

# Capacity and Error Exponents of Stationary Point Processes with Additive Displacement Noise

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## Structure of the Lecture

- Capacity and Error Exponents for
  - Additive White Gaussian Noise **AWGN** Displacement of a Point Process
  - Additive Stationary Ergodic Noise **ASEN** Displacement of a Point Process
- Capacity and Error Exponents for
  - AWGN Channel with constraints
  - ASEN Channel with constraints

## AWGN DISPLACEMENT OF A POINT PROCESS

- $\mu^n$ : (simple) stationary ergodic point process on  $\mathbb{R}^n$ .
- $\lambda_n = e^{nR}$ : intensity of  $\mu^n$ .
- $\{T_n^k\}$ : points of  $\mu^n$  (**codewords**).
- $\mathbb{P}_n^0$ : Palm probability of  $\mu^n$ .
- $\{D_k^n\}$ : i.i.d. sequence of displacements, independent of  $\mu^n$ :

$$D_k^n = (D_k^n(1), \dots, D_k^n(n))$$

i.i.d. over the coordinates and  $\mathcal{N}(0, \sigma^2)$  (**noise**).

- $Z_k^n = T_k^n + D_k^n$ : displacement of the p.p. (**received messages**)

## AWGN UNDER MLE DECODING

■  $\{\mathcal{V}_k^n\}$ : Voronoi cell of  $T_k^n$  in  $\mu^n$ .

■ Error probability under MLE decoding:

$$p_e(n) = \mathbb{P}_n^0(Z_0^n \notin \mathcal{V}_0^n) = \mathbb{P}_n^0(D_0^n \notin \mathcal{V}_0^n) = \lim_{A \rightarrow \infty} \frac{\sum_k 1_{T_k^n \in B^n(0,A)} 1_{Z_k^n \notin \mathcal{V}_k^n}}{\sum_k 1_{T_k^n \in B^n(0,A)}}$$

■ Theorem 1-wgn Poltyrev [94]

1. If  $R < -\frac{1}{2} \log(2\pi e\sigma^2)$ , there exists a sequence of point processes  $\mu^n$  (e.g. Poisson) with intensity  $e^{nR}$  s.t.

$$p_e(n) \rightarrow 0, \quad n \rightarrow \infty$$

2. If  $R > -\frac{1}{2} \log(2\pi e\sigma^2)$ , for all sequences of point processes  $\mu^n$  with intensity  $e^{nR}$ ,

$$p_e(n) \rightarrow 1, \quad n \rightarrow \infty$$

## Proof of 2 [AB 08]

- $V_n(r)$ : volume of the  $n$ -ball of radius  $r$ .
- By monotonicity arguments, if  $|\mathcal{V}_0^n| = V_n(\sqrt{n}L_n)$ ,

$$\mathbb{P}_n^0(D_0^n \notin \mathcal{V}_0^n) \geq \mathbb{P}_n^0(D_0^n \notin B^n(0, \sqrt{n}L_n)) = \mathbb{P}_n^0\left(\frac{1}{n} \sum_{i=1}^n D_0^n(i)^2 \geq L_n^2\right)$$

- By the SLLN,

$$\mathbb{P}_n^0\left(\left|\frac{1}{n} \sum_{i=1}^n D_0^n(i)^2 - \sigma^2\right| \geq \epsilon\right) = \eta_\epsilon(n) \xrightarrow{n \rightarrow \infty} 0$$

- Hence

$$\begin{aligned} \mathbb{P}_n^0(D_0^n \notin \mathcal{V}_0^n) &\geq \mathbb{P}_n^0(\sigma^2 - \epsilon \geq L_n^2) - \eta_\epsilon(n) \\ &= 1 - \mathbb{P}_n^0(V_n(\sqrt{n(\sigma^2 - \epsilon)}) < |\mathcal{V}_0^n|) - \eta_\epsilon(n) \end{aligned}$$

Proof of 2 [AB 08] (continued)

– By Markov ineq.

$$\mathbb{P}_n^0(|\mathcal{V}_0^n|) > V_n(\sqrt{n(\sigma^2 - \epsilon)}) \leq \frac{\mathbb{E}_n^0(|\mathcal{V}_0^n|)}{V_n(\sqrt{n(\sigma^2 - \epsilon)})}$$

– By classical results on the Voronoi tessellation

$$\mathbb{E}_n^0(|\mathcal{V}_0^n|) = \frac{1}{\lambda_n} = e^{-nR}$$

– By classical results

$$V_n(r) = \frac{\pi^{\frac{n}{2}} r^n}{\Gamma(\frac{n}{2} + 1)} \sim \frac{\pi^{\frac{n}{2}} r^n}{\sqrt{\pi n} \left(\frac{n}{2e}\right)^{\frac{n}{2}}}$$

– Hence

$$\frac{\mathbb{E}_n^0(|\mathcal{V}_0^n|)}{V(\sqrt{n(\sigma^2 - \epsilon)})} \sim e^{-nR} e^{-\frac{n}{2} \log(2\pi e(\sigma^2 - \epsilon))} \xrightarrow{n \rightarrow \infty} 0$$

since  $R > -\frac{1}{2} \log(2\pi e\sigma^2)$ .

## AWN DISPLACEMENT OF A POINT PROCESS

- Same framework as above concerning the p.p.  $\mu^n$ .
- $\{D_k^n\}$ : i.i.d. sequence of centered displacements, independent of  $\mu^n$ .
- $D_k^n = (D_k^n(1), \dots, D_k^n(n))$ : i.i.d. coordinates with a density  $f$  with well defined **differential entropy**

$$h(D) = - \int_{\mathbb{R}} f(x) \log(f(x)) dx$$

- If  $D$  is  $\mathcal{N}(0, \sigma^2)$ ,  $h(D) = \frac{1}{2} \log(2\pi e\sigma^2)$

## AWN UNDER TYPICALITY DECODING

- **Aim:** For all  $n$ , find a partition  $\{\mathcal{C}_k^n\}$  of  $\mathbb{R}^n$ , jointly stationary with  $\mu^n$  such that

$$p_e(n) = \mathbb{P}_n^0(D_0^n \notin \mathcal{C}_0^n) \xrightarrow{n \rightarrow \infty} 0$$

- **Theorem 1-wn**

1. **If  $R < -h(D)$** , there exists a sequence of point processes  $\mu^n$  (e.g. Poisson) with intensity  $e^{nR}$  and a partition s.t.

$$p_e(n) \rightarrow 0, \quad n \rightarrow \infty$$

2. **If  $R > -h(D)$** , for all sequences of point processes  $\mu^n$  with intensity  $e^{nR}$ , for all jointly stationary partitions,

$$p_e(n) \rightarrow 1, \quad n \rightarrow \infty$$



## Proof of 1

- Let  $\mu^n$  be a Poisson p.p. with intensity  $e^{nR}$  with  $R + h(D) < 0$ .
- For all  $n$  and  $\delta$ , let

$$A_\delta^n = \left\{ (y(1), \dots, y(n)) \in \mathbb{R}^n : \left| -\frac{1}{n} \sum_{i=1}^n \log f(y(i)) - h(D) \right| < \delta \right\}$$

- By the SLLN,  $\mathbb{P}_0^n((D_0^n(1), \dots, D_0^n(n)) \in A_\delta^n) \xrightarrow{n \rightarrow \infty} 1$

Proof of 1 (continued)

■  $C_n^k$  contains

- all the locations  $x$  which belong to the set  $T_k^n + \mathcal{A}_\delta^n$  and to no other set of the form  $T_l^n + \mathcal{A}_\delta^n$ ;
- all the locations  $x$  that are ambiguous and which are closer to  $T_k^n$  than to any other point;
- all the locations which are uncovered and which are closer to  $T_k^n$  than to any other point.

Proof of 1 (continued)

■ Let  $\tilde{\mu}^n = \mu^n - \epsilon_0$  under  $\mathbb{P}_n^0$

■ Basic bound:

$$\mathbb{P}_n^0(D_0^n \notin \mathcal{C}_0^n) \leq \mathbb{P}_n^0(D_0^n \notin A_\delta^n) + \mathbb{P}_n^0(D_0^n \in A_\delta^n, \tilde{\mu}^n(D_0^n - A_\delta^n) > 0)$$

■ The first term tends to 0 because of the SLLN.

■ For the second, use **Slivnyak's theorem** to bound it from above by

$$\begin{aligned} \mathbb{P}(\mu^n(D_0^n - A_\delta^n) > 0) &\leq \mathbb{E}(\mu^n(D_0^n - A_\delta^n)) \\ &= \mathbb{E}(\mu^n(-A_\delta^n)) = e^{nR} |A_\delta^n| \end{aligned}$$

Proof of 1 (continued)

■ But

$$\begin{aligned}
 1 &\geq \mathbb{P}(D_0^n \in A_\delta^n) = \int_{A_\delta^n} \prod_{i=1}^n f(y(i)) dy = \int_{A_\delta^n} e^{n \frac{1}{n} \sum_{i=1}^n \log(f(y(i)))} dy \\
 &\geq \int_{A_\delta^n} e^{n(-h(D)-\delta)} dy = e^{-n(h(D)+\delta)} |A_\delta^n|
 \end{aligned}$$

so that

$$|A_\delta^n| \leq e^{n(h(D)+\delta)}$$

■ Hence the second term is bounded above by

$$e^{nR} e^{n(h(D)+\delta)} \xrightarrow{n \rightarrow \infty} 0$$

since  $R + h(D) < 0$ .

## EXAMPLES

- Examples of  $A_\delta^n$  sets for white noise with variance  $\sigma^2$ :
  - **Gaussian case:** difference of two concentric  $L_2$   $n$ -balls of radius approximately  $\sqrt{n}\sigma$ .
  - **Symmetric exponential case:** difference of two concentric  $L_1$   $n$ -balls of radius approximately  $n\frac{\sigma}{\sqrt{2}}$ .
  - **Uniform case:**  $n$ -cube of side  $2\sqrt{3}\sigma$ .

## ADDITIVE STATIONARY AND ERGODIC DISPLACEMENT OF A POINT PROCESS

### ■ Setting

- Same framework as above concerning the p.p.  $\mu^n$ .
- $\{\mathcal{D}\}_k$ : i.i.d. sequence of centered, stationary and ergodic displacement processes, independent of the p.p.s.
- For all  $n$ ,  $D_k^n = (\mathcal{D}_k(1), \dots, \mathcal{D}_k(n))$  with density  $f^n$  on  $\mathbb{R}^n$ .

ADDITIVE STATIONARY AND ERGODIC DISPLACEMENT OF A POINT PROCESS (*continued*)

■  $\mathcal{D}$ : with well defined differential entropy rate  $h(\mathcal{D})$

–  $H(D^n)$  differential entropy of  $D^n = (\mathcal{D}(1), \dots, \mathcal{D}(n))$

–  $h(\mathcal{D})$  defined by

$$h(\mathcal{D}) = \lim_{n \rightarrow \infty} \frac{1}{n} H(D^n) = \lim_{n \rightarrow \infty} -\frac{1}{n} \int_{\mathbb{R}^n} \ln(f^n(x^n)) f^n(x^n) dx^n.$$

■ Typicality sets

$$A_\delta^n = \left\{ x^n = (x(1), \dots, x(n)) \in \mathbb{R}^n : \left| -\frac{1}{n} \log(f^n(x^n)) - h(\mathcal{D}) \right| < \delta \right\}.$$

## ASEN UNDER TYPICALITY DECODING

### ■ Theorem 1-sen

1. If  $R < -h(\mathcal{D})$ , there exists a sequence of point processes  $\mu^n$  (e.g. Poisson) with intensity  $e^{nR}$  and a partition s.t.

$$p_e(n) \rightarrow 0, \quad n \rightarrow \infty$$

2. If  $R > -h(\mathcal{D})$ , for all sequences of point processes  $\mu^n$  with intensity  $e^{nR}$ , for all jointly stationary partitions,

$$p_e(n) \rightarrow 1, \quad n \rightarrow \infty$$

### ■ Proof: similar to that of the i.i.d. case.



## COLORED GAUSSIAN NOISE EXAMPLE

- $\{\mathcal{D}\}$  regular stationary and ergodic Gaussian process with spectral density  $g(\beta)$ , covariance matrix  $\Gamma_n$ :

$$\mathbb{E}[\mathcal{D}(i)\mathcal{D}(j)] = \Gamma_n(i, j) = r(|i - j|)$$

and

$$\mathbb{E}[\mathcal{D}(0)\mathcal{D}(k)] = \frac{1}{2\pi} \int_0^{2\pi} e^{ik\beta} g(\beta) d\beta.$$

COLORED GAUSSIAN NOISE EXAMPLE (*continued*)

– **Differential entropy rate:**

$$h(\mathcal{D}) = \frac{1}{2} \ln \left( 2e\pi \exp \left( \frac{1}{2\pi} \int_{-\pi}^{\pi} \ln(g(\beta)) d\beta \right) \right).$$

– **Typicality sets:**

$$A_{\delta}^n = \left| \frac{1}{n} (x^n)^t \Gamma_n^{-1} x^n - 1 + d(n) \right| < 2\delta,$$

with

$$d(n) = \frac{1}{n} \ln(\text{Det}(\Gamma_n)) - \left( \frac{1}{2\pi} \int_{-\pi}^{\pi} \ln(g(\beta)) d\beta \right) \xrightarrow{n \rightarrow \infty} 0.$$

## MARKOV NOISE EXAMPLE

- Assume that  $\{\mathcal{D}_n\}$  is a stationary Markov chain with values in  $\mathbb{R}$ , stationary distribution  $\pi(x)dx$ , mean 0 and with transition kernel  $P(dy | x) = p(y | x)dy$ , where  $p(y | x)$  is a density on  $\mathbb{R}$ .
- If  $(\mathcal{D}_1, \mathcal{D}_2)$  has a well defined differential entropy then

$$h(\mathcal{D}) = - \int_{\mathbb{R}^2} \pi(x)p(y | x) \ln(p(y | x)) dx dy = h(\mathcal{D}_2 | \mathcal{D}_1) ,$$

with  $h(U|V)$  the conditional entropy of  $V$  given  $U$ .

## REPRESENTATION OF AWGN MLE ERROR PROB.

■ **Theorem 2-wgn.** Assume WGN and MLE,

– If  $\mu^n$  is stationary and ergodic, the probability of success is

$$p_s(n) = \int_{r \geq 0} \int_{\vec{v} \in \mathbb{S}^{n-1}} \mathbb{P}_0^n(\mu^n(B_n(r\vec{v}, r)) = 0) \frac{g_\sigma^n(r)}{A_{n-1}} d\vec{v} dr ,$$

with  $A_{n-1}$ , the area of the  $n$ -sphere of radius 1:  $\mathbb{S}^{n-1}(1)$ , and

$$g_\sigma^n(r) = 1_{r>0} e^{-\frac{r^2}{2\sigma^2}} \frac{1}{2^{n/2}} \frac{r^{n-1}}{\sigma^n} \frac{2}{\Gamma(n/2)} .$$

– If  $\mu^n$  is **Poisson**,

$$p_s(n) = \int_0^\infty e^{-\lambda_n V_B^n(r)} g_\sigma^n(r) dr = \int_0^\infty e^{-\lambda_n V_B^n(r\sigma)} g_1^n(r) dr ,$$

with  $V_B^n(r)$  the volume of the ball  $B^n(0, r)$ .

## PROOF

- $x \in \mathcal{V}_0^n$  iff the open ball  $B^n(x, |x|)$  has no point of  $\mu^n$ :

$$p_s(n) = \mathbb{P}_0^n(D_0^n \in \mathcal{V}_0^n) = \mathbb{P}_0^n(\mu^n(B^n(D_0^n, |D_0^n|)) = 0).$$

- $|D_0^n|$  has for density  $g_\sigma^n(x) = g_1^n(x/\sigma)/\sigma$  on  $\mathbb{R}^+$ .
- Given that  $|D_0^n| = r$ , the angle is uniform on  $\mathbb{S}_{n-1}$ .
- In the Poisson case, from Slyvniak's theorem,

$$\mathbb{P}_0^n(\mu^n(B^n(r\vec{v}, r)) = 0) = \mathbb{P}(\mu^n(B^n(r\vec{v}, r)) = 0) = e^{-\lambda_n V_B^n(r)}.$$

## REPRESENTATION OF ASEN MLE ERROR PROB.

- **Stun-discrepancy** between  $s^n \in \mathbb{R}^n$  and  $t^n \in \mathbb{R}^n$ :

$$\mathbb{D}(s^n, t^n) = -\frac{1}{n} \ln(f^n(s^n - t^n)).$$

- **Key observation:**

$$\mathbb{D}(x^n, T_k^n) > \mathbb{D}(x^n, 0), \quad \forall k \neq 0 \quad \Leftrightarrow \quad (\mu^n - \epsilon_0)(F(x^n)) = 0$$

$$\begin{aligned} F(x^n) &= \{y^n \in \mathbb{R}^n \text{ s.t. } \mathbb{D}(x^n, y^n) \leq \mathbb{D}(x^n, 0)\} \\ &= \{y^n \in \mathbb{R}^n \text{ s.t. } -\frac{1}{n} \ln(f^n(x^n - y^n)) \leq -\frac{1}{n} \ln(f^n(x^n))\}. \end{aligned}$$

- $\text{Vol}(F(x^n))$  only depends on  $\mathbb{D}(x^n, 0) = -\frac{1}{n} \ln(f^n(x^n))$ . Let

$$V_f^n(r) = \text{Vol} \{y^n \in \mathbb{R}^n \text{ s.t. } -\frac{1}{n} \ln(f^n(y^n)) \leq r\}.$$

REPRESENTATION OF ASEN MLE ERROR PROB. (*continued*)

■ **Theorem 2-sen.** Assume MLE,

- If  $\mu^n$  is stationary and ergodic, the probability of success under MLE is

$$p_s(n) \geq \int_{x^n \in \mathbb{R}^n} \mathbb{P}_0^n((\mu^n - \epsilon_0)(F(x^n)) = 0) f^n(x^n) dx^n .$$

- If  $\mu^n$  is **Poisson**, then

$$p_s(n) \geq \int_{r \in \mathbb{R}} \exp(-\lambda_n V_f^n(r)) \rho^n(dr) ,$$

where  $\rho^n(dr)$  is the law of the random variable  $-\frac{1}{n} \ln(f^n(D^n))$ .

REPRESENTATION OF ASEN MLE ERROR PROB. ( <i>continued</i> )
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■ Terminology in relation with

$$\int_{r \in \mathbb{R}} \exp(-\lambda_n V_f^n(r)) \rho^n(dr),$$

- Normalized entropy density of  $D^n$ : **RV**  $-\frac{1}{n} \ln(f^n(D^n))$
- Entropy spectrum of  $D^n$ : law  $\rho^n(dr)$  on  $\mathbb{R}$ :
- Stun level sets of  $D^n$ :

$$\mathcal{S}_f^n(r) = \{y^n \in \mathbb{R}^n \text{ s.t. } -\frac{1}{n} \ln(f^n(y^n)) \leq r\}$$

- Stun level volume for  $r$ : volume  $V_f^n(r)$  of  $\mathcal{S}_f^n(r)$ .



## REPRESENTATION OF ASEN MLE ERROR PROB. (continued)

■ The **Stun cell**  $\mathcal{L}_k^n(\mathcal{D})$  of point  $T_k^n$ :

$$\begin{aligned} \mathcal{L}_k^n(\mathcal{D}) = & \{x^n \text{ s.t. } \mathbb{D}(x^n, T_k^n) < \inf_{l \neq k} \mathbb{D}(x^n, T_l^n)\} \\ & \cup \{x^n \text{ s.t. } \mathbb{D}(x^n, T_k^n) = \mathbb{D}(x^n, T_l^n) \text{ for some } l \neq k\} \cap \mathcal{V}_k^n. \end{aligned}$$

- The locations  $x^n$  with a **stun discrepancy** (w.r.t.  $f^n$ ) to  $T_k^n$  smaller than that to any other point;
- The locations  $x^n$  with an **ambiguous discrepancy** (this includes the case where  $\mathbb{D}(x^n, T_k^n) = \infty$  for all  $k$ ) which are closer to  $T_k^n$  than to all other point.

These cells form a **decomposition of the Euclidean space**.

## ERROR EXPONENTS

- $\mathcal{D}$ , displacement process;
  - $\mu^n$ , stationary and ergodic point process with intensity  $e^{nR}$ ,  $R = -h(\mathcal{D}) - \ln(\alpha)$ ,  $\alpha > 1$ ;
  - $\mathcal{C}^n = \{\mathcal{C}_k^n\}_k$  jointly stationary partition.
- Associated error probability:

$$p_e^{pp}(n, \mu^n, \mathcal{C}^n, \alpha, \mathcal{D})$$

- Optimal error:

$$p_{e,opt}^{pp}(n, \alpha, \mathcal{D}) = \inf_{\mu^n, \mathcal{C}^n} p_e^{pp}(n, \mu^n, \mathcal{C}^n, \alpha, \mathcal{D})$$

**ERROR EXPONENTS** (*continued*)■ **Error exponents:**

$$\bar{\eta}(\alpha, \mathcal{D}) = \limsup_n -\frac{1}{n} \log p_{e,opt}^{pp}(n, \alpha, \mathcal{D}) ,$$

$$\underline{\eta}(\alpha, \mathcal{D}) = \liminf_n -\frac{1}{n} \log p_{e,opt}^{pp}(n, \alpha, \mathcal{D}) ,$$

ERROR EXPONENTS (continued)

- Each particular point process sequence  $\mu = \{\mu^n\}$  and partition  $\mathcal{C} = \{\mathcal{C}^n\}$  provides a lower bound on  $\underline{\eta}(\alpha, \mathcal{D})$ :

$$\underline{\pi}(\mu, \mathcal{C}, \alpha, \mathcal{D}) = \liminf_n -\frac{1}{n} \log p_e^{pp}(n, \mu^n, \mathcal{C}^n, \alpha, \mathcal{D})$$

- Main focus in what follows:

$$\underline{\eta}(\alpha, \mathcal{D}) \geq \underline{\pi}(\mathbf{Poisson}, \mathcal{L}(\mathcal{D}), \alpha, \mathcal{D}) \quad (\text{random coding e-e})$$

## POISSON LOWER BOUNDS ON WGN ERROR EXPONENTS

**Theorem 3-wgn-Poisson [AB 08]** In the  $\mathcal{D}$ =AWGN case,

**1. For  $1 < \alpha < \sqrt{2}$ :**  $\underline{\pi}(\text{Poisson}, \mathcal{L}(\mathcal{D}), \alpha, \mathcal{D}) = \frac{\alpha^2}{2} - \frac{1}{2} - \log(\alpha)$

**2. For  $\alpha > \sqrt{2}$ :**  $\underline{\pi}(\text{Poisson}, \mathcal{L}(\mathcal{D}), \alpha, \mathcal{D}) = \frac{1}{2} - \log(2) + \log(\alpha)$

■ Obtained from the Poisson–Voronoi case with

$$R = -\frac{1}{2} \log(2\pi e \sigma^2 \alpha^2), \quad \alpha > 1$$

## Idea of Proof

- From Palm representation of  $p_e(n, \alpha)$ :

$$p_e(n, \alpha) = \int_0^{\infty} \left(1 - e^{-\lambda_n V_n(r)}\right) g_n^\sigma(r) dr$$

with  $g_n^\sigma(v\sigma\sqrt{n}) = e^{-n\left(\frac{v^2}{2} - \frac{1}{2} - \log(v) + o(1)\right)}$

- Since  $\lambda_n = e^{\frac{n}{2} \log 2\pi e \sigma^2 \alpha^2}$ ,  $1 - e^{-\lambda_n V_n(v\sigma\sqrt{n})} = e^{-n\left((\log \alpha - \log v)^+ + o(1)\right)}$  and

$$p_e(n, \alpha) = \int_0^{\infty} e^{-n\left(\frac{v^2}{2} - \frac{1}{2} - \log v + (\log \alpha - \log v)^+ + o(1)\right)} dv$$

- The result follows from the minimization of the function

$$\frac{v^2}{2} - \frac{1}{2} - \log v + (\log \alpha - \log v)^+.$$

## POISSON LOWER BOUNDS ON SEN ERROR EXPONENTS

### ■ Setting Stationary ergodic noise $\mathcal{D}$

- $H(D^n)$  differential entropy of  $D^n = (\mathcal{D}_1, \dots, \mathcal{D}_n)$
- $h(\mathcal{D})$  differential entropy rate of  $\{\mathcal{D}\}$ .

We have

$$\begin{aligned}
 h(\mathcal{D}) &= \lim_{n \rightarrow \infty} \frac{1}{n} H(D^n) = \lim_{n \rightarrow \infty} -\frac{1}{n} \int_{\mathbb{R}^n} \ln(f^n(x^n)) f^n(x^n) dx^n \\
 &= \lim_{n \rightarrow \infty} \frac{1}{n} \int_{\mathbb{R}} r \rho^n(dr).
 \end{aligned}$$

■ **SEN Assumption:**

The family of measures  $\rho^n(\cdot)$  satisfies an LDP with good rate function  $I(x)$

■ **Example 1: Gärtner-Ellis:** if  $\{-\ln(f^n(D^n))\}$  satisfies the conditions of the Gärtner-Ellis Theorem, namely if the limit

$$\lim_{n \rightarrow \infty} \frac{1}{n} \ln \left( \mathbb{E} \left( (f^n(D^n))^{-\theta} \right) \right) = G(\theta)$$

exists and satisfies appropriate continuity properties, then the family of measures  $\rho^n(\cdot)$  satisfies a LDP with good rate function

$$I(x) = \sup_{\theta} (\theta x - G(\theta)).$$



POISSON LOWER BOUNDS ON SEN ERROR EXPONENTS (*continued*)

■ **Example 2: LDP on empirical measures: wn case**

- $S$  the support of  $f$
- $K(\tau \parallel \phi)$  relative entropy (or Kullback-Leibler divergence) of the probability law  $\tau(dx)$  w.r.t. the probability law  $\phi(dx) = f(x)dx$ :

$$K(\tau \parallel \phi) = \int_{\mathbb{R}} \ln(r(x)) r(x) f(x) dx,$$

with  $r = \frac{d\tau}{d\phi}$ . This is  $\infty$  unless  $\tau$  is absolutely continuous w.r.t.  $\phi$ , i.e.  $\tau$  admits a density  $g$  such that  $g(y) = 0$  when  $f(y) = 0$  for a.a.  $y$ . In this case,

$$K(\tau \parallel \phi) = \int_S \ln\left(\frac{g(x)}{f(x)}\right) g(x) dx.$$

POISSON LOWER BOUNDS ON SEN ERROR EXPONENTS (*continued*)

- From **Sanov's theorem**, the empirical measures

$$\nu^n = -\frac{1}{n} \sum_{i=1}^n \epsilon_{\mathcal{D}_i}$$

are  $\mathbb{M}_1(S)$ -valued random variables which satisfy an LDP with good and convex rate function  $K(\cdot \parallel \phi)$

- From the **contraction principle**, if the function  $x \rightarrow \ln(f(x))$  from  $S$  to  $\mathbb{R}$  is continuous and bounded, then the family of measures  $\rho_{\mathcal{D}}^n$  on  $\mathbb{R}$  satisfies an LDP with good and convex rate function

$$\begin{aligned} I(u) &= \inf_{\tau \in \mathbb{M}_1(S): -\int_S \ln(f(x)) \tau(dx) = u} K(\tau \parallel \phi) \\ &= u - \sup_{\tau \in \mathbb{M}_1(S): K(\tau \parallel \phi) + h(\tau) = u} h(\tau). \end{aligned}$$

POISSON LOWER BOUNDS ON SEN ERROR EXPONENTS (*continued*)

- **Example 3: LDP on empirical measures: Markov case**
- $S \subseteq \mathbb{R}^2$ : support of the measure on  $\mathbb{R}^2$  with density  $a(x)p(y|x)$ .
- Under technical conditions, the empirical measures

$$-\frac{1}{n} \sum_{i=1}^n \epsilon_{\mathcal{D}_i, \mathcal{D}_{i+1}}$$

satisfy an LDP on  $\mathbb{M}_1(S)$  with good and convex rate function

$$I(\tau) = \begin{cases} K(\tau || \tau_1 \otimes P) & \text{if } \tau \in \text{Sym}\mathbb{M}_1(S) \\ \infty & \text{otherwise.} \end{cases}$$

- $K$ : Kullback-Leibler divergence of measures on  $\mathbb{R}^2$
- $\tau_1$ : marginals of  $\tau$ ;  $\tau_1 \otimes P$ : the measure  $\tau_1(dx)P(x, y)dy$ .

POISSON LOWER BOUNDS ON SEN ERROR EXPONENTS (*continued*)

- If  $(x, y) \rightarrow \ln(p(y | x))$  from  $S$  to  $\mathbb{R}$  is continuous and bounded, Then  $\rho_{\mathcal{D}}^n$  satisfies an LDP with good and convex rate function

$$\begin{aligned}
 I(u) &= \inf_{\tau \in \text{SymM}_1(S): \int_{\pi(x)p(y|x)>0} \ln(p(y|x))\tau(dx dy)=u} K(\tau || \tau_1 \otimes P) \\
 &= u - \sup_{\tau \in \text{SymM}_1(S): K(\tau || \tau_1 \otimes P) + h(\tau_2 | \tau_1) = u} h(\tau_2 | \tau_1),
 \end{aligned}$$

provided the last function is convex and admits an essentially smooth Fenchel-Legendre transform

POISSON LOWER BOUNDS ON SEN ERROR EXPONENTS (*continued*)

■ **Lemma 2** [Volume Exponent]

Assume that  $\rho^n$  satisfies a LDP with good rate function  $I$ .  
Then the **stun level volumes** verify:

$$\sup_{s < u} (s - I(s)) \leq \liminf_{n \rightarrow \infty} \frac{1}{n} \ln(V_{\mathcal{D}}^n(u)) \leq \limsup_{n \rightarrow \infty} \frac{1}{n} \ln(V_{\mathcal{D}}^n(u)) \leq \sup_{s \leq u} (s - I(s)).$$

The function

$$J(u) = \sup_{s \leq u} (s - I(s)),$$

the **volume exponent**, is upper semicontinuous.

POISSON LOWER BOUNDS ON SEN ERROR EXPONENTS (*continued*)

**Theorem 3-sen-Poisson** [Main Result]

Under the SEN assumption (LDP) on  $\mathcal{D}$ ,

$$\underline{\pi}(\mathbf{Poisson}, \mathcal{L}(\mathcal{D}), \alpha, \mathcal{D}) \geq \inf_r \{F(r) + I(r)\} ,$$

where

–  $I(r)$  is the rate function of the noise entropy spectrum  $\rho^n$

–  $F(r)$  is

$$F(r) = (\ln(\alpha) + h(\mathcal{D}) - J(r))^+ ,$$

with

$$J(r) = \sup_{s \leq r} (s - I(s))$$

the noise volume exponent.

## IDEA OF PROOF

- Use the **Palm representation** and the bound

$$1 - e^{-\lambda_n V_f^n(r)} \leq \min(1, \lambda_n V_f^n(r))$$

to write

$$p_e(n) \leq \int_{r>0} e^{-n\phi_n(r)} \rho^n(dr),$$

with

$$\phi_n(r) = \left( \ln(\alpha) + h(\mathcal{X}) - \frac{1}{n} \ln(V_f^n(r)) \right)^+.$$

- Leverage the LDP on  $\rho^n$ :

Use the **Laplace–Varadhan integral lemma**

(more precisely an extension of this lemma in **Varadhan 84**).

## SYMMETRIC EXPONENTIAL WN EXAMPLE

### ■ LDP

$$\mathbb{E} (f(X)^{-\theta}) = (\sqrt{2}\sigma)^\theta \mathbb{E} \left( \exp \left( \theta \frac{|X|\sqrt{2}}{\sigma} \right) \right) = (\sqrt{2}\sigma)^\theta \frac{1}{1-\theta}.$$

So, the LDP assumption holds with the good rate function:

$$I(x) = \sup_{\theta} \left( \theta x - \theta \ln(\sqrt{2}\sigma) + \ln(1-\theta) \right) = x - h(X) - \ln(x - \ln(\sqrt{2}\sigma))$$

### ■ Error exponent

$$\underline{\pi}(\mathbf{Poisson}, \mathcal{L}(\mathcal{D}), \alpha, \mathcal{D}) \geq \begin{cases} \alpha - 1 - \ln \alpha & \text{if } 1 \leq \alpha < \sqrt{2} \\ \sqrt{2} - 1 - \ln 2 + \ln \alpha & \text{if } \sqrt{2} \leq \alpha. \end{cases}$$



## COLORED GAUSSIAN NOISE EXAMPLE

### ■ LDP

From the Grenander–Szegő Theorem, the Gärtner-Ellis Theorem holds with

$$G(\theta) = \frac{\theta}{2} \ln(2\pi) - \frac{1}{2} \ln(1 - \theta) + \frac{\theta}{2} \ln \left( \frac{1}{2\pi} \int_{-\pi}^{\pi} \ln(g(\beta)) d\beta \right),$$

when  $\theta < 1$  and  $G(\theta) = \infty$  for  $\theta > 1$ . So, the LDP assumption holds with the good rate function

$$I(x) = x - h(\mathcal{D}) - 1/2 \ln(2x - \ln(2\pi\sigma^2)),$$

### ■ Error exponent:

$$\underline{\pi}(\alpha, \mathcal{D}) \geq \begin{cases} \frac{\alpha^2}{2} - \frac{1}{2} - \ln \alpha & \text{if } 1 \leq \alpha < \sqrt{2} \\ \frac{1}{2} - \ln 2 + \ln \alpha & \text{if } \sqrt{2} \leq \alpha < \infty \end{cases}.$$

## OTHER EXAMPLES STUDIED

- Uniform white noise
- Markov noise

## AWGN CAPACITY AND ERROR EXPONENTS WITH CONSTRAINTS

- $M, n$  positive integers.
- $\mathcal{C}$  an  $(M, n)$  code:

$$\begin{bmatrix} t_1(1) & t_1(2) & \cdots & t_1(n) \\ \vdots & & & \vdots \\ t_M(1) & t_M(2) & \cdots & t_M(n) \end{bmatrix}$$

- Rate of the code:  $\frac{1}{n} \ln(M)$
- Power constraint:  $\frac{1}{n} \sum_{i=1}^n t_m(i)^2 \leq P$  for all  $m$ ;  
i.e. all codewords belong to  $B^n(0, \sqrt{nP})$ .

AWGN CAPACITY AND ERROR EXPONENTS WITH CONSTRAINTS (*continued*)

- $W$  uniform on  $\{1, \dots, M\}$ .
- Transmitter sends  $(T(1), \dots, T(n)) = (t_W(1), \dots, t_W(n))$
- The channel adds an independent noise  $(D(1), \dots, D(n))$  where coordinates  $D(i)$  are i.i.d.  $\mathcal{N}(0, \sigma^2)$ .
- The receiver gets  $(Z(1), \dots, Z(n))$  with  $Z(i) = T(i) + D(i)$ .
- MLE decoding:

$$\widehat{W} = \operatorname{argmin}_m \sum_{i=1}^n (Z(i) - t_m(i))^2$$

and

$$p_e(\mathcal{C}) = P(\widehat{W} \neq W)$$

**AWGN CAPACITY AND ERROR EXPONENTS WITH CONSTRAINTS** (*continued*)■ **Shannon capacity of the AWGN channel**

$$C = \frac{1}{2} \log \left( 1 + \frac{P}{\sigma^2} \right)$$

– **If  $R < C$** , there exists a sequence of  $(e^{nR}, n)$  codes  $\mathcal{C}_n$  s.t.

$$p_e(\mathcal{C}_n) \rightarrow 0, \quad n \rightarrow \infty$$

– **If  $R > C$** , for all sequences of  $(e^{nR}, n)$  codes  $\mathcal{C}_n$

$$\liminf_n p_e(\mathcal{C}_n) = 1, \quad n \rightarrow \infty$$

AWGN CAPACITY AND ERROR EXPONENTS WITH CONSTRAINTS ( <i>continued</i> )
---

■ **Error exponents for the AWGN channel**

- $P_{e,opt}(n, R, A)$ : infimum of  $P_e(\mathcal{C})$  over all codebooks in  $\mathbb{R}^n$  of rate at least  $R$  when the signal-to-noise ratio is  $A^2 = P/\sigma^2$ .

$$\mathcal{E}(n, R, A) = -\frac{1}{n} \log P_{e,opt}(n, R, A) .$$

- **Error exponent:**

$$\bar{\mathcal{E}}(R, A) = \limsup_n \mathcal{E}(n, R, A),$$

$$\underline{\mathcal{E}}(R, A) = \liminf_n \mathcal{E}(n, R, A).$$

## ASEN CAPACITY WITH CONSTRAINTS

- Same setting but with a stationary and ergodic noise  $\mathcal{D}$
- Shannon capacity of the ASEN channel

$$C_P(\mathcal{D}) = \lim_{n \rightarrow \infty} \frac{1}{n} \sup_{T^n, \mathbb{E}(\sum_{i=1}^n |T_i|^2) < nP} I(T^n, T^n + D^n),$$

where the supremum bears on all distribution functions for  $T^n \in \mathbb{R}^n$  such that  $\mathbb{E}(\sum_{i=1}^n |T_i|^2) < nP$ .

## RELATION BETWEEN CAPACITY WITH AND WITHOUT CONSTRAINTS

- Additive stationary and ergodic noise  $\mathcal{D}$  with
  - Differential entropy rate:  $h(\mathcal{D})$
  - Variance:  $\sigma^2 = \mathbb{E}(\mathcal{D}(0)^2)$
  - Capacity:  $c(\mathcal{D}) = -h(\mathcal{D})$

- **Lemma [Shannon]**

Under the above assumptions

$$\frac{1}{2} \ln(2\pi eP) + c(\mathcal{D}) \leq C_P(\mathcal{D}) \leq \frac{1}{2} \ln(2\pi e(P + \sigma^2)) + c(\mathcal{D})$$

and

$$C_P(\mathcal{D}) = \frac{1}{2} \ln(2\pi eP) + c(\mathcal{D}) + O(1/P), \quad P \rightarrow \infty.$$



## ASEN ERROR EXPONENTS WITH CONSTRAINTS

- As above:

$$\mathcal{E}(n, R, P, \mathcal{D}) = -\frac{1}{n} \log P_{e,opt}(n, R, P, \mathcal{D}) .$$

- Error exponent:

$$\begin{aligned} \bar{\mathcal{E}}(R, P, \mathcal{D}) &= \limsup_n \mathcal{E}(n, R, P, \mathcal{D}), \\ \underline{\mathcal{E}}(R, P, \mathcal{D}) &= \liminf_n \mathcal{E}(n, R, P, \mathcal{D}). \end{aligned}$$

## RELATION BETWEEN ERROR EXPONENTS WITH AND WITHOUT CONSTRAINTS

- $\underline{\mathcal{E}}(R, P, \mathcal{D})$ : e-e for rate  $R$ , power constraint  $P$ , noise  $\mathcal{D}$ .
- $\underline{\pi}(\mu, \mathcal{L}(\mathcal{D}), \alpha, \mathcal{D})$ : e-e for  $\mu$  with intensity  $e^{nR}$ ,  
 $R = -h(\mathcal{D}) - \ln(\alpha)$ , noise  $\mathcal{D}$  and MLE.

- **Theorem** Under the above assumptions,  
 for all  $\mu$  and  $\mathcal{C}$  with  $\alpha > 1$ , for all  $P > 0$ ,

$$\underline{\mathcal{E}}\left(\frac{1}{2}\ln(2\pi eP) - h(\mathcal{D}) - \ln(\alpha), P, \mathcal{D}\right) \geq \underline{\pi}(\mu, \mathcal{L}(\mathcal{D}), \alpha, \mathcal{D}).$$

- Matches Shannon's random error exponent and expurgated exponent in AWGN

## IDEA OF PROOF

■ Consider as codebook the restriction of the p.p.  $\mu^n$  of intensity  $e^{n(-h(\mathcal{D})-\ln(\alpha))}$  in the ball of radius  $\sqrt{nP}$ .

■ The mean number of codewords is  $e^{nR+o(1)}$  with

$$R = -h(\mathcal{D}) - \ln(\alpha) + \frac{1}{2} \ln(2\pi eP).$$

■ Compare the error in this codebook and in the stationary point process.

IDEA OF PROOF (continued)

- For all  $n$ ,

$$p_e^{pp}(n, \mu^n, \mathcal{C}^n, \alpha, \mathcal{D}) = \frac{\mathbb{E}^n \left( \sum_k \mathbf{s.t.} \ T_k^n \in B^n(0, \sqrt{nP}) \ p_{e,k} \right)}{e^{-nh(\mathcal{D})} e^{-n \ln(\alpha)} V_B^n(\sqrt{nP})},$$

with  $p_{e,k}$  the probability that  $T_k^n + D_k^n \notin \mathcal{C}_k^n$  given  $\{T_l^n, \mathcal{C}_l^n\}_l$ .

## IDEA OF PROOF (continued)

■ Hence, for all  $\gamma > 0$ ,

$$p_e^{pp}(n, \mu^n, \mathcal{C}^n, \alpha, \mathcal{D})$$

$$\geq \frac{\mathbb{E}^n \sum_{k \text{ s.t. } T_k^n \in B^n(0, \sqrt{nP})} p_{e,k} 1_{\mu^n(B^n(0, \sqrt{nP})) \geq (2\pi eP)^{\frac{n}{2}} e^{-nh(\mathcal{D})} e^{-n \ln(\alpha + \gamma)}}}{e^{-nh(\mathcal{D})} e^{-n \ln(\alpha)} V_B^n(\sqrt{nP})}$$

$$\geq \mathbb{P}^n \left( \mu^n(B^n(0, \sqrt{nP})) \geq (2\pi eP)^{\frac{n}{2}} e^{-nh(\mathcal{D})} e^{-n \ln(\alpha + \gamma)} \right)$$

$$p_{e,opt}(n, \frac{1}{2} \ln(2\pi eP) - h(\mathcal{D}) - \ln(\alpha + \gamma), P, \mathcal{D}) e^{-n \ln(\alpha + \gamma)} e^{n \ln(\alpha)} \frac{(2\pi eP)^{\frac{n}{2}}}{V_B^n(\sqrt{nP})}.$$

## IDEA OF PROOF (continued)

Hence

$$\begin{aligned}
 & -\frac{1}{n} \ln (p_e^{pp}(n, \mu^n, \mathcal{C}^n, \alpha, \mathcal{D})) \\
 & \leq -\frac{1}{n} \ln \left( p_{e,opt}(n, \frac{1}{2} \ln(2\pi eP) - h(\mathcal{D}) - \ln(\alpha + \gamma), P, \mathcal{D}) \right) \\
 & \quad -\frac{1}{n} \ln \left( \mathbb{P}^n \left( \mu^n(B^n(0, \sqrt{nP})) \geq (2\pi eP)^{\frac{n}{2}} e^{-nh(\mathcal{D})} e^{-n(\alpha+\gamma)} \right) \right) \\
 & \quad - \ln(\alpha) + \ln(\alpha + \gamma) - \frac{1}{n} \ln \left( \frac{(2\pi eP)^{\frac{n}{2}}}{V_B^n(\sqrt{nP})} \right) .
 \end{aligned}$$

**Proof concluded when taking**

- a **liminf** in  $n$ ;
- a **lim** in  $\gamma$ .

## CONCLUSION, FUTURE WORK

Bridge between  
Information Theory and Stochastic Geometry

New viewpoint on error exponents  
New stochastic geometry problems in high dimension

Other point processes to be investigated:  
Matérn, Gibbs, Determinantal, etc.

## MATERN POINT PROCESSES FOR WGN

- Built from a Poisson processes  $\mu_n$  of rate  $\lambda_n = e^{nR}$  where  $R = \frac{1}{2} \ln \frac{1}{2\pi e \alpha^2 \sigma^2}$

- Exclusion radius  $(\alpha - \epsilon)\sigma\sqrt{n}$

- The intensity of this Matérn p.p. is

$$\tilde{\lambda}_n = \lambda_n e^{-\lambda_n V_B^n((\alpha - \epsilon)\sigma\sqrt{n})}$$

- We have

$$\frac{\tilde{\lambda}_n}{\lambda_n} \xrightarrow{n \rightarrow \infty} 1.$$



## MATERN LOWER BOUNDS ON WGN ERROR EXPONENTS

$$\underline{\eta}(\alpha, \mathcal{D}) \geq \underline{\pi}(\text{Poisson}, \mathcal{L}(\mathcal{D}), \alpha, \mathcal{D}) \quad (\text{random coding e-e})$$

$$\underline{\eta}(\alpha, \mathcal{D}) \geq \underline{\pi}(\text{Matern}, \mathcal{L}(\mathcal{D}), \alpha, \mathcal{D}) \quad (\text{expurgated e-e})$$

**Theorem 3-wgn-Matérn [AB 08]** In the  $\mathcal{D}=\text{AWGN}$  case

**3 For  $\alpha > 2$ :**  $\underline{\pi}(\text{Matérn}, \mathcal{L}(\mathcal{D}), \alpha, \mathcal{D}) \geq \frac{\alpha^2}{8}$

■ Matches Poltyrev's expurgated error exponent **Poltyrev [94]**

## MATERN POINT PROCESSES FOR SEN

- Assume for simplicity that  $f^n(x^n) = f^n(-x^n)$ .
- If two points  $S$  and  $T$  of the Poisson point process  $\mu^n$  are such that  $\mathbb{D}(T, S) < \xi$ , then  $T$  is discarded.
- The surviving points form the **Matérn- $\mathcal{D}$ - $\xi$**  point process  $\hat{\mu}^n$ .
- **Lemma** The probability of error for the Matérn- $\mathcal{D}$ - $\xi$  point process satisfies the bound

$$p_e(n) \leq \int_{x^n \in \mathbb{R}^n} \min \left( 1, \lambda_n \int_{y^n \in \mathbb{R}^n} 1_{\mathbb{D}(y^n, 0) \geq \xi} 1_{\mathbb{D}(x^n, y^n) \leq \mathbb{D}(x^n, 0)} dy^n \right) f^n(x^n) dx^n.$$

## SYMMETRIC EXPONENTIAL EXAMPLE

■ For  $\mathcal{D}$  symmetric exponential

$$\underline{\pi}(\mathbf{Mat}, \mathcal{L}(\mathcal{D}), \alpha, \mathcal{D}) \geq \begin{cases} \alpha - \ln(\alpha) - 1 & \text{for } \alpha \leq 2 \\ \ln(\alpha) + 1 - 2 \ln(2) & \text{for } 2 \leq \alpha \leq 4 \\ \frac{\alpha}{2} - \ln(\alpha) - 1 + 2 \ln(2) & \text{for } \alpha \geq 4. \end{cases}$$

## VARADHAN'S LEMMA

- Theorem 2.3 in **Varadhan 84**
- $P_\epsilon$  satisfies a LDP with good rate function  $I(\cdot)$ .
- $F_\epsilon$  non negative and such that

$$\liminf_{\epsilon \rightarrow 0, y \rightarrow x} F_\epsilon(y) \geq F(x), \quad \forall x$$

with  $F$  lower semicontinuous.

- Then

$$\liminf_{\epsilon \rightarrow 0} -\epsilon \ln \left( \int e^{-\frac{F_\epsilon(x)}{\epsilon}} P_\epsilon(dx) \right) \geq \inf \{ F(x) + I(x) \}.$$

## Szego's Theorem

- Under technical conditions, the eigenvalues  $\tau(i, n)$ ,  $i = 0, \dots, n - 1$  of the covariance matrix  $\Gamma^n$  are such that

$$\lim \frac{1}{n} \sum_{i=0}^n F(\tau(i, n)) = \frac{1}{2\pi} \int_0^{2\pi} F(f(\beta)) d\beta.$$

- Key relations

$$r_k = \frac{1}{2\pi} \int_0^{2\pi} e^{-ik\beta} g(\beta) d\beta.$$

$$g(\beta) = \sum_{k=-\infty}^{\infty} t_k e^{ik\beta}, \quad \beta \in [0, 2\pi].$$