=\chi(\kappa, \mu)$.

Proof. Since $x \in \mathscr{N}_{\kappa}\left(\operatorname{Sat}^{\mu}([u, v])\right)$ it follows that either $x \in \mathscr{N}_{\kappa}([u, v])$ or $x \in \mathscr{N}_{\kappa}(A)$, where $\mathscr{N}_{\mu}(A) \cap$ $[u, v] \neq \emptyset$. In the first case it follows that $\operatorname{dist}_{S \cup \mathscr{H}}\left(x, x^{\prime}\right) \leqslant \kappa$, while in the second case we may apply Lemma 8.21.

Corollary 8.23. Let $u, v$ be a pair of vertices in $\operatorname{Cayley}(G, S \cup \mathscr{H})$ and let $x, y \in \Lambda_{u v}$ and $x^{\prime}, y^{\prime}$ their chosen respective projections on $[u, v]$. Then, in Cayley $(G, S \cup \mathscr{H}), \Lambda_{u v}[x, y]=\Lambda_{u v}[y, x]$ is at Hausdorff distance $\chi$ of $\left[x^{\prime}, y^{\prime}\right] \subset[u, v]$, where $\chi=\chi(G)$.

Before proving properties (I), (II), (III), we make some remarks and introduce some notations.
Remark 8.24. (1) For every quasi-geodesic $\mathfrak{q}$ in $\operatorname{Cayley}(G, S)$, we have that $\operatorname{Sat}^{\mu}(\mathfrak{q})$ is in the $(\mu+1)$ tubular neighborhood of $\mathfrak{q}$ in $\operatorname{Cayley}(G, S \cup \mathscr{H})$.
(2) Lemma 8.17 implies that there exist two constants $\eta$ and $c$ such that for every three geodesics $[u, v],[v, w],[u, w]$ in Cayley $(G, S)$ every point $x \in \mathscr{C}_{\kappa_{0}}^{M_{0}}([u, v],[v, w],[u, w])$ satisfies one of the following two properties:
(i) the ball $B(x, \eta)$ intersects each of the three geodesics $[u, v],[v, w],[u, w]$;
(ii) $x \in \mathscr{N}_{\kappa_{0}}(A)$ and $\mathscr{N}_{c}(A)$ intersects each of the three geodesics $[u, v],[v, w],[u, w]$.

We note that the constants $\eta$ and $c$ depend on $M_{0}$ and $\kappa_{0}$, so they depend only on $G$. We may suppose without loss of generality that $c \geqslant M_{0}$.
(3) Lemma 8.21 implies that there exists $\xi$ such that if $[u, v]$ is a geodesic, $A \in \mathscr{A}$ is such that $\mathscr{N}_{c}(A)$ intersects $[u, v]$ and $x$ is a point in $\mathscr{N}_{\kappa_{0}}(A)$, then any projection of $x$ on $[u, v]$ is in $\mathscr{N}_{\xi}(A)$. The constant $\xi$ depends on $\max \left(c, \kappa_{0}\right)$, so it depends only on $G$. Without loss of generality we may suppose that $\xi \geqslant M_{0}$.
(4) In the sequel we denote the constant $\mathfrak{D}(1,0, c)$ provided by Lemma 8.15 simply by $\mathfrak{d}$.

Proof of properties (I), (II), (III). (I). Let $x=\phi(u, v, w)$ and let $x_{1}$ and $x_{2}$ be the chosen projections of $x$ on $[u, v]$ and on $[u, w]$, respectively. According to Corollary 8.23 , it suffices to prove that $\left[u, x_{1}\right]$ and $\left[u, x_{2}\right]$ are at uniformly bounded Hausdorff distance in Cayley $(G, S \cup \mathscr{H})$. The point $x=\phi(u, v, w)$ satisfies either (i) or (ii) from Remark 8.24(2).

Suppose $x$ is in case (ii). Then $x \in \mathcal{N}_{\kappa_{0}}(A)$ such that $\mathscr{N}_{c}(A)$ intersects the three geodesic edges. Lemma 8.21 implies that $x_{1}, x_{2} \in \mathscr{N}_{\xi}(A)$. The geodesic [ $\left.u, x_{1}\right]$ has its endpoints in $\mathscr{N}_{\xi}\left(\mathrm{Sat}^{\xi}\left[u, x_{2}\right]\right)$. Lemma 8.10 implies that $\left[u, x_{1}\right]$ is entirely contained in $\mathcal{N}_{\tau \xi}\left(\operatorname{Sat}^{\xi}\left[u, x_{2}\right]\right)$. It follows that $\left[u, x_{1}\right]$ is in the $[(\tau+1) \xi+1]$-tubular neighborhood of $\left[u, x_{2}\right]$ in Cayley $(G, S \cup \mathscr{H})$. A similar argument done for $\left[u, x_{2}\right]$ allows one to conclude that (I) is satisfied.

Suppose $x$ is in case (i). Then $\operatorname{dist}_{S}\left(x, x_{i}\right) \leqslant \eta$ for $i=1,2$. Hence dist ${ }_{S}\left(x_{1}, x_{2}\right) \leqslant 2 \eta$ and $\left[u, x_{i}\right]$ has its endpoints in $\mathscr{N}_{2 \eta}\left(\operatorname{Sat}\left[u, x_{j}\right]\right)$, for $\{i, j\}=\{1,2\}$. We repeat the previous argument.
(II) The fact that dist ${ }_{S \cup \mathscr{H}}(p, q) \leqslant 1$ means that either $\operatorname{dist}_{S}(p, q) \leqslant 1$ or $p, q \in A_{0}$, where $A_{0} \in \mathscr{A}$. Let $x=\phi(u, v, p)$ and $y=\phi(u, v, q)$. We have to show that $\Lambda_{u v}[x, y]$ has uniformly bounded diameter in Cayley $(G, S \cup \mathscr{H})$. Let $x_{0}$ and $y_{0}$ be the respective projections of $x$ and $y$ on $[u, v]$. Corollary 8.23 implies that it suffices to prove that $\left[x_{0}, y_{0}\right]$ has uniformly bounded diameter in Cayley ( $G, S \cup \mathscr{H}$ ), where by [ $x_{0}, y_{0}$ ] we denote the sub-arc of $[u, v]$ of endpoints $x_{0}, y_{0}$.

Suppose that both $x$ and $y$ are in case (i). We have that $x_{0} \in \mathcal{N}_{2 \eta}[u, p] \cap \mathcal{N}_{2 \eta}[v, p]$ and that $y_{0} \in$ $\mathscr{N}_{2 \eta}[u, q] \cap \mathscr{N}_{2 \eta}[v, q]$. Since $[u, p] \subset \mathscr{N}_{\tau}(\operatorname{Sat}[u, q])$ and $[v, p] \subset \mathscr{N}_{\tau}(\operatorname{Sat}[v, q])$, we conclude that $x_{0}, y_{0} \in \mathscr{C}_{2 \eta+\tau}^{M_{0}}([u, q],[v, q],[u, v])$, and hence that $\left[x_{0}, y_{0}\right] \subset \mathscr{C}_{\tau(2 \eta+\tau)}^{M_{0}}([u, q],[v, q],[u, v])$. We complete the proof by applying Proposition 8.16.

Suppose $x$ is in case (i) and $y$ is in case (ii). The case when $x$ is in case (ii) and $y$ is in case (i) is discussed similarly. As above we have that $x_{0} \in \mathscr{C}_{2 \eta+\tau}^{M_{0}}([u, q],[v, q],[u, v])$. We have that $y \in$ $\mathscr{N}_{\kappa_{0}}(A)$ such that $\mathscr{N}_{c}(A)$ intersects $[u, q],[v, q],[u, v]$. Lemma 8.21 implies that $y_{0} \in \mathscr{N}_{\xi}(A)$. Then $y_{0} \in \mathscr{C}_{\xi}^{c}([u, q],[v, q],[u, v])$. As previously we obtain that $\left[x_{0}, y_{0}\right] \subset \mathscr{C}_{\tau^{\prime} r}^{s}([u, q],[v, q],[u, v])$, where $r=\max (2 \eta+\tau, \xi), s=\max \left(M_{0}, c\right)$ and $\tau^{\prime}=\tau^{\prime}(s)$. Proposition 8.16 allows one to complete the argument.

Suppose that both $x$ and $y$ are in case (ii). Then $x \in \mathscr{N}_{\kappa_{0}}(A)$ such that $\mathscr{N}_{c}(A)$ intersects $[p, u],[p, v]$, $[u, v]$. Let $p_{1} \in[u, p] \cap \mathscr{N}_{c}(A)$ and $p_{2} \in[v, p] \cap \mathscr{N}_{c}(A)$ be such that $\left[p, p_{i}\right] \cap \overline{\mathscr{N}}_{c}(A)$ has diameter at most $\mathfrak{D}, i=1$, 2. Likewise we consider $u_{1} \in[u, v] \cap \mathscr{N}_{c}(A)$ and $u_{2} \in[u, p] \cap \mathscr{N}_{c}(A)$ so that $\left[u, u_{i}\right] \cap \overline{\mathscr{N}}_{c}(A)$ has diameter at most $\mathfrak{D}$, and $v_{1} \in[p, v] \cap \mathscr{N}_{c}(A)$ and $v_{2} \in[u, v] \cap \mathscr{N}_{c}(A)$ so that $\left[v, v_{i}\right] \cap \overline{\mathscr{N}}_{c}(A)$ has diameter at most $\mathfrak{D}$. Corollary 8.14 implies that $\operatorname{dist}_{S}\left(p_{1}, p_{2}\right), \operatorname{dist}_{S}\left(u_{1}, u_{2}\right)$ and $\operatorname{dist}_{S}\left(v_{1}, v_{2}\right)$ are at most $\zeta$, where $\zeta=\zeta(G)$.

We have that either $A \subset \operatorname{Sat}[u, q]$ or $\mathscr{N}_{c}(A) \cap \mathscr{N}_{\tau}(\operatorname{Sat}[u, q])$ has diameter at most $\gamma$, where $\gamma=\gamma(G)$. The latter case implies, together with the inclusion $[u, p] \subset \mathscr{N}_{\tau}(\operatorname{Sat}[u, q])$, that $\operatorname{dist}\left(p_{1}, u_{2}\right) \leqslant \gamma$. Thus, we have that either $A \subset \operatorname{Sat}[u, q]$ or $\operatorname{dist}\left(p_{1}, u_{2}\right) \leqslant \gamma$. Likewise, we obtain that either $A \subset \operatorname{Sat}[v, q]$ or $\operatorname{dist}\left(p_{2}, v_{1}\right) \leqslant \gamma$.

Suppose that dist $\left(p_{1}, u_{2}\right) \leqslant \gamma$. Then $\operatorname{dist}\left(p_{1}, u_{1}\right) \leqslant \gamma+\zeta$, and hence $B\left(p_{1}, \gamma+\zeta\right)$ intersects $[p, u],[p, v]$, $[u, v]$. We can argue similarly to the case above when $x$ is in case (i) and $y$ is in case (ii), with $x$ replaced by $p_{1}$ and $\eta$ by $\gamma+\zeta$. We obtain that if $p_{1}^{\prime}$ is the chosen projection of $p_{1}$ on $[u, v]$ then $\left[p_{1}^{\prime}, y_{0}\right]$ has the diameter bounded in $\operatorname{Cayley}(G, S \cup \mathscr{H})$ by a constant depending on $G$. Since $\left[x_{0}, y_{0}\right] \subset\left[x_{0}, p_{1}^{\prime}\right] \cup\left[p_{1}^{\prime}, y_{0}\right]$, it remains to prove that $\left[x_{0}, p_{1}^{\prime}\right]$ has bounded diameter in Cayley $(G, S \cup \mathscr{H})$. Lemma 8.21 provides for $\alpha=\max \left(\kappa_{0}, c\right)$ a constant $\tilde{\lambda}$. We have that $x_{0}$ and $p_{1}^{\prime}$ are in $\mathscr{N}_{\tilde{\lambda}}(A)$, and hence that $\left[x_{0}, p_{1}^{\prime}\right] \subset \mathscr{N}_{\tau}(A)$. We conclude that the diameter of $\left[x_{0}, p_{1}^{\prime}\right]$ in $\operatorname{Cayley}(G, S \cup \mathscr{H})$ is at most $2 \tau \tilde{\lambda}+1$. A similar argument works if $\operatorname{dist}\left(p_{2}, v_{1}\right) \leqslant \gamma$.

Now suppose that $A \subset \operatorname{Sat}[u, q] \cap \operatorname{Sat}[v, q]$. Lemma 8.21 implies that $x_{0} \in \mathscr{N}_{\xi}(A)$. Since $y$ is also in case (ii), we have that $y \in \mathscr{N}_{\kappa_{0}}(B)$ such that $\mathscr{N}_{c}(B)$ intersects the three geodesic edges $[q, u],[q, v],[u, v]$ and that $y_{0} \in \mathscr{N}_{\xi}(B)$. We have that $A \cup B \subset \operatorname{Sat}^{c}[u, q] \cap \operatorname{Sat}^{c}[v, q] \cap \operatorname{Sat}^{c}[u, v]$. Lemma 8.10 implies that $\left[x_{0}, y_{0}\right] \subset \mathscr{C}_{\tau \xi}^{c}([q, u],[q, v],[u, v])$ and Proposition 8.16 allows one to finish the argument.
(III) Let $u, v, w$ be three vertices such that $w \in \mathscr{N}_{\kappa_{0}}(\operatorname{Sat}[u, v])$. Let $x=\phi(u, v, w)$. Let $w_{0}$ and $x_{0}$ be the projections of $w$ and $x$, respectively on $[u, v]$. We bound the diameter of $\left[x_{0}, w_{0}\right]$ in Cayley $(G, S \cup \mathscr{H})$.

We have $x, w \in \mathscr{C}_{k_{0}}^{M_{0}}([u, v],[u, w],[v, w])$. Suppose both $x$ and $w$ are in case (i). Then $x_{0}, w_{0} \in$ $\mathscr{C}_{\kappa_{0}+\eta}^{M_{0}}([u, v],[u, w],[v, w]) ;$ consequently $\left[x_{0}, w_{0}\right] \subset \mathscr{C}_{\tau\left(\kappa_{0}+\eta\right)}^{M_{0}}([u, v],[u, w],[v, w])$ and we apply Proposition 8.16 to obtain the conclusion.

Suppose that $x$ is in case (i) and $w$ in case (ii). The case when $x$ is in case (ii) and $w$ in case (i) is similar. The ball $B(x, \eta)$ intersects the three edges and $w \in \mathscr{N}_{\kappa_{0}}(A)$ such that $\mathscr{N}_{c}(A)$ intersects the three edges. Lemma 8.21 implies that $w_{0} \in \mathcal{N}_{\xi}(A) \subset \mathscr{C}_{\xi}^{c}([u, v],[u, w],[v, w])$. The point $x_{0}$ is in $\mathscr{C}_{\eta+\kappa_{0}}^{M_{0}}([u, v],[u, w],[v, w])$. It follows that $\left[x_{0}, w_{0}\right] \subset \mathscr{C}_{\tau^{\prime} r}^{s}([u, v],[u, w],[v, w])$, where $r=\max (\eta+$ $\left.\kappa_{0}, \xi\right), s=\max \left(M_{0}, c\right)$ and $\tau^{\prime}=\tau^{\prime}(s)$. We apply Proposition 8.16.

Suppose that $x$ and $w$ are both in case (ii). We have that $x \in \mathcal{N}_{\kappa_{0}}(A)$ and $w \in \mathscr{N}_{\kappa_{0}}(B)$ such that both $\mathscr{N}_{c}(A)$ and $\mathscr{N}_{c}(B)$ intersect the three edges. We also have that $x_{0} \in \mathscr{N}_{\xi}(A)$ and $w_{0} \in \mathscr{N}_{\xi}(B)$; hence $\left[x_{0}, w_{0}\right] \subset \mathscr{C}_{\tau \xi}^{c}([u, v],[u, w],[v, w])$. We end the proof by applying Proposition 8.16.

Proposition 8.7 implies that $\operatorname{Cayley}(G, S \cup \mathscr{H})$ is hyperbolic. Moreover we have that $\Lambda_{u v}$ is at bounded Hausdorff distance from every geodesic connecting $u$ and $v$ in Cayley $(G, S \cup \mathscr{H})$. Since in the previous argument the choice of the geodesics $[u, v]$ in Cayley $(G, S)$ was arbitrary, we have the following.

Proposition 8.25. Every geodesic in Cayley $(G, S)$ joining two points $u$ and $v$ is at bounded Hausdorff distance in Cayley $(G, S \cup \mathscr{H})$ from any geodesic joining $u$ and $v$ in Cayley $(G, S \cup \mathscr{H})$.

### 8.2. The BCP property

Given two vertices $u, v$ in $\operatorname{Cayley}(G, S \cup \mathscr{H})$, we denote by $[u, v]$ a geodesic joining them in $\operatorname{Cayley}(G, S)$ and by $\mathfrak{g}_{u v}$ a geodesic joining them in Cayley $(G, S \cup \mathscr{H})$.

Definition 8.26. For a path $\mathfrak{p}$ in $\operatorname{Cayley}(G, S \cup \mathscr{H})$, we denote by $\tilde{p}$ a path in Cayley $(G, S)$ obtained by replacing every $\mathscr{H}$-component $s$ in $\mathfrak{p}$ by a geodesic in Cayley $(G, S)$ connecting $s_{-}$and $s_{+}$. We call $\tilde{\mathfrak{p}}$ a lift of $\mathfrak{p}$.

We now prove the following.
Proposition 8.27. If $G$ is asymptotically tree-graded with respect to $\left\{H_{1}, \ldots, H_{m}\right\}$ and $G$ is weakly hyperbolic relative to $\left\{H_{1}, \ldots, H_{m}\right\}$ then the pair $\left(G,\left\{H_{1}, \ldots, H_{m}\right\}\right)$ satisfies the $B C P$ property.

Proof. Let $\lambda \geqslant 1$. Let $\mathfrak{p}$ and $\mathfrak{q}$ be two $\lambda$-bi-Lipschitz paths without backtracking in Cayley $(G, S \cup \mathscr{H})$ such that $\mathfrak{p}_{-}=\mathfrak{q}_{-}$and $\operatorname{dist}_{S}\left(\mathfrak{p}_{+}, \mathfrak{q}_{+}\right) \leqslant 1$.
(1) Let $s$ be an $\mathscr{H}$-component of $\mathfrak{p}$ contained in a left $\operatorname{coset} A \in \mathscr{A}$, and let $\operatorname{dist}_{S}\left(s_{-}, s_{+}\right)=D$. We show that if $D$ is large enough then $\mathfrak{q}$ has an $\mathscr{H}$-component contained in $A$.

Notations. In this section $M$ denotes $M(\lambda, 0)$, the constant given by $\left(\alpha_{2}^{\prime}\right)$ for $\theta=\frac{1}{3}$ and $(L, C)=(\lambda, 0)$. The graph Cayley $(G, S \cup \mathscr{H})$ is hyperbolic. Therefore for the given $\lambda$ there exists $\chi=x(\lambda)$ such that two $\lambda$-bi-Lipschitz paths $\mathfrak{p}$ and $\mathfrak{q}$ in $\operatorname{Cayley}(G, S \cup \mathscr{H})$ with $\operatorname{dist}_{S \cup \mathscr{H}}\left(\mathfrak{p}_{-}, \mathfrak{q}_{-}\right) \leqslant 1$ and dist $\operatorname{d}_{S} \cup \mathscr{H}\left(\mathfrak{p}_{+}, \mathfrak{q}_{+}\right) \leqslant 1$ are at Hausdorff distance at most $x$.

Step I. We show that for $D \geqslant D_{0}(G)$, some lift $\tilde{q}$ of $\mathfrak{q}$ intersects $\mathcal{N}_{M^{\prime}}(A)$, where $M^{\prime}=M^{\prime}(G)$. We choose $u$ on the $\operatorname{arc} \mathfrak{p}\left[p_{-}, s_{-}\right]$such that either the length of $\mathfrak{p}\left[u, s_{-}\right]$is $2 \lambda(x+1)$ or, if the length of $\mathfrak{p}\left[p_{-}, s_{-}\right]$ is less than $2 \lambda(x+1), u=\mathfrak{p}_{-}$. Likewise we choose $v$ on the $\operatorname{arc} \mathfrak{p}\left[s_{+}, \mathfrak{p}_{+}\right]$such that either the length of $\mathfrak{p}\left[s_{+}, v\right]$ is $2 \lambda(\varkappa+1)$ or $v=p_{+}$. We have that dist $\operatorname{di}_{\mathscr{H}}\left(u, s_{-}\right)$, $\operatorname{dist}_{S \cup \mathscr{H}}\left(s_{+}, v\right) \in\left[2(\varkappa+1), 2 \lambda^{2}(\varkappa+1)\right]$, in the first cases.

There exist $w$ and $z$ on $\mathfrak{q}$ such that dist $\mathcal{S U}_{\mathscr{H}}(u, w) \leqslant \chi$ and $\operatorname{dist}_{S \cup \mathscr{H}}(v, z) \leqslant \chi$. We consider $\mathfrak{g}_{u w}$ and $\mathfrak{g}_{v z}$ geodesics in Cayley ( $G, S \cup \mathscr{H}$ ).

Let $u^{\prime}$ be the farthest from $u$ point on $\mathfrak{g}_{u w}$ which is contained in the same left coset $B \in \mathscr{A}$ as an $\mathscr{H}$-component $\sigma$ of $\mathfrak{p}[u, v]$. Suppose that $\sigma \cap \mathfrak{p}\left[s_{-}, v\right] \neq \emptyset$. We have that

$$
\operatorname{dist}_{S \cup \mathscr{H}}\left(u, u^{\prime}\right) \geqslant \operatorname{dist}_{S \cup \mathscr{H}}\left(u, \sigma_{+}\right)-1 \geqslant \frac{1}{\lambda} \text { length }\left(\mathfrak{p}\left[u, \sigma_{+}\right]\right)-1 \geqslant \frac{1}{\lambda} \text { length }\left(\mathfrak{p}\left[u, s_{-}\right]\right)-1 \geqslant 2 x+1 .
$$

This contradicts the inequality dist $\mathcal{S \cup \mathscr { H }}\left(u, u^{\prime}\right) \leqslant \chi$. Therefore $\sigma$ is contained in $\mathfrak{p}\left[u, s_{-}\right] \backslash\left\{s_{-}\right\}$. We choose $v^{\prime}$ the farthest from $v$ point on $\mathfrak{g}_{v z}$ contained in the same left coset as a component $\sigma^{\prime}$ of $\mathfrak{p}[u, v]$. In a similar way we prove that $\sigma^{\prime}$ is contained in $\mathfrak{p}\left[s_{+}, v\right] \backslash\left\{s_{+}\right\}$. It is possible that $u^{\prime}=u, \sigma=\{u\}$ and/or $v^{\prime}=v$, $\sigma^{\prime}=\{v\}$ (Fig. 10).

We consider the path in $\operatorname{Cayley}(G, S \cup \mathscr{H})$ defined as $\mathfrak{r}=\mathfrak{g}_{w u^{\prime}} \sqcup \mathfrak{g}_{u^{\prime} \sigma_{+}} \sqcup \mathfrak{p}\left[\sigma_{+}, \sigma_{-}^{\prime}\right] \sqcup \mathfrak{g}_{\sigma_{-}^{\prime} v^{\prime}} \sqcup \mathfrak{g}_{v^{\prime} z}$, where $\mathfrak{g}_{w u^{\prime}}$ and $\mathfrak{g}_{v^{\prime} z}$ are sub-geodesics of $\mathfrak{g}_{w u}$ and $\mathfrak{g}_{v z}$, respectively, and $\mathfrak{g}_{u^{\prime} \sigma_{+}}$and $\mathfrak{g}_{\sigma_{-}^{\prime} v^{\prime}}$ are composed of one edge. The length of $r$ is at most $N=\lambda(4 \chi+5)+2 \chi$. It contains the component $s$. We show that it has no backtracking. By construction and the fact that geodesics do not have backtracking [43, Lemma 2.23], we have that the sub-arcs $\mathfrak{r}\left[w, v^{\prime}\right]$ and $\mathfrak{r}\left[u^{\prime}, z\right]$ do not have backtracking. Suppose that $\mathfrak{g}_{w u^{\prime}}$ and $\mathfrak{g}_{v^{\prime} z}$ have $\mathscr{H}$-components in the same left coset. It follows that there exists $x \in \mathfrak{g}_{w u^{\prime}}$ and $y \in \mathfrak{g}_{v^{\prime} z}$ with $\operatorname{dist}_{S \cup \mathscr{H}}(x, y) \leqslant 1$. Then dist $\operatorname{du\mathscr {H}}(u, v) \leqslant 2 \chi+1$. By construction either length $\mathfrak{p}[u, v] \geqslant 2 \lambda(x+1)+1$ or


Fig. 10. Proof of (1) in BCP property.
$u=\mathfrak{p}_{-}$and $v=\mathfrak{p}_{+}$. In the latter case, the geodesic $\mathfrak{g}_{w u}$ is trivial, $\mathfrak{g}_{v z}$ is an edge $e$ in Cayley $(G, S)$, and $\mathfrak{r}=\mathfrak{p} \cup e$ has no backtracking. In the former case we have that dist $\operatorname{SU}_{S \mathscr{H}}(u, v)>2 x+2$, which contradicts the previous inequality.

We conclude that $r$ is without backtracking. A lift $\tilde{r}$ of it is composed of $n$ consecutive sub-paths,

$$
\begin{equation*}
\tilde{\mathfrak{r}}=\tilde{\mathfrak{r}}_{1} \cup \cdots \cup \tilde{\mathfrak{r}}_{n} \tag{27}
\end{equation*}
$$

with $n \leqslant N$, such that each $\tilde{\mathrm{r}}_{i}$ is either
$\left(\mathrm{R}_{1}\right)$ a $\lambda$-bi-Lipschitz arc both in $\operatorname{Cayley}(G, S)$ and in Cayley $(G, S \cup \mathscr{H})$ of length at most $N$ or $\left(\mathrm{R}_{2}\right)$ a geodesic in Cayley $(G, S)$ with endpoints in some left coset $A_{i} \in \mathscr{A}$.

Since r is without backtracking, we have that $A_{i} \neq A_{j}$ when $i \neq j$. Lemma 8.12 implies that $\tilde{\mathrm{r}}$ is an $\left(L_{N}, C_{N}\right)$-almost geodesic.

On the other hand, $\operatorname{dist}_{S \cup \mathscr{H}}(w, z) \leqslant$ length $\mathfrak{r} \leqslant N$. Hence the length of $\mathfrak{q}[w, z]$ is at most $N_{1}$, where $N_{1}=\lambda N$. As above, a lift $\tilde{q}[w, z]$ decomposes into $m$ consecutive sub-paths,

$$
\begin{equation*}
\tilde{\mathfrak{q}}[w, z]=\tilde{\mathfrak{q}}_{1} \cup \cdots \cup \tilde{\mathfrak{q}}_{m}, \tag{28}
\end{equation*}
$$

with $m \leqslant N_{1}$, such that each $\tilde{\mathfrak{q}}_{i}$ is either
$\left(\mathrm{Q}_{1}\right)$ a $\lambda$-bi-Lipschitz arc both in $\operatorname{Cayley}(G, S)$ and $\operatorname{Cayley}(G, S \cup \mathscr{H})$, of length at most $N_{1}$, or $\left(\mathrm{Q}_{2}\right)$ a geodesic in Cayley $(G, S)$ with endpoints in some left coset $B_{i} \in \mathscr{A}$.

Since $\mathfrak{q}$ is without backtracking, we have that $B_{i} \neq B_{j}$ when $i \neq j$. Lemma 8.12 implies that $\tilde{\mathfrak{q}}[w, z]$ is an $\left(L_{N_{1}}, C_{N_{1}}\right)$-almost geodesic. We denote $L^{\prime}=\max \left(L_{N}, L_{N_{1}}\right)$ and $C^{\prime}=\max \left(C_{N}, C_{N_{1}}\right)$. We denote $M^{\prime}=M\left(L^{\prime}, C^{\prime}\right)$. Lemma 4.25 implies that in $\operatorname{Cayley}(G, S)$ the path $\tilde{\mathfrak{r}}$ is contained in the $\tau^{\prime}$-tubular neighborhood of $\operatorname{Sat}(\tilde{\mathfrak{q}}[w, z])=\operatorname{Sat}^{M^{\prime}}(\tilde{q}[w, z])$, where $\tau^{\prime}=\tau^{\prime}\left(L^{\prime}, C^{\prime}\right)$. In particular the component $s$ is contained in $\mathscr{N}_{\tau^{\prime}}(\operatorname{Sat}(\tilde{q}[w, z]))$; hence the set $\mathscr{N}_{\tau^{\prime}}(\operatorname{Sat}(\tilde{q}[w, z])) \cap A$ has diameter at least $D$. Lemma 4.22 implies that for $D \geqslant D_{0}\left(L^{\prime}, C^{\prime}, \tau^{\prime}\right)$ we must have that $\mathscr{N}_{M^{\prime}}(A) \cap \tilde{q}[w, z] \neq \emptyset$.

Step II. We show that there exist two points $w_{1}$ and $z_{1}$ on $\tilde{q}[w, z]$ such that $\operatorname{dist}_{S}\left(w_{1}, s_{-}\right) \leqslant D_{1}$ and $\operatorname{dist}_{S}\left(z_{1}, s_{+}\right) \leqslant D_{1}$, where $D_{1}=D_{1}(G)$. We do this by means of Corollary 8.14.

Lemma 8.15 implies that there exist $w_{1}, z_{1} \in \tilde{\mathfrak{q}}[w, z] \cap \mathscr{N}_{M^{\prime}}(A)$ such that $\tilde{\mathfrak{q}}\left[w, w_{1}\right]$ and $\tilde{\mathfrak{q}}\left[z_{1}, z\right]$ intersect $\overline{\mathscr{N}}_{M^{\prime}}(A)$ in two sets of diameter at most $\mathfrak{D}_{1}$, where $\mathfrak{D}_{1}=\mathfrak{D}_{1}\left(L^{\prime}, C^{\prime}, M^{\prime}\right)$.

We show that $\tilde{\mathrm{r}}\left[w, s_{-}\right]$and $\tilde{r}\left[s_{+}, z\right]$ intersect $\overline{\mathcal{N}}_{M^{\prime}}(A)$ in two sets of bounded diameter. We prove it only for $\tilde{r}\left[w, s_{-}\right]$; the same argument works for $\tilde{r}\left[s_{+}, z\right]$. Let $x \in \tilde{\mathfrak{r}}\left[w, s_{-}\right] \cap \overline{\mathscr{N}}_{M^{\prime}}(A)$ and let dist ${ }_{S}\left(x, s_{-}\right)=\delta$. According to the decomposition (27), we have that $\tilde{\mathfrak{r}}\left[x, s_{-}\right]=\tilde{\mathfrak{r}}_{i}^{\prime} \cup \tilde{\mathfrak{r}}_{i+1} \cup \cdots \cup \tilde{\mathfrak{r}}_{j}$, where $i \leqslant j, i, j \in$
$\{1,2, \ldots, n\}$ and $\tilde{r}_{\tilde{r}}^{\prime}$ is eventually a restriction of $\tilde{r}_{i}$ such that $x$ is an endpoint of it. If all the components are of type $\left(\mathrm{R}_{1}\right)$, then $\tilde{r}\left[x, s_{-}\right]$has length at most $N$ and $\delta \leqslant N$. Suppose that at least one component is of type $\left(\mathrm{R}_{2}\right)$. We have at most $N$ such components. Then at least one component $\tilde{\mathfrak{r}}_{k}$ of type $\left(\mathrm{R}_{2}\right)$ has the distance between its endpoints at least $(\delta-N) / N$. On the other hand since $x, s_{-} \in \mathcal{N}_{M^{\prime}+1}(A)$ and $\tilde{r}\left[x, s_{-}\right]$is an $\left(L^{\prime}, C^{\prime}\right)$-almost-geodesic, it follows that $\tilde{r}\left[x, s_{-}\right] \subset \mathscr{N}_{\tau^{\prime}\left(M^{\prime}+1\right)}(A)$. In particular $\tilde{\mathfrak{r}}_{k}$ is contained in the same tubular neighborhood; therefore the diameter of $A_{k} \cap \mathscr{N}_{\tau^{\prime}\left(M^{\prime}+1\right)}(A)$ is at least $(\delta-N) / N$. There exists $\delta_{0}=\delta_{0}\left(L^{\prime}, C^{\prime}, N\right)$ such that if $\delta \geqslant \delta_{0}$ then $A_{k}=A$. This contradicts the fact that $\mathfrak{r}$ is without backtracking. We conclude that $\delta \leqslant \delta_{0}$.

We apply Corollary 8.14 to $\tilde{\mathfrak{q}}\left[w, w_{1}\right]$ and to $\tilde{\mathfrak{r}}\left[w, s_{-}\right]$and we obtain that $\operatorname{dist}_{S}\left(w_{1}, s_{-}\right) \leqslant D_{1}$, where $D_{1}=D_{1}\left(L^{\prime}, C^{\prime}, \delta_{0}\right)$. With a similar argument we obtain that $\operatorname{dist}_{S}\left(z_{1}, s_{+}\right) \leqslant D_{1}$.

Step III. We show that $\mathfrak{q}$ has a component in $A$.
We have that $\operatorname{dist}_{S}\left(w_{1}, z_{1}\right) \geqslant D-2 D_{1}$ and that $\tilde{\mathfrak{q}}\left[w_{1}, z_{1}\right] \subset \mathscr{N}_{\tau^{\prime} D_{1}}(A)$. The decomposition (28) implies that $\tilde{\mathfrak{q}}\left[w_{1}, z_{1}\right]=\tilde{\mathfrak{q}}_{k}^{\prime} \cup \tilde{\mathfrak{q}}_{k+1} \cup \cdots \cup \tilde{\mathfrak{q}}_{l-1} \cup \tilde{\mathfrak{q}}_{l}^{\prime}$, where $k \leqslant l, k, l \in\left\{1,2, \ldots, N_{1}\right\}$ and $\tilde{\mathfrak{q}}_{k}^{\prime}, \tilde{\mathfrak{q}}_{l}^{\prime}$ are eventually restrictions of $\tilde{\mathfrak{q}}_{k}, \tilde{\mathfrak{q}}_{l}$, respectively, with endpoints $w_{1}$ and $z_{1}$. If $D-2 D_{1}>N_{1}$ it follows that $\tilde{\mathfrak{q}}\left[w_{1}, z_{1}\right]$ has at least a component of type $\left(\mathrm{Q}_{2}\right)$. Since it has at most $N_{1}$ such components, we may moreover say that $\tilde{\mathfrak{q}}\left[w_{1}, z_{1}\right]$ has at least a component $\tilde{\mathfrak{q}}_{i}$ with endpoints at distance at least $\left(D-2 D_{1}-N_{1}\right) / N_{1}$. Consequently the diameter of $B_{i} \cap \mathscr{N}_{\tau^{\prime} D_{1}}(A)$ is at least $\left(D-2 D_{1}-N_{1}\right) / N_{1}$. For $D$ large enough we obtain that $B_{i}=A$. We conclude that $\mathfrak{q}$ has a component in $A$.
(2) Suppose that $s$ and $t$ are $\mathscr{H}$-components of $\mathfrak{p}$ and $\mathfrak{q}$, respectively, contained in a left coset $A \in \mathscr{A}$. We show that $\operatorname{dist}_{S}\left(s_{-}, t_{-}\right)$and $\operatorname{dist}_{S}\left(s_{+}, t_{+}\right)$are bounded by a constant depending on $G$.

We take $u \in \mathfrak{p}\left[\mathfrak{p}_{-}, s_{-}\right]$either such that the length of $\mathfrak{p}\left[u, s_{-}\right]$is $2 \lambda(x+1)$ or, if the length of $\mathfrak{p}\left[p_{-}, s_{-}\right]$ is less than $2 \lambda(x+1), u=\mathfrak{p}_{-}$. Likewise we take $v \in \mathfrak{p}\left[s_{+}, \mathfrak{p}_{+}\right]$either such that the length of $\mathfrak{p}\left[s_{+}, v\right]$ is $2 \lambda(x+1)$ or, if the length of $\mathfrak{p}\left[s_{+}, \mathfrak{p}_{+}\right]$is less than $2 \lambda(x+1), v=\mathfrak{p}_{+}$.

Since $\operatorname{dist}_{S \cup \mathscr{H}}\left(s_{-}, t_{-}\right) \leqslant 1$ and $\operatorname{Cayley}(G, S \cup \mathscr{H})$ is hyperbolic, there exists $w \in \mathfrak{q}\left[q_{-}, t_{-}\right]$such that dist $\operatorname{du}_{\mathscr{H}}(u, w) \leqslant \chi$. Similarly, dist $S \cup \mathscr{H}\left(s_{+}, t_{+}\right) \leqslant 1$ implies the existence of $z \in \mathfrak{q}\left[t_{+}, \mathfrak{q}_{+}\right]$such that $\operatorname{dist}_{S \cup \mathscr{H}}(v, z) \leqslant \chi$. We consider two geodesics $\mathfrak{g}_{u w}$ and $\mathfrak{g}_{v z}$. As in Step 1 of the proof of (1), we show that the path $\mathfrak{g}_{w u} \cup \mathfrak{p}[u, v] \cup \mathfrak{g}_{v z}$ can be modified to give a path $\mathfrak{r}$ with endpoints $w$ and $z$ and of length at most $N$, without backtracking, containing $s$, such that any of its lifts, $\tilde{\mathrm{r}}$, decomposes as in (27) and it is an $\left(L^{\prime}, C^{\prime}\right)$-almost-geodesic. Again as in Step I of the proof of (1), we show that the length of $\mathfrak{q}[w, z]$ is at most $N_{1}$ and that any lift $\tilde{q}[w, z]$ decomposes as in (28) and it is an ( $L^{\prime}, C^{\prime}$ )-almost-geodesic.

With an argument as in Step II of the proof of (1), we show that $\tilde{r}\left[w, s_{-}\right]$and $\tilde{r}\left[s_{+}, z\right]$ intersect $\mathscr{N}_{M^{\prime}}(A)$ in sets of diameter at most $\delta_{0}$. The same argument can be used to show that $\tilde{q}\left[w, t_{-}\right]$and $\tilde{\mathfrak{q}}\left[t_{+}, z\right]$ intersect $\mathcal{N}_{M^{\prime}}(A)$ in sets of diameter at most $\delta_{0}^{\prime}=\delta_{0}^{\prime}\left(L^{\prime}, C^{\prime}, N_{1}\right)$. Corollary 8.14 implies that dist $S_{S}\left(s_{-}, t_{-}\right)$and $\operatorname{dist}_{S}\left(s_{+}, t_{+}\right)$are at most $D_{1}$, where $D_{1}=D_{1}\left(L^{\prime}, C^{\prime}, \delta_{0}, \delta_{0}^{\prime}\right)$.

### 8.3. The Morse lemma

Proposition 8.25 can be strengthened to the following statement.
Proposition 8.28. Let $\mathfrak{q}:[0, \ell] \rightarrow \operatorname{Cayley}(G, S)$ be an $(L, C)$-quasi-geodesic and let $\mathfrak{p}$ be a geodesic in Cayley ( $G, S \cup \mathscr{H}$ ) joining the endpoints of $\mathfrak{q}$. In Cayley $(G, S)$ the quasi-geodesic segment $\mathfrak{q}$ is contained in the T-tubular neighborhood of the M-saturation of the lift $\tilde{\mathfrak{p}}$ of $\mathfrak{p}$. Conversely, the lift $\tilde{\mathfrak{p}}$ is contained in the $T$-tubular neighborhood of the $M$-saturation of $\mathfrak{q}$. The constants $T$ and $M$ depend on $L, C$ and $S$.

Proof. According to Proposition 8.25, the Hausdorff distance from $\mathfrak{q}$ to $\mathfrak{p}$ in Cayley ( $G, S \cup \mathscr{H}$ ) is at most $\chi$. We divide $\mathfrak{p}$ into arcs of length $3(x+2)$, with the exception of the two arcs at the endpoints, which can be shorter. Let $s$ be one of these arcs. Consider $u$ on the sub-arc of $\mathfrak{p}$ between $\mathfrak{p}_{-}$and $s_{-}$such that either $\operatorname{dist}_{S \cup \mathscr{H}}\left(u, s_{-}\right)=\chi+2$ or $u=\mathfrak{p}_{-}$. Likewise let $v$ be a point on the sub-arc of $\mathfrak{p}$ between $s_{+}$and $\mathfrak{p}_{+}$such that either dist ${ }_{S \cup \mathscr{H}}\left(s_{+}, v\right)=\chi+2$ or $v=\mathfrak{p}_{+}$. Let $w$ and $z$ be two points on $\mathfrak{q}$ at distance at most $x$ from $u$ and $v$, respectively, in $\operatorname{Cayley}(G, S \cup \mathscr{H})$.

We repeat the argument from the proof of Proposition 8.27, Step I. Consider $\mathfrak{g}_{u w}$ and $\mathfrak{g}_{v z}$ geodesics in Cayley ( $G, S \cup \mathscr{H}$ ). Consider $u^{\prime}$ the farthest from $u$ point on $\mathfrak{g}_{u w}$ contained in the same left coset as an $\mathscr{H}$-component $\sigma$ of $\mathfrak{p}$. Likewise let $v^{\prime}$ be the farthest from $v$ point on $\mathfrak{g}_{v z}$ contained in the same left coset as an $\mathscr{H}$-component $\sigma^{\prime}$ of $\mathfrak{p}$. Then $\sigma$ does not intersect $s$, otherwise the distance from $u$ to $s$ in $\operatorname{Cayley}(G, S \cup \mathscr{H})$ would be at most $x+1$. Similarly, $\sigma^{\prime}$ does not intersect $s$.

Consider the path in $\operatorname{Cayley}(G, S \cup \mathscr{H})$ defined as $\mathfrak{r}=\mathfrak{g}_{w u^{\prime}} \sqcup \mathfrak{g}_{u^{\prime} \sigma_{+}} \sqcup \mathfrak{p}\left[\sigma_{+}, \sigma_{-}^{\prime}\right] \sqcup \mathfrak{g}_{\sigma_{-}^{\prime} v^{\prime}} \sqcup \mathfrak{g}_{v^{\prime} z}$, where $\mathfrak{g}_{w u^{\prime}}$ and $\mathfrak{g}_{v^{\prime} z}$ are sub-geodesics of $\mathfrak{g}_{w u}$ and $\mathfrak{g}_{v z}$, respectively, and $\mathfrak{g}_{u^{\prime} \sigma_{+}}$and $\mathfrak{g}_{\sigma_{-}^{\prime} v^{\prime}}$ are composed of one edge. It has no backtracking and its lift $\tilde{\mathfrak{r}}$ is an $\left(L^{\prime}, C^{\prime}\right)$-quasi-geodesic, where $L^{\prime}$ and $C^{\prime}$ depend on the length of $\mathfrak{r}$, and hence on $x$. It has the same endpoints as a sub-quasi-geodesic of $\mathfrak{q}$ of endpoints $w$ and $z$; hence it is contained in the $T$-tubular neighborhood of the $M$-saturation of it, where $M=M(L, C)$ and $T=T(L, C, x)$. In particular this is true for the lift of $s$. Since $s$ is arbitrary, we have obtained that the lift $\tilde{p}$ is contained in the $T$-tubular neighborhood of the $M$-saturation of $\mathfrak{q}$.

We now consider $\mathfrak{q}$ endowed with the order from $[0, \ell]$. We consider the path $\widehat{\mathfrak{q}}$ in Cayley $(G, S \cup \mathscr{H})$ obtained by deleting the part of $\mathfrak{q}$ between the first and the last point in $\mathfrak{q}$ contained in the same left coset, replacing it with an edge, and performing this successively for every coset intersecting $\mathfrak{q}$ in more than one point. Then, for a constant $D$ to be chosen later, we divide $\widehat{\mathfrak{q}}$ into $\operatorname{arcs} t$ such that $t_{+}$is the first vertex on $\widehat{\mathfrak{q}}$ (in the order inherited from $\mathfrak{q}$ ) which is at distance $D$ of $t_{-}$. We start constructing these arcs from $\mathfrak{q}_{-}$and we end in $\mathfrak{q}_{+}$by an arc which possibly has endpoints at distance smaller than $D$. Consider $t$ one of these arcs. Let $u$ be a point on $\mathfrak{q}$ between $\mathfrak{q}_{-}$and $t_{-}$with the property that it is at distance $\chi+2$ of $t$. If no such point exists, take $u=\mathfrak{q}_{-}$. Similarly, take $v$ a point on $\mathfrak{q}$ between $t_{+}$and $\mathfrak{q}_{+}$with the property that it is at distance $x+2$ of $t$, or $v=\mathfrak{q}_{+}$. There exist $w$ and $z$, respectively on $\mathfrak{p}$ at distance at most $x$ from $u$ and $v$. Then $\operatorname{dist}_{S \cup \mathscr{H}}(w, z) \leqslant 2 \chi+2(\varkappa+2)+6 D$. It follows that the lift $\tilde{\mathfrak{p}}_{w z}$ of the sub-geodesic $\mathfrak{p}_{w z}$ of $\mathfrak{p}$ of endpoints $w$ and $z$ is an $\left(L^{\prime \prime}, C^{\prime \prime}\right)$-quasi-geodesic, where $L^{\prime \prime}$ and $C^{\prime \prime}$ depend on $x$ and $D$.

As above we choose $u^{\prime} \in \mathfrak{g}_{u w}$ and $\sigma$ an $\mathscr{H}$-component of $\widehat{\mathfrak{q}}$ in the same left class as $u^{\prime}$. The choice of $u$ implies that $\sigma$ does not intersect $t$, otherwise $u$ would be at distance at most $\alpha+1$ of $t$. Likewise we choose $v^{\prime}$ and $\sigma^{\prime}$, and we construct the path $\mathfrak{r}^{\prime}=\mathfrak{g}_{w u^{\prime}} \sqcup \mathfrak{g}_{u^{\prime} \sigma_{+}} \sqcup \widehat{\mathfrak{q}}\left[\sigma_{+}, \sigma_{-}^{\prime}\right] \sqcup \mathfrak{g}_{\sigma_{-}^{\prime} v^{\prime}} \sqcup \mathfrak{g}_{v^{\prime} z}$ in Cayley $(G, S \cup \mathscr{H})$ of bounded length, with $\widehat{\mathfrak{q}}\left[\sigma_{+}, \sigma_{-}^{\prime}\right]$ containing $t$. As in the proof of Proposition 8.27, Step I, the subarcs $\mathfrak{r}^{\prime}\left[w, v^{\prime}\right]$ and $\mathfrak{r}^{\prime}\left[u^{\prime}, z\right]$ do not have backtracking. Suppose that $\mathfrak{g}_{w u^{\prime}}$ and $\mathfrak{g}_{v^{\prime} z}$ have $\mathscr{H}$-components in the same left coset. Let $w^{\prime}$ and $z^{\prime}$ be the nearest points to $u^{\prime}$ and, respectively $v^{\prime}$ contained in the same left coset.Lemma 8.12 implies that $\mathfrak{I}=\mathfrak{g}_{\sigma_{+} u^{\prime}} \sqcup \mathfrak{g}_{u^{\prime} w^{\prime}} \sqcup \mathfrak{g}_{w^{\prime} z^{\prime}} \sqcup \mathfrak{g}_{z^{\prime} v^{\prime}} \sqcup \mathfrak{g}_{v^{\prime} \sigma_{-}^{\prime}}$, which has length at most $2 x+3$, lifts to an $\left(L_{1}, C_{1}\right)$-quasi-geodesic, where $\left(L_{1}, C_{1}\right)$ depends on $\chi$. It follows that the sub-arc of $\mathfrak{q}$ between $\sigma_{+}$and $\sigma_{-}^{\prime}$ is contained in the $\tau$-neighborhood of the $M^{\prime}$-saturation of $\tilde{\mathscr{I}}$, where $M^{\prime}=M^{\prime}(\chi)$ and $\tau=\tau(\chi, L, C)$. It follows that the diameter of $\widehat{\mathfrak{q}}\left[\sigma_{+}, \sigma_{-}^{\prime}\right]$ is at most $2 \tau+2+2 M^{\prime}+$ length I. Hence $D \leqslant 2\left(\tau+1+M^{\prime}+x\right)+3$. Thus, if we take $D=2\left(\tau+1+M^{\prime}+x\right)+4$, we get a contradiction.

We conclude that $\mathfrak{r}^{\prime}$ has no backtracking, hence it lifts to a quasi-geodesic, by Lemma 8.12. We make a slight change when lifting it to a path $\tilde{\mathfrak{r}}^{\prime}$, in that the sub-arcs in $\widehat{\mathfrak{q}}$ are lifted to the corresponding sub-arcs of $\mathfrak{q}$. We obtain a quasi-geodesic $\tilde{\mathfrak{r}}^{\prime}$ with the same endpoints as $\tilde{\mathfrak{p}}_{w z}$, hence contained in the $T$ tubular neighborhood of the $M$-saturation of it, where $M=M(L, C, \chi)$ and $T=T(L, C, \chi)$. In particular this applies to the lift of $t$. Since $t$ was arbitrary, this allows one to obtain the desired statement for $\mathfrak{q}$ and $\tilde{p}$.

Proposition 8.28 together with Proposition 8.25 and Lemmas 4.25, 4.26, and 4.28 imply Theorem 1.12.

### 8.4. Undistorted subgroups and outer automorphisms of relatively hyperbolic groups

Theorem 8.29. Let $G=\langle S\rangle$ be a finitely generated group that is hyperbolic relative to subgroups $H_{1}, \ldots, H_{n}$. Let $G_{1}=\left\langle S_{1}\right\rangle$ be an undistorted finitely generated subgroup of $G$. Then $G_{1}$ is relatively hyperbolic with respect to subgroups $H_{1}^{\prime}, \ldots, H_{m}^{\prime}$, where each $H_{i}^{\prime}$ is one of the intersections $G_{1} \cap g H_{j} g^{-1}$, $g \in G$.

Proof. Since $G_{1}$ is undistorted, there exists a constant $D \geqslant 1$ such that for every element $g \in G_{1}$, $|g|_{S_{1}} \leqslant D|g|_{S}$. Here by $|g|_{S}$ and $|g|_{S_{1}}$ we denote the length of $g$ in $G$ and $G_{1}$, respectively. We can assume that $S_{1} \subseteq S$ so that the graph Cayley $\left(G_{1}, S_{1}\right)$ is inside Cayley $(G, S)$. Then every geodesic in Cayley $\left(G_{1}, S_{1}\right)$ is a ( $D, 0$ )-quasi-geodesic of Cayley $(G, S)$.

Step I. Let us prove that for every coset $g H_{i}$ and every constant $C>0$ there exists $C^{\prime}=C^{\prime}(C, g, i)>0$ such that $G_{1} \cap \mathscr{N}_{C}\left(g H_{i}\right) \subseteq \mathscr{N}_{C^{\prime}}\left(G_{1} \cap g H_{i} g^{-1}\right)$. By contradiction, let $\left(x_{j}\right)_{j \in \mathbb{N}}$ be a sequence of elements in $G_{1}$ such that $x_{j}=g h_{j} p_{j} \in G_{1}, h_{j} \in H_{i},\left|p_{j}\right|_{S}<C$, and $\operatorname{dist}\left(x_{j}, G_{1} \cap g H_{i} g^{-1}\right) \geqslant j$ for every $j$. Without loss of generality we can assume that $p_{j}=p$ is constant. Then $x_{j} x_{1}^{-1} \in G_{1} \cap g H_{i} g^{-1}$. Hence $\operatorname{dist}\left(x_{j}, G_{1} \cap g H_{i} g^{-1}\right) \leqslant\left|x_{1}\right| s$, a contradiction.

Step II. Let $R>0$ and let $g H_{i}$ be such that $\mathcal{N}_{R}\left(g H_{i}\right) \cap G_{1} \neq \emptyset$.
We prove that for every $K>0$ there exists $K^{\prime}=K^{\prime}(K, R)$ such that

$$
G_{1} \cap \mathscr{N}_{K}\left(g H_{i}\right) \subset \mathscr{N}_{K^{\prime}}\left(G_{1} \cap g_{1} \gamma H_{i} \gamma^{-1}\right)
$$

for some $g_{1} \in G_{1}$ and some $\gamma \in G$ with $|\gamma|_{S} \leqslant R$.
Fix $K>0$ and define $K^{\prime}$ as the maximum of numbers $C^{\prime}(K, \gamma, i)$ defined in Step I taken over all $i \in\{1,2, \ldots, n\}$ and all $\gamma \in G$ with $|\gamma|_{S} \leqslant R$.

Let $g \in G$ be such that $G_{1} \cap \mathscr{N}_{R}\left(g H_{i}\right) \neq \emptyset$. Let $g_{1}$ be an element of the intersection. Then $g_{1}^{-1} \mathscr{N}_{R}\left(g H_{i}\right)=\mathscr{N}_{R}\left(g_{1}^{-1} g H_{i}\right)$ contains 1; hence $g_{1}^{-1} g H_{i}=\gamma H_{i}$ where $|\gamma| S \leqslant R$.

Step I and the choice of $K^{\prime}$ imply that

$$
G_{1} \cap \mathscr{N}_{K}\left(\gamma H_{i}\right) \subset \mathscr{N}_{K^{\prime}}\left(G_{1} \cap \gamma H_{i} \gamma^{-1}\right)
$$

Multiplying this inclusion by $g_{1}$ on the left, we obtain

$$
G_{1} \cap \mathscr{N}_{K}\left(g H_{i}\right) \subset \mathscr{N}_{K^{\prime}}\left(G_{1} \cap g_{1} \gamma H_{i} \gamma^{-1}\right)
$$

Step III. Let $R=M\left(D, 0, \frac{1}{3}\right)$ be the constant given by the property $\left(\alpha_{2}^{\prime}\right)$ satisfied by the left cosets $\left\{g H_{i} \mid g \in G, i=1,2, \ldots, n\right\}$ in Cayley $(G, S)$.

For every $i \in\{1, \ldots, n\}$ consider the following equivalence relation on the ball $B(1, R)$ in $G$ :

$$
\gamma \sim_{i} \gamma^{\prime} \quad \text { iff } \quad G_{1} \gamma H_{i}=G_{1} \gamma^{\prime} H_{i}
$$

For each pair $\left(\gamma, \gamma^{\prime}\right)$ of $\sim_{i}$-equivalent elements in $B(1, R)$ we choose one $g_{1} \in G_{1}$ such that $\gamma \in g_{1} \gamma^{\prime} H_{i}$. Let $\tilde{C}$ be the maximal length of these elements $g_{1}$.

Let $\mathscr{M}$ be the collection of all non-trivial subgroups of $G_{1}$ in the set

$$
\left\{G_{1} \cap \gamma H_{i} \gamma^{-1}\left|i \in\{1,2, \ldots, n\},|\gamma|_{S} \leqslant R\right\} .\right.
$$

By Step II, this collection of subgroups has the property that for every $K>0$ there exists $K^{\prime}=K^{\prime}(K, R)$ such that for every $g \in G$ with $\mathscr{N}_{R}\left(g H_{i}\right) \cap G_{1} \neq \emptyset$, we have

$$
\begin{equation*}
G_{1} \cap \mathscr{N}_{K}\left(g H_{i}\right) \subset \mathscr{N}_{K^{\prime}}\left(g_{1} H\right) \tag{29}
\end{equation*}
$$

for some $g_{1} \in G_{1}$ and $H \in \mathscr{M}$.
We say that two non-trivial subgroups $G_{1} \cap \gamma H_{i} \gamma^{-1}$ and $G_{1} \cap \beta H_{i} \beta^{-1}$ from $\mathscr{M}$ are equivalent if $\gamma \sim_{i} \beta$.
Let $H_{1}^{\prime}, \ldots, H_{m}^{\prime}$ be the set of representatives of equivalent classes in $\mathscr{M}$. If $\mathscr{M}$ is empty, we set $m=1$, $H_{1}^{\prime}=\{1\}$.

Notice that for every $H \in \mathscr{M}$ there exists $j \in\{1, \ldots, m\}$ such that $H$ is at Hausdorff distance at most $\tilde{C}$ from a left coset $g H_{j}^{\prime}$ from $G_{1}$. Indeed, $H=\gamma H_{i} \gamma^{-1} \cap G_{1}$. Let $H_{j}^{\prime}=\beta H_{i} \beta^{-1} \cap G_{1}$ be equivalent to $H$. Then $\gamma=g \beta h$ for some $g \in G_{1}, h \in H_{i}$, where $|g| \leqslant \tilde{C}$. Then

$$
H=g \beta h H_{i} h^{-1} \beta^{-1} g^{-1} \cap G_{1}=g H_{j}^{\prime} g^{-1}
$$

from which we deduce that $H$ is at Hausdorff distance at most $\tilde{C}$ from $g H_{j}^{\prime}$.
Hence (29) remains true if we replace $\mathscr{M}$ by the smaller set $\left\{H_{1}^{\prime}, \ldots, H_{m}^{\prime}\right\}$ and $K^{\prime}$ by $K^{\prime}+\tilde{C}$.
We shall prove that $G_{1}$ is relatively hyperbolic with respect to $\left\{H_{1}^{\prime}, \ldots, H_{m}^{\prime}\right\}$ by checking properties $\left(\alpha_{1}\right),\left(\alpha_{2}^{1 / 6 D}\right),\left(\alpha_{3}\right)$ from Theorem 4.1 and Remark 4.2 for the collection of left cosets $\left\{g_{1} H_{j}^{\prime} \mid g_{1} \in\right.$ $\left.G_{1}, j=1,2, \ldots, m\right\}$.

Property $\left(\alpha_{1}\right)$. Consider $g_{1} H_{j}^{\prime} \neq g_{1}^{\prime} H_{k}^{\prime}$. We have that

$$
\begin{aligned}
\mathscr{N}_{\delta}\left(g_{1} H_{j}^{\prime}\right) \cap \mathscr{N}_{\delta}\left(g_{1}^{\prime} H_{k}^{\prime}\right) & \subset \mathscr{N}_{\delta}\left(g_{1} \gamma H_{i_{j}} \gamma^{-1}\right) \cap \mathscr{N}_{\delta}\left(g_{1}^{\prime} \gamma^{\prime} H_{i_{k}}\left(\gamma^{\prime}\right)^{-1}\right) \\
& \subset \mathscr{N}_{\delta+R}\left(g_{1} \gamma H_{i_{j}}\right) \cap \mathscr{N}_{\delta+R}\left(g_{1}^{\prime} \gamma^{\prime} H_{i_{k}}\right)
\end{aligned}
$$

Suppose that $g_{1} \gamma H_{i_{j}}=g_{1}^{\prime} \gamma^{\prime} H_{i_{k}}$. Then $\left(g_{1} \gamma\right)^{-1} g_{1}^{\prime} \gamma^{\prime} \in H_{i_{j}}$ and hence $g_{1} \gamma H_{i_{j}}=g_{1}^{\prime} \gamma^{\prime} H_{i_{j}}$. We deduce that $H_{i_{j}}=H_{i_{k}}$. Therefore $g_{1} \gamma=g_{1}^{\prime} \gamma^{\prime} h$ for some $h \in H_{i_{j}}$. Hence $\gamma \sim_{i_{j}} \gamma^{\prime}$, so $\gamma=\gamma^{\prime}$. We deduce that $g_{1} \gamma H_{i_{j}} \gamma^{-1}=g_{1}^{\prime} \gamma H_{i_{j}} \gamma^{-1}$. So $g_{1} H_{j}^{\prime}=g_{1}^{\prime} H_{k}^{\prime}$, a contradiction.

Thus, $g_{1} \gamma H_{i_{j}} \neq g_{1}^{\prime} \gamma^{\prime} H_{i_{k}}$. Property $\left(\alpha_{1}\right)$ satisfied by the left cosets $\left\{g H_{i} \mid g \in G, i=1,2, \ldots, n\right\}$ allows one to complete the proof.

Property $\left(\alpha_{2}^{1 / 6 D}\right)$. Let $\theta_{1} \in[0,1 / 6 D)$. We may write $\theta_{1}(\theta / D)$, with $\theta \in\left[0, \frac{1}{6}\right)$. Let $\mathfrak{g}:[0, \ell] \rightarrow$ Cayley $\left(G_{1}, S_{1}\right)$ be a geodesic of length $\ell$ in Cayley $\left(G_{1}, S_{1}\right)$ with endpoints in $\mathcal{N}_{\theta_{1} \ell}\left(g_{1} H_{j}^{\prime}\right) \subset \mathcal{N}_{\theta_{1} \ell+R}$ $\left(g_{1} \gamma H_{i}\right)$, where $|\gamma|_{S} \leqslant R$ and $i \in\{1,2, \ldots, n\}$. Then $\mathfrak{g}$ is a $(D, 0)$-quasi-geodesic in Cayley $(G, S)$.

Suppose that $\ell \leqslant 6 D R$. Then $\mathfrak{g}$ is contained in the $(3 D R+R)$-tubular neighborhood of $g_{1} H_{j}^{\prime}$ in $\operatorname{Cayley}\left(G_{1}, S_{1}\right)$.

Suppose that $\ell>6 D R$. Then the endpoints of $\mathfrak{g}$ are contained in $\mathscr{N}_{(\theta+1 / 6) \ell / D}\left(g_{1} \gamma H_{i}\right) \subset \mathcal{N}_{(1 / 3) \ell / D}$ $\left(g_{1} \gamma H_{i}\right)$ in Cayley $(G, S)$. Since the property $\left(\alpha_{2}^{\prime}\right)$ is satisfied by the cosets of $H_{i}$ in $G$, it follows that $\mathfrak{g}$ intersects $\mathscr{N}_{R}\left(g_{1} \gamma H_{i}\right)$. Hence $g$ intersects $G_{1} \cap \mathscr{N}_{R}\left(g_{1} \gamma H_{i}\right)=g_{1}\left[G_{1} \cap \mathscr{N}_{R}\left(\gamma H_{i}\right)\right] \subset g_{1} \mathscr{N}_{R^{\prime}}\left(H_{j}^{\prime}\right)$ where $R^{\prime}=R^{\prime}(R, R)$ is given by Step II.

We conclude that $\mathfrak{g}$ intersects $\mathscr{N}_{M^{\prime}}\left(g_{1} H_{j}^{\prime}\right)$ in Cayley $\left(G_{1}, S_{1}\right)$, for $M^{\prime}=\sup \left(D R^{\prime}, 3 D R+R\right)$.
Property $\left(\alpha_{3}\right)$. We use the property (29) of $\left\{H_{1}^{\prime}, \ldots, H_{m}^{\prime}\right\}$ and the property $\left(\alpha_{3}^{\prime}\right)$ satisfied by the cosets of groups $H_{i}$.

Fix an integer $k \geqslant 2$. Let $P$ be a $(\vartheta, 2,8 D)$-fat geodesic $k$-gon in Cayley $\left(G_{1}, S_{1}\right)$ for some $\vartheta$. Then $P$ has $(D, 0)$-quasi-geodesic sides in Cayley $(G, S)$ and it is $(\vartheta / D, 2 D, 8 D)$-fat. Consequently, for $\vartheta$ large enough, by property $\left(\alpha_{3}^{\prime}\right)$ satisfied by the left cosets $\left\{g H_{i} \mid g \in G, i=1, \ldots, n\right\}$, the $k$-gon $P$ is contained in a tubular neighborhood $\mathcal{N}_{\chi}\left(g H_{i}\right)$ in Cayley $(G, S)$ for some $\chi>0$.

Suppose that all edges of $P$ have lengths at most $3 D \chi$ in Cayley $\left(G_{1}, S_{1}\right)$. Then $P$ has diameter at most $3 k D x$ in the same Cayley graph.

Suppose that one edge $\mathfrak{g}$ of $P$ has length at least $3 D \chi$. The fact that $P \subset \mathcal{N}_{\chi}\left(g H_{i}\right)$ and property $\left(\alpha_{2}^{\prime}\right)$ is satisfied by the left cosets $\left\{g H_{i}\right\}$ implies that $\mathfrak{g}$ intersects $\mathscr{N}_{R}\left(g H_{i}\right)$; therefore $\mathcal{N}_{R}\left(g H_{i}\right) \cap$ $G_{1} \neq \emptyset$.

Then by (29) there exists $\chi^{\prime}=\chi^{\prime}(\chi, R)$ such that

$$
G_{1} \cap \mathscr{N}_{\chi}\left(g H_{i}\right) \subset \mathscr{N}_{x^{\prime}}\left(g_{1} H_{j}^{\prime}\right)
$$

for some $g_{1} \in G_{1}$ and $j \in\{1,2, \ldots, m\}$. We conclude that in this case $P \subset \mathcal{N}_{x^{\prime}}\left(g_{1} H_{j}^{\prime}\right)$.
Thus we can take $\xi$ needed in $\left(\alpha_{3}\right)$ to be the maximum of $3 k D \chi$ and $\chi^{\prime}$.

Remark 8.30. (1) If in Theorem 8.29 the subgroup $G_{1}$ is unconstricted then $G_{1}$ is inside a conjugate of one of the subgroups $H_{i}$.
(2) If the subgroup $G_{1}$ intersects with all conjugates of the subgroups $H_{1}, \ldots, H_{n}$ by hyperbolic subgroups then $G_{1}$ is hyperbolic.

Proof. (1) Indeed, Corollary 5.8 implies that $G_{1}$ is contained in the $K$-tubular neighborhood of a left coset $g H_{i}$, where $K$ depends only on the non-distortion constants. For every $g_{1} \in G_{1}, G_{1}=g_{1} G_{1}$ is contained in the $K$-tubular neighborhoods of $g_{1} g H_{i}$ and of $g H_{i}$. Since $G_{1}$ is infinite, property ( $\alpha_{1}$ ) implies that $g_{1} g H_{i}=g H_{i}$. We conclude that $G_{1}$ is contained in $g H_{i} g^{-1}$.
(2) By Theorem $8.29 G_{1}$ is relatively hyperbolic with respect to hyperbolic subgroups, so every asymptotic cone of $G_{1}$ is tree-graded with respect to $\mathbb{R}$-trees, whence it is an $\mathbb{R}$-tree itself. Therefore $G_{1}$ is hyperbolic [30].

Corollary 8.31. Let $G$ be a finitely generated group that is relatively hyperbolic with respect to subgroups $H_{1}, \ldots, H_{m}$. Suppose that $H_{1}$ is unconstricted and that each $H_{i}, i \in\{2, \ldots, m\}$, is infinite and either unconstricted or does not contain a copy of $H_{1}$. Let $\mathrm{Fix}\left(\mathrm{H}_{1}\right)$ be the subgroup of the automorphism group of $G$ consisting of the automorphisms that fix $H_{1}$ as a set. Then:
(1) Inn $(G) \operatorname{Fix}\left(H_{1}\right)$ has index at most $m!$ in $\operatorname{Aut}(G)$ (in particular, ifm $=1$, these two subgroups coincide).
(2) $\operatorname{Inn}(G) \cap \operatorname{Fix}\left(H_{1}\right)=\operatorname{Inn}_{H_{1}}(G)$, where $\operatorname{Inn}_{H_{1}}(G)$ is by definition $\left\{i_{h} \in \operatorname{Inn}(G) \mid h \in H_{1}\right\}$.
(3) There exists a natural homomorphism from a subgroup of index at most m! in $\operatorname{Out}(G)$ to $\operatorname{Out}\left(H_{1}\right)$ given by $\left.\phi \mapsto i_{g_{\phi}} \phi\right|_{H_{1}}$, where $g_{\phi}$ is an element of $G$ such that $i_{g_{\phi}} \phi \in \operatorname{Fix}\left(H_{1}\right)$, and $\left.\right|_{H_{1}}$ denotes the restriction of the automorphism to $H_{1}$.

Proof. (1) Indeed, every automorphism $\phi$ of $G$ is a quasi-isometry of the Cayley graph of $G$. Hence $\phi\left(H_{1}\right)$ is an undistorted subgroup of $G$ that is isomorphic to $H_{1}$. By Remark 8.30(1), we have that $\phi\left(H_{1}\right) \subset g H_{j} g^{-1}$ for some $g \in G$ and $j \in\{1,2, \ldots, m\}$. In particular $i_{g}^{-1} \phi\left(H_{1}\right) \subset H_{j}$. By hypothesis $H_{j}$ is unconstricted. If we denote by $\psi$ the automorphism $i_{g}^{-1} \phi$, we have that $\psi^{-1}\left(H_{j}\right) \subset \gamma H_{k} \gamma^{-1}$, for some $\gamma \in G$ and $k \in\{1,2, \ldots, m\}$. Consequently $H_{1} \subset \gamma H_{k} \gamma^{-1}$. We deduce from the fact that $H_{1}$ is infinite and from property $\left(\alpha_{1}\right)$ that $H_{1}=\gamma H_{k} \gamma^{-1}$ and $i_{g}^{-1} \phi\left(H_{1}\right)=H_{j}$. In particular every automorphism of $G$ induces a permutation of the set
$\left\{H_{i} \mid H_{i}\right.$ is isomorphic to $\left.H_{1}\right\}$.
Therefore we have an action of $\operatorname{Aut}(G)$ on a subset of $\left\{H_{1}, \ldots, H_{m}\right\}$. Let $S$ be the kernel of this action. Then $|\operatorname{Aut}(G): S| \leqslant m!$. The composition of any $\phi \in S$ with an inner automorphism $i_{g}^{-1}$ induced by $g^{-1}$ is in $\operatorname{Fix}\left(H_{1}\right)$. Therefore $S$ is contained in $\operatorname{Inn}(G) \operatorname{Fix}\left(H_{1}\right)$.
(2) Let $i_{g}$ be an element in $\operatorname{Inn}(G) \cap \operatorname{Fix}\left(H_{1}\right)$. Then $g$ normalizes $H_{1}$; hence by [43], $g \in H_{1}$.
(3) This immediately follows from (1) and (2).

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## Appendix A. Relatively hyperbolic groups are asymptotically tree-graded. By Denis Osin and Mark Sapir

Here we prove the "if" statement in Theorem 8.5.
Theorem A.1. Let $G$ be a group generated by a finite set $S$, that is relatively hyperbolic with respect to finitely generated subgroups $H_{1}, \ldots, H_{m}$. Then $G$ is asymptotically tree-graded with respect to these subgroups.

Throughout the rest of this section we assume that $G, H_{1}, \ldots, H_{m}$, an ultrafilter $\omega$, and a sequence of numbers $d=\left(d_{i}\right)$ are fixed, $G$ is generated by a finite set $S$ and is hyperbolic relative to $H_{1}, \ldots, H_{m}$. We denote the asymptotic cone $\operatorname{Con}^{\omega}(G ; e, d)$ by $C$.

If $\left(g_{i}\right),\left(h_{i}\right)$ are sequences of numbers, we shall write $g_{i} \leqslant \omega h_{i}$ instead of " $g_{i} \leqslant h_{i} \omega$-almost surely". The signs $=\omega, \epsilon_{\omega}$ have similar meanings.

As before, $\mathscr{H}=\left(\bigcup_{i=1}^{m} H_{i}\right) \backslash\{e\}$. For every $i=1, \ldots, m$, in every coset of $H_{i}(i=1, \ldots, m)$ we choose a smallest length representative. The set of these representatives is denoted by $T_{i}$. Let $\mathscr{T}_{i}$ be the set $\left\{\left(g_{j}\right)^{\omega} \mid \lim ^{\omega}\left(\left|g_{i}\right|_{S}\right)<\infty\right\}$. For each $\gamma=\left(g_{j}\right)^{\omega} \in \mathscr{T}_{i}$ we denote by $M_{\gamma}$ the $\omega$-limit lim ${ }^{\omega}\left(g_{j} H_{i}\right)_{e}$. We need to show that $C$ is tree-graded with respect to all $\mathscr{P}=\left\{M_{\gamma} \mid \gamma \in \mathscr{T}_{i}, i=1, \ldots, m\right\}$.

We use the notation dist $_{S}$ and dist ${ }_{S \cup H}$ for combinatorial metrics on Cayley $(G, S)$ and Cayley ( $G$, $S \cup \mathscr{H})$. When speaking about geodesics in Cayley $(G, S \cup \mathscr{H})$ we always assume them to be geodesic with respect to dist ${ }_{S \cup H}$.

The lemma below can be found in [43, Theorem 3.23].
Lemma A.2. There exists a constant $v>0$ such that the following condition holds. Let $\Delta=$ pqr be a geodesic triangle in $\operatorname{Cayley}(G, S \cup \mathscr{H})$ whose sides are geodesic (with respect to the metric dist ${ }_{S \cup \mathscr{H}}$ ). Then for any vertex $v$ on $p$, there exists a vertex $u$ on the union $q \cup r$ such that

$$
\operatorname{dist}_{S}(u, v) \leqslant v
$$

Lemma A.3. Let $p$ and $q$ be paths in Cayley $(G, S \cup \mathscr{H})$ such that $p_{-}=q_{-}, p_{+}=q_{+}$, and $q$ is geodesic. Then for any vertex $v \in q$, there exists a vertex $u \in p$ such that

$$
\operatorname{dist}_{S}(u, v) \leqslant(1+v) \log _{2}|p|
$$

Proof. Let $f: \mathbb{N} \rightarrow \mathbb{N}$ be the smallest function such that the following condition holds. Let $p$ and $q$ be paths in $\operatorname{Cayley}(G, S \cup \mathscr{H})$ such that $p_{-}=q_{-}, p_{+}=q_{+}, q$ is geodesic, and $|p| \leqslant n$. Then for any vertex $v \in q$, there exists a vertex $u \in p$ such that $\operatorname{dist}_{S}(u, v) \leqslant f(n)$. Clearly $f(n)$ is finite for each value of the argument. By dividing $p$ into two parts and applying Lemma A.2, we obtain $f(m+$ $n) \leqslant \max \{f(m), f(n)\}+v$. In particular, $f(2 n) \leqslant f(n)+v$ and $f(n+1) \leqslant f(n)+v$.

Suppose that

$$
n=\varepsilon_{0}+2 \varepsilon_{1}+\cdots+2^{k} \varepsilon_{k}
$$

where $\varepsilon_{i} \in\{0,1\}$ and $\varepsilon_{k}=1$. Then

$$
\begin{aligned}
f(n) & =f\left(\varepsilon_{0}+2\left(\varepsilon_{1}+\cdots+2\left(\varepsilon_{k-1}+2\right) \ldots\right)\right) \\
& \leqslant \underbrace{v+v+\cdots+v}_{2 k \text { times }}+f(1) \leqslant 2 v \log _{2} n .
\end{aligned}
$$

The next lemma can be found in [43, Lemma 3.1].

Lemma A.4. There is a constant $\alpha$ such that for any cycle q in Cayley ( $G, S \cup \mathscr{H}$ ), and any set of isolated $\mathscr{H}$-components of $p_{1}, \ldots, p_{k}$ of $q$, we have

$$
\sum_{i=1}^{k} \operatorname{dist}_{S}\left(\left(p_{i}\right)_{-},\left(p_{i}\right)_{+}\right) \leqslant \alpha|q| .
$$

The following lemma holds for any (not necessarily relatively hyperbolic) finitely generated group $G$ and any subgroup $H \leqslant G$.

Lemma A.5. For any $i=1, \ldots, m, \theta, \sigma \in \mathscr{T}_{i}$, if $\theta \neq \sigma$ then the intersection $M_{\theta} \cap M_{\sigma}$ consists of at most 1 point.

Proof. Suppose that $x, y \in M_{\theta} \cap M_{\sigma}$. Suppose that $\theta=\left(f_{j}\right)^{\omega}, \sigma=\left(g_{j}\right)^{\omega}$. Then

$$
x=\lim ^{\omega}\left(f_{j} a_{j}\right), \quad y=\lim ^{\omega}\left(f_{j} s_{j}\right)
$$

for some $a_{j}, s_{j} \in H_{i}$ and

$$
x=\lim ^{\omega}\left(g_{j} b_{j}\right), \quad y=\lim ^{\omega}\left(g_{j} t_{j}\right)
$$

for some $b_{j}, t_{j} \in H_{i}$. Since the sequences $\left(f_{j} a_{j}\right)^{\omega}$ and $\left(g_{j} b_{j}\right)^{\omega}$ are equivalent, we have $f_{j} a_{j}=$ $g_{j} b_{j} u_{j}$, where $\left|u_{j}\right| S={ }_{\omega} o\left(d_{j}\right)$. Similarly $f_{j} s_{j}=g_{j} t_{j} v_{j}$, where $\left|v_{j}\right|_{S}={ }_{\omega} o\left(d_{j}\right)$. From these equalities we have

$$
a_{j}^{-1} s_{j}=u_{j}^{-1} b_{j}^{-1} t_{j} v_{i} .
$$

Let $U_{j}, V_{j}$ be the shortest words over $S$ representing $u_{j}$ and $v_{j}$, respectively. Let also $h_{j}=a_{j}^{-1} s_{i}$ and $k_{j}=b_{j}^{-1} t_{j}$. Then there exists a quadrangle

$$
q^{j}=p_{1}^{j} p_{2}^{j} p_{3}^{j} p_{4}^{j}
$$

in Cayley $(G, S)$ such that $\phi\left(p_{1}^{j}\right) \equiv U_{i}, \phi\left(p_{3}^{j}\right) \equiv V_{j}^{-1}$ and $p_{2}^{j}, p_{4}^{j}$ are edges of Cayley $(G, S)$ labelled $h_{j}$ and $k_{j}^{-1}$, respectively. Note that the cycle $q^{j}$ contains only two components, namely, $p_{2}^{j}$ and $p_{4}^{j}$, as the labels of $p_{1}^{j}$ and $p_{3}^{j}$ are words over $S$. Let $A \subseteq \mathbb{N}$ be the set of all $j$ such that the components $p_{2}^{j}$ and $p_{4}^{j}$ are connected. There are two cases to consider.

Case 1. $\omega(A)=1$. Note that $\phi\left(p_{1}^{j}\right)$ represents an element of $H_{i}$ in $G$ for any $j \in A$, i.e. $s_{j} \in_{\omega} H_{i}$. It follows that $\theta=\sigma$.

Case 2. $\omega(A)=0$. Note that $p_{2}^{j}$ is an isolated component of $q^{j}$ for any $j \in \mathbb{N} \backslash A$. Since $\omega(\mathbb{N} \backslash A)=1$, applying Lemma A.4, we obtain

$$
\left|h_{j}\right| S=\operatorname{dist}_{S}\left(\left(p_{2}\right)_{-},\left(p_{2}\right)_{+}\right) \leqslant \alpha\left|q^{j}\right| \leqslant \omega_{\omega} \alpha\left(2+2 o\left(d_{j}\right)\right)=o\left(d_{j}\right) .
$$

This yields

$$
\operatorname{dist}(x, y)=\lim ^{\omega}\left(\frac{1}{d_{j}} \operatorname{dist}_{S}\left(f_{j} a_{j}, f_{j} s_{j}\right)\right)=\lim ^{\omega}\left(\frac{1}{d_{j}}\left|h_{j}\right| S\right)=0
$$

i.e. $x=y$.

The following lemma does use the relative hyperbolicity of $G$.
Lemma A.6. For every $i \neq i^{\prime}$ and every $\theta \in \mathscr{T}_{i}, \sigma \in \mathscr{T}_{i^{\prime}}$, the intersection $M_{\theta} \cap M_{\sigma}$ consists of at most 1 point.

Proof. Indeed, repeating the argument from the proof of Lemma A.5, we immediately get contradiction with the BCP property.

Lemmas A. 5 and A. 6 show that the asymptotic cone $C$ satisfies property $\left(T_{1}\right)$ with respect to the set $\mathscr{P}$. Now we are going to prove $\left(T_{2}\right)$.

Lemma A.7. Let $\mathfrak{g}$ be a simple loop in C. Suppose that $\mathfrak{g}=\lim ^{\omega}\left(\mathfrak{g}_{j}\right)$ for certain loops $\mathfrak{g}_{j}$ in Cayley $(G, S)$, $\left|\mathfrak{g}_{j}\right| \leqslant C d_{j}$ for some constant $C$. Then there exists $i=1, \ldots, m$ and $\theta \in \mathscr{T}_{i}$ such that $\mathfrak{g}$ belongs to $M_{\theta}$.

Proof. Let $a \neq b$ be two arbitrary points of $\mathfrak{g}$,

$$
a=\lim ^{\omega}\left(a_{j}\right), \quad b=\lim ^{\omega}\left(b_{j}\right)
$$

where $a_{j}, b_{j}$ are vertices on $\mathfrak{g}_{j}$. For every $j$, we consider a geodesic path $\mathfrak{q}_{j}$ in Cayley $(G, S \cup \mathscr{H})$ such that $\left(\mathfrak{q}_{j}\right)_{-}=a_{j},\left(\mathfrak{q}_{j}\right)_{+}=b_{j}$.

According to Lemma A.3, for every vertex $v \in \mathfrak{q}_{j}$, there exist vertices $x_{j}=x_{j}(v) \in \mathfrak{g}_{j}\left[a_{j}, b_{j}\right]$ and $y_{j}=y_{j}(v) \in \mathfrak{g}_{j}\left[b_{j}, a_{j}\right]$ (here $\mathfrak{g}_{j}\left[a_{j}, b_{j}\right]$ and $\mathfrak{g}_{j}\left[b_{j}, a_{j}\right]$ are segments of $\mathfrak{g}_{j}=\mathfrak{g}_{j}\left[a_{j}, b_{j}\right] \mathfrak{g}_{j}\left[b_{j}, a_{j}\right]$ ) such that

$$
\begin{equation*}
\operatorname{dist}_{S}\left(v, x_{j}\right) \leqslant 2 v \log _{2}\left|\mathfrak{g}_{j}\left[a_{j}, b_{j}\right]\right|<2 v \log _{2}\left(C d_{j}\right)=o\left(d_{j}\right) \tag{30}
\end{equation*}
$$

and similarly

$$
\begin{equation*}
\operatorname{dist}_{S}\left(v, y_{j}\right) \leqslant 2 v \log _{2}\left|\mathfrak{g}_{j}\left[b_{j}, a_{j}\right]\right|<2 v \log _{2}\left(C d_{j}\right)=o\left(d_{j}\right) \tag{31}
\end{equation*}
$$

Summing (30) and (31), we obtain

$$
\operatorname{dist}_{S}\left(x_{j}, y_{j}\right) \leqslant \operatorname{dist}_{S}\left(x_{j}, v\right)+\operatorname{dist}_{S}\left(v, y_{j}\right)=o\left(d_{j}\right)
$$

Thus for any $j$, there are only two possibilities: either $\lim ^{\omega}\left(x_{j}\right)=\lim ^{\omega}\left(y_{j}\right)=a$ or $\lim ^{\omega}\left(x_{j}\right)=\lim ^{\omega}\left(y_{j}\right)=b$, otherwise the loop $\mathfrak{g}$ is not simple.

For every $j$, we take two vertices $v_{j}, w_{j} \in \mathfrak{q}_{j}$ such that

$$
\begin{aligned}
& \lim ^{\omega}\left(x_{j}\left(v_{j}\right)\right)=\lim ^{\omega}\left(y_{j}\left(v_{j}\right)\right)=a \\
& \lim ^{\omega}\left(x_{j}\left(w_{j}\right)\right)=\lim ^{\omega}\left(y_{j}\left(w_{j}\right)\right)=b
\end{aligned}
$$

and $\operatorname{dist}_{S \cup H}\left(v_{j}, w_{j}\right)=1$. Since $\lim ^{\omega}\left(x_{j}\left(v_{j}\right)\right)=a$, we have $\operatorname{dist}_{S}\left(x_{j}\left(v_{j}\right), a\right)={ }_{\omega} o\left(d_{j}\right)$. Hence

$$
\operatorname{dist}_{S}\left(v_{j}, a_{j}\right) \leqslant \operatorname{dist}_{S}\left(v_{j}, x_{j}\left(v_{j}\right)\right)+\operatorname{dist}_{S}\left(x_{j}\left(v_{j}\right), a_{j}\right)=_{\omega} o\left(d_{j}\right)
$$

Similarly,

$$
\operatorname{dist}_{S}\left(w_{j}, b\right)={ }_{\omega} o\left(d_{j}\right)
$$

This means that

$$
\begin{equation*}
\lim ^{\omega}\left(a_{j}\right)=\lim ^{\omega}\left(v_{j}\right) \quad \text { and } \quad \lim ^{\omega}\left(b_{j}\right)=\lim ^{\omega}\left(w_{j}\right) \tag{32}
\end{equation*}
$$

For every $i=1, \ldots, m$, set $A_{i}=\left\{j \in \mathbb{N} \mid v_{j}^{-1} w_{j} \in H_{i}\right\}$. Let us consider two cases.
Case 1. $\omega\left(A_{i}\right)=1$ for some $i$. Set $\theta=\left(t_{i}\left(v_{j}\right)\right)^{\omega} \in \mathscr{T}_{i}$ where $t_{i}\left(v_{j}\right)$ is the representative of the coset $v_{j} H_{i}$ chosen in the definition of $\mathscr{T}_{i}$. Then $a, b \in_{\omega} M_{\theta}$. Indeed, this is obvious for $a$ since $\lim ^{\omega}\left(a_{j}\right)=\lim ^{\omega}\left(v_{j}\right) \in$ $M_{\theta}$. Further, since $v_{j}^{-1} w_{j} \in_{\omega} H_{i}$, we have $t\left(w_{j}\right)={ }_{\omega} t\left(v_{j}\right)$. Hence $\lim ^{\omega}\left(b_{j}\right)=\lim ^{\omega}\left(w_{j}\right) \in M_{\theta}$.

Case 2. $\omega\left(A_{i}\right)=0$ for every $i$. Recall that $v_{j}^{-1} w_{j} \in S \cup \mathscr{H}$. Thus we have $v_{j}^{-1} w_{j} \in_{\omega} S$. This implies $\left|v_{j}^{-1} w_{j}\right|_{S}={ }_{\omega} 1$ and $\lim ^{\omega}\left(v_{j}\right)=\lim ^{\omega}\left(w_{j}\right)$. Taking into account (32), we obtain $\lim ^{\omega}\left(a_{j}\right)=\lim ^{\omega}\left(b_{j}\right)$, i.e. $a=b$.

Since $a$ and $b$ were arbitrary points of $\beta$, the lemma is proved.
Now property $\left(T_{2}\right)$ immediately follows from Proposition 3.29 and Lemma A.7.

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## Further reading

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[^1]:    ${ }^{1}$ These groups are also called strongly relatively hyperbolic in order to distinguish them from weakly relatively hyperbolic groups in the sense of Farb.

[^2]:    ${ }^{2}$ We shall only use non-principal ultrafilters in this paper, so the word non-principal will be omitted.

