# Applications of Matrix Functions Part III: Quantum Chemistry 

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## Prologue

The main purpose of this lecture is to present a rigorous mathematical theory for a class of methods, called $O(N)$ methods, that are being developed by computational physicists and chemists for the solution of the electronic structure problem, which is fundamental to quantum chemistry, solid state physics, biology, etc.

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The theory is based on general results on the decay in the entries of functions of sparse matrices. In particular, one needs to study the asymptotic behavior of the off-diagonal matrix elements for $N \rightarrow \infty$.

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The theory is based on general results on the decay in the entries of functions of sparse matrices. In particular, one needs to study the asymptotic behavior of the off-diagonal matrix elements for $N \rightarrow \infty$.

While this work is primarily theoretical, the theory can be used to construct better algorithms for electronic structure computations. Some of our techniques are already used in a code called FreeON developed by a group headed by Matt Challacombe at Los Alamos National Laboratory.

## References

This lecture is based in parts on the results contained in the following papers:
M. Benzi and G. H. Golub, Bounds for the entries of matrix functions with applications to preconditioning, BIT, 39 (1999), pp. 417-438.
M. Benzi and N. Razouk, Decay bounds and $O(n)$ algorithms for approximating functions of sparse matrices, Electr. Trans. Numer. Anal., 28 (2007), pp. 16-39.
M. Benzi, P. Boito and N. Razouk, Decay properties of spectral projectors with applications to electronic structure, SIAM Review, 55 (2013), pp. 3-64.

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The problem amounts to computing the ground state (smallest eigenvalue and corresponding eigenfunction) of the many-body quantum-mechanical Hamiltonian (Schrödinger operator), $\mathcal{H}$.

Variationally, we want to minimize the Rayleigh quotient:

$$
E_{0}=\min _{\Psi \neq 0} \frac{\langle\mathcal{H} \Psi, \Psi\rangle}{\langle\Psi, \Psi\rangle} \quad \text { and } \quad \Psi_{0}=\operatorname{argmin}_{\Psi \neq 0} \frac{\langle\mathcal{H} \Psi, \Psi\rangle}{\langle\Psi, \Psi\rangle}
$$

where $\langle\cdot, \cdot\rangle$ denotes the $L^{2}$ inner product.

## The Electronic Structure Problem



## The Electronic Structure Problem

In the Born-Oppenheimer approximation, the many-body Hamiltonian (in atomic units) is given by

$$
\mathcal{H}=\sum_{i=1}^{N}\left(-\frac{1}{2} \Delta_{i}-\sum_{j=1}^{M} \frac{Z_{j}}{\left|\mathbf{x}_{i}-\mathbf{r}_{j}\right|}+\sum_{j \neq i}^{N} \frac{1}{\left|\mathbf{x}_{i}-\mathbf{x}_{j}\right|}\right)
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where $N=$ number of electrons and $M=$ number of nuclei in the system.
The operator $\mathcal{H}$ acts on a suitable subspace $D(\mathcal{H}) \subset L^{2}\left(\mathbb{R}^{3 N}\right)$, the antisymmetrized tensor product of $N$ copies of $H^{1}\left(\mathbb{R}^{3}\right)$ :

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This is because electrons are Fermions and therefore subject to Pauli's Exclusion Principle. Hence, the wavefunction must be antisymmetric:

$$
\Psi\left(\mathrm{x}_{1}, \ldots, \mathrm{x}_{i}, \ldots, \mathrm{x}_{j}, \ldots, \mathrm{x}_{N}\right)=-\Psi\left(\mathrm{x}_{1}, \ldots, \mathrm{x}_{j}, \ldots, \mathrm{x}_{i}, \ldots, \mathrm{x}_{N}\right)
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NOTE: To simplify notation, spin is ignored here.

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- Hybrid methods


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■ Density Functional Theory (e.g., Kohn-Sham; Nobel Prize, 1998)

- Hybrid methods

In these approximations the original, linear eigenproblem $H \Psi=E \Psi$ for the many-electrons Hamiltonian is replaced by a nonlinear one-particle eigenproblem of the form

$$
F\left(\psi_{i}\right)=\lambda_{i} \psi_{i}, \quad\left\langle\psi_{i}, \psi_{j}\right\rangle=\delta_{i j}, \quad 1 \leq i, j \leq N
$$

where $\lambda_{1} \leq \lambda_{2} \leq \cdots \leq \lambda_{N}$. This problem is nonlinear because the operator $F$ depends nonlinearly on the $\psi_{i}$.

## The Electronic Structure Problem

Roughly speaking, in DFT the idea is to consider a single electron moving in the electric field generated by the nuclei and by some average distribution of the other electrons. Starting with an initial guess of the charge density, a potential is formed and the corresponding one-particle eigenproblem is solved; the resulting charge density is used to define the new potential, and so on until the charge density no longer changes appreciably.

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More formally, DFT reformulates the problem so that the unknown function is the electronic density

$$
\rho(\mathbf{x})=N \int_{\mathbb{R}^{3(N-1)}}\left|\Psi\left(\mathbf{x}, \mathbf{x}_{2}, \ldots, \mathbf{x}_{N}\right)\right|^{2} \mathrm{~d}_{2} \cdots \mathrm{~d}_{N}
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a scalar field on $\mathbb{R}^{3}$.

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a scalar field on $\mathbb{R}^{3}$.
The function $\rho$ minimizes a certain functional, the form of which is not known explicitly.

## The Electronic Structure Problem

Various forms of the density functional have been proposed, the most successful being the Kohn-Sham model:

$$
I_{K S}(\rho)=\inf \left\{T_{K S}+\int_{\mathbb{R}^{3}} \rho V \mathrm{~d} \mathbf{x}+\frac{1}{2} \int_{\mathbb{R}^{3}} \int_{\mathbb{R}^{3}} \frac{\rho(\mathbf{x}) \rho(\mathbf{y})}{|\mathbf{x}-\mathbf{y}|} \mathrm{d} \mathbf{x d} \mathbf{y}+E_{x c}(\rho)\right\}
$$

where $\rho(\mathbf{x})=\sum_{i=1}^{N}\left|\psi_{i}(\mathbf{x})\right|^{2}, T_{K S}=\frac{1}{2} \sum_{i=1}^{N} \int_{\mathbb{R}^{3}}\left|\nabla \psi_{i}\right|^{2} \mathrm{~d} \mathbf{x}$ is the kinetic energy term, $V$ denotes the Coulomb potential, and $E_{x c}$ denotes the exchange term that takes into account the interaction between electrons. The infimum above is taken over all functions $\psi_{i} \in H^{1}\left(\mathbb{R}^{3}\right)$ such that $\left\langle\psi_{i}, \psi_{j}\right\rangle=\delta_{i j}$, where $1 \leq i, j \leq N$ and $\sum_{i=1}^{N}\left|\psi_{i}(\mathbf{x})\right|^{2}=\rho$.

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This $I_{K S}$ is minimized with respect to $\rho$. Note that $\rho$, being the electron density, must satisfy $\rho>0$ and $\int_{\mathbb{R}^{3}} \rho \mathrm{dx}=N$.

## The Electronic Structure Problem

The Euler-Lagrange equations for this variational problem are the Kohn-Sham equations:

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F(\rho) \psi_{i}=\lambda_{i} \psi_{i}, \quad\left\langle\psi_{i}, \psi_{j}\right\rangle=\delta_{i j} \quad(1 \leq i, j \leq N)
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with

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where $U$ denotes a (complicated) potential, and $\rho=\sum_{i=1}^{N}\left|\psi_{i}(\mathbf{x})\right|^{2}$.
Hence, the original intractable linear eigenvalue problem for the many-body Hamiltonian is reduced to a tractable nonlinear eigenvalue problem for a single-particle Hamiltonian.

## The Electronic Structure Problem

The nonlinear problem can be solved by a 'self-consistent field' (SCF) iteration, leading to a sequence of linear eigenproblems

$$
F^{(k)} \psi_{i}^{(k)}=\lambda_{i}^{(k)} \psi_{i}^{(k)}, \quad\left\langle\psi_{i}^{(k)}, \psi_{j}^{(k)}\right\rangle=\delta_{i j}, \quad k=1,2, \ldots
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$(1 \leq i, j \leq N)$, where each $F^{(k)}=-\frac{1}{2} \Delta+U^{(k)}$ is a one-electron linearized Hamiltonian:

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Solution of each of the (discretized) linear eigenproblems above leads to a typical $O\left(N^{3}\right)$ cost per SCF iteration. However, the actual eigenpairs $\left(\psi_{i}^{(k)}, \lambda_{i}^{(k)}\right)$ are unnecessary, and diagonalization of the one-particle Hamiltonians can be avoided!

## The Electronic Structure Problem

The individual eigenfunctions $\psi_{i}$ are not needed. All one needs is the orthogonal projector $P$ onto the occupied subspace

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V_{o c c}=\operatorname{span}\left\{\psi_{1}, \ldots, \psi_{N}\right\}
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Higher moments of observables can also be computed once $P$ is known.

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## Density matrices

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In practice, the operators are replaced by matrices by Rayleigh-Ritz projection onto a finite-dimensional subspace spanned by a set of basis functions $\left\{\phi_{i}\right\}_{i=1}^{N_{b}}$, where $N_{b}$ is a multiple of $N$. Typically, $N=C \cdot N_{e}$ where $C \geq 2$ is a moderate integer when linear combinations of GTOs (Gaussian-type orbitals) are used.

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In some codes, plane waves are used. Finite difference and finite element ( "real space") methods, while also used, are less popular.

## Density matrices

The Gramian matrix $S=\left(S_{i j}\right)$ where $S_{i j}=\left\langle\phi_{i}, \phi_{j}\right\rangle$ is called the overlap matrix in electronic structure. It is dense, but its entries fall off very rapidly for increasing separation. In the case of GTOs:

$$
\left|S_{i j}\right| \approx \mathrm{e}^{-|i-j|^{2}}, \quad 1 \leq i, j \leq N_{b}
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Neglecting tiny entries leads to banded overlap matrices.

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Trasforming the Hamiltonian $H$ to an orthogonal basis means performing a congruence trasformation: $\hat{H}=Z H Z^{T}$, where $Z$ is such that $Z Z^{T}=S^{-1}$. Common choices for $Z$ are the inverse Cholesky factor of $S$ or the inverse square root $S^{-1 / 2}$. This can be done efficiently (AINV algorithm).

## Example: Hamiltonian for $\mathrm{C}_{52} \mathrm{H}_{106}$, AO basis.



## Example: Hamiltonian for $\mathrm{C}_{52} \mathrm{H}_{106}$, orthogonal basis



## Density matrices

Summarizing, in electronic structure theory we need to compute $P$, the spectral projector onto the subspace spanned by the $N$ lowest eigenfunctions of $H$ (occupied states):

$$
P=\psi_{1} \otimes \psi_{1}+\cdots+\psi_{N} \otimes \psi_{N}=\left|\psi_{1}\right\rangle\left\langle\psi_{1}\right|+\cdots+\left|\psi_{N}\right\rangle\left\langle\psi_{N}\right|
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$$

where $N$ is the number of electrons and $H \psi_{i}=\lambda_{i} \psi_{i}, i=1, \ldots, N$.
Note that we can write $P=f(H)$ where $f$ is the step function

$$
f(x)=\left\{\begin{array}{lll}
1 & \text { if } & x<\mu \\
\frac{1}{2} & \text { if } & x=\mu \\
0 & \text { if } & x>\mu
\end{array}\right.
$$

with $\lambda_{N}<\mu<\lambda_{N+1}$ ( $\mu$ is the "Fermi level").

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This property implies that in the thermodynamic limit ( $N \rightarrow \infty$ while keeping the particle density constant) the number of entries $P_{i j}$ with $\left|P_{i j}\right|>\varepsilon$ grows only linearly with $N$, for any prescribed $\varepsilon>0$.

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For insulators and semiconductors, this makes $O(N)$ methods possible.

## Example: Density matrix for $\mathrm{C}_{52} H_{106}$, orthogonal basis



Example: Density matrix for $H=-\frac{1}{2} \Delta+V$, random $V$, finite differences (2D lattice), $N=10$


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1 Chebyshev expansion: $P=f(H) \approx \frac{c_{0}}{2}+\sum_{k=1}^{n} c_{k} T_{k}(H)$
2 Rational expansions based on contour integration:

$$
P=\frac{1}{2 \pi i} \int_{\Gamma}(z I-H)^{-1} \mathrm{~d} z \approx \sum_{k=1}^{q} w_{k}\left(z_{k} I-H\right)^{-1}
$$

3 Density matrix minimization:
$\operatorname{Tr}(P H)=\min , \quad$ subject to $P=P^{*}=P^{2} \quad$ and $\quad \operatorname{rank}(P)=N$
4 Etc. (see C. Le Bris, Acta Numerica, 2005; Bowler \& Miyazaki, 2011)

## $O(N)$ methods

The fact that $P$ is very nearly sparse allows the development of $O(N)$ approximation methods. Popular methods include
1 Chebyshev expansion: $P=f(H) \approx \frac{c_{0}}{2}+\sum_{k=1}^{n} c_{k} T_{k}(H)$
2 Rational expansions based on contour integration:

$$
P=\frac{1}{2 \pi i} \int_{\Gamma}(z I-H)^{-1} d z \approx \sum_{k=1}^{q} w_{k}\left(z_{k} I-H\right)^{-1}
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All these methods can achieve $O(N)$ scaling by exploiting "sparsity."

## Overview

## 1 The electronic structure problem

2 Density matrices
$3 O(N)$ methods

4 A mathematical foundation for $O(N)$ methods

## $5 O(N)$ approximation of functions of sparse matrices

6 A few numerical experiments
7 Some open problems

## A mathematical foundation for $O(N)$ methods

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The main tool used in our analysis, besides linear algebra, is classical approximation theory.

## A mathematical foundation for $O(N)$ methods

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We call a sequence of discrete Hamiltonians a sequence of matrices $\left\{H_{N}\right\}$ of order $N_{b}$, such that

1 The matrices $H_{N}$ have spectra uniformly bounded w.r.t. $N$ : up to shifting and scaling, we can assume $\sigma\left(H_{N}\right) \subset[-1,1]$ for all $N$.

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These assumptions model the fact that the Hamiltonians have finite interaction range, which remains bounded in the thermodynamic limit $N \rightarrow \infty$.

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Next, let $H$ be a Hamiltonian of order $N_{b}$. Denote the eigenvalues of $H$ as

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-1 \leq \lambda_{1} \leq \ldots \leq \lambda_{N}<\lambda_{N+1} \leq \ldots \leq \lambda_{N_{b}} \leq 1
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The spectral gap is then $\gamma_{N}=\lambda_{N+1}-\lambda_{N}$. In quantum chemistry this is known as the HOMO-LUMO gap, in solid state physics as the band gap.

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$2 \inf _{N} \gamma_{N}=0$.
The first case corresponds to insulators and semiconductors, the second one to metallic systems.

## Example: Spectrum of the Hamiltonian for $\mathrm{C}_{52} \mathrm{H}_{106}$.



## Exponential decay in the density matrix for gapped systems

## Theorem

Let $\left\{H_{N}\right\}$ be a sequence of discrete Hamiltonians of size $N_{b}=C \cdot N$, with $C$ constant and $N \rightarrow \infty$. Let $P_{N}$ denote the spectral projector onto the $N$ occupied states associated with $H_{N}$. If there exists $\gamma>0$ such that the gaps $\gamma_{N} \geq \gamma$ for all $N$, then there exists constants $K$ and $\alpha$ such that

$$
\left|\left[P_{N}\right]_{i j}\right| \leq K \mathrm{e}^{-\alpha d_{N}(i, j)} \quad(1 \leq i, j \leq N)
$$

where $d_{N}(i, j)$ denotes the geodetic distance between node $i$ and node $j$ in the graph $G_{N}$ associated with $H_{N}$. The constants $K$ and $\alpha$ depend only on the gap $\gamma$ (not on $N$ ) and are easily computable.

Note: The graph $G_{N}=\left(V_{N}, E_{N}\right)$ is the graph with $N_{b}$ vertices such that there is an edge $(i, j) \in E_{N}$ if and only if $\left[H_{N}\right]_{i j} \neq 0$.

## Exponential decay in the density matrix for gapped systems

Sketch of the proof. There are a few steps involved:
1 Recall that $P_{N}=f\left(H_{N}\right)$ where $f$ is a step function. For gapped systems, $f$ can be approximated arbitrarily well in the sup norm by an analytic function, for example, the Fermi-Dirac function $f_{F D}$.

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2 Use best approximation polynomials to approximate $f_{F D}$ (in the sup norm).
3 By Bernstein's Theorem, for any analytic function $g$ defined on a neighborhood of $[-1,1]$, the best $n$th degree polynomial error satisfies

$$
E_{n}(g):=\left\|p_{n}-g\right\|_{\infty} \leq c \cdot e^{-\xi n}
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for suitable constants $c$ and $\xi$ which depend only on $g$.

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for suitable constants $c$ and $\xi$, which depend only on $g$.
4 Apply Bernstein's result to $g=f_{F D}$, compute the decay constants, and use the spectral theorem to go from scalars to matrices.

## Analytic approximations of the step function

If $\mu$ (the "Fermi level") is in the gap, $\lambda_{N}<\mu<\lambda_{N+1}$, the step function can be approximated by the Fermi-Dirac function: $f(x)=\lim _{\beta \rightarrow \infty} f_{F D}(x)$, where

$$
f_{F D}(x)=\frac{1}{1+\mathrm{e}^{\beta(x-\mu)}}
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Here $\beta$ can be interpreted as an inverse temperature.
Other approximations of the step function are also in use, such as

$$
\begin{gathered}
f(x)=\lim _{\beta \rightarrow \infty}\left[\frac{1}{2}+\frac{1}{\pi} \tan ^{-1}(\beta \pi(x-\mu))\right], \\
f(x)=\lim _{\beta \rightarrow \infty} \operatorname{erfc}(-\beta(x-\mu)),
\end{gathered}
$$

or

$$
f(x)=\lim _{\beta \rightarrow \infty}[1+\tanh (\beta((x-\mu))]
$$

## Fermi-Dirac approximation of step function $(\mu=0)$



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In practice, $\gamma$ is either known experimentally or can be estimated by computing the eigenvalues of a moderate-size Hamiltonian.

## Dependence of decay rate on the spectral gap and on the temperature

In the physics literature, there has been some controversy on the precise dependence of the inverse correlation length $\alpha$ in the decay estimate

$$
\left|\left[P_{N}\right]_{i j}\right| \leq c \cdot \mathrm{e}^{-\alpha d_{N}(i, j)}
$$

on the spectral gap $\gamma$ (for insulators) and on the electronic temperature $T$ (for metals at positive temperature).

Our theory gives the following results:
$1 \alpha=c \gamma+O\left(\gamma^{3}\right)$, for $\gamma \rightarrow 0+$ and $T=0$;
$2 \alpha=\pi \kappa_{B} T+O\left(T^{3}\right)$, for $T \rightarrow 0+$ (indep. of $\gamma$ ).
These asymptotics are in agreement with experimental and numerical results, as well as with physical intuition.

## Decay bounds for the Fermi-Dirac approximation

Assume that $H$ is $m$-banded and has spectrum in $[-1,1]$, then

$$
\left|\left[\left(I+\mathrm{e}^{\beta(H-\mu /)}\right)^{-1}\right]_{i j}\right| \leq K \mathrm{e}^{-\alpha|i-j|} \equiv K \lambda^{\frac{|i-j|}{m}} .
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Note that $K, \lambda$ depend only on $\beta$. In turn, $\beta$ depends on $\gamma$ and on the desired accuracy.
We have

$$
\gamma \rightarrow 0^{+} \quad \Rightarrow \quad \lambda \rightarrow 1^{-}
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and

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\gamma \rightarrow 1 \Rightarrow \lambda \rightarrow 0.872
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We choose $\beta$ and $\hat{m}$ so as to guarantee an accuracy $\|P-f(H)\|_{2}<10^{-6}$.

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We choose $\beta$ and $\hat{m}$ so as to guarantee an accuracy $\|P-f(H)\|_{2}<10^{-6}$. We can regard $\gamma^{-1}$ as the condition number of the problem.

## Computed bandwidth for approximations of $P$

$$
f(x)=\frac{1}{1+e^{\beta(x-\mu)}}
$$



## Density matrix, $N_{e}=30$, relative gap $\gamma=0.6$



## Density matrix, $N_{e}=30$, relative gap $\gamma=0.2$



## Density matrix, $N_{e}=30$, relative gap $\gamma=0.0001$



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## Decay in analytic functions of sparse matrices

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Sparsity pattern of a $2 n \times 2 n$ Hamiltonian matrix $A$ and decay in $\mathrm{e}^{A}$.



Note that $\mathrm{e}^{A}$ is symplectic.

## Decay for logarithm of a sparse matrix

Sparsity pattern of $H=$ mesh3e1 (from NASA) and decay in $\log (H)$.



Here $H$ is symmetric positive definite.

## Sufficient conditions for $O(N)$ approximation of $f(H)$

- Let $\left\{H_{N}\right\}$ be a sequence of $N \times N$ Hermitian matrices such that there is a closed interval $\mathcal{I}$ with the property that $\sigma\left(H_{N}\right) \subset \mathcal{I}$ for all $N$


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■ Generalizations to non-normal matrices are possible, e.g., using Crouzeix's theorem.

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## Approximation of $f(H)$ by Chebyshev polynomials

Algorithm (Goedecker \& Colombo, 1994) © More

- We compute approximations of $f(H)$ using Chebyshev polynomials
- The degree of the polynomial can be estimated a priori
- The coefficients of the polynomial can be pre-computed (indep. of $N$ )
- Estimates for the extreme eigenvalues of $H$ are required
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## Cost

This method is multiplication-rich; the matrices are kept sparse throughout the computation, hence $O(N)$ arithmetic and storage requirements. Matrix polynomials can be efficiently evaluated by the Paterson-Stockmeyer algorithm.

## Chebyshev expansion of Fermi-Dirac function

The bandwidth was computed prior to the calculation to be $\approx 20$; here $H$ is tridiagonal (1D Anderson model).

Table: Results for $f(x)=\frac{1}{1+\mathbf{e}^{(\beta(x-\mu))}}$

|  | $\mu=2, \beta=2.13$ |  | $\mu=0.5, \beta=1.84$ |  |  |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| $N$ | error | $k$ | $\tilde{m}$ | error | $k$ | $\tilde{m}$ |
| 100 | $9 e-06$ | 18 | 20 | $6 e-06$ | 18 | 22 |
| 200 | $4 e-06$ | 19 | 20 | $9 e-06$ | 18 | 22 |
| 300 | $4 e-06$ | 19 | 20 | $5 e-06$ | 20 | 22 |
| 400 | $6 e-06$ | 19 | 20 | $8 e-06$ | 20 | 22 |
| 500 | $8 e-06$ | 19 | 20 | $8 e-06$ | 20 | 22 |

## Computation of Fermi-Dirac function



The $O(N)$ behavior of Chebyshev's approximation to the Fermi-Dirac function $f(H)=(\exp (\beta(H-\mu I))+I)^{-1}$.

## Chebyshev expansion of entropy-like function

Some results for $H=H_{N}$ tridiagonal, SPD, $f(x)=x \log (x)$

|  | $H \log (H)$ | $\operatorname{Tr}[H \log (H)]$ |  |  |
| :--- | :--- | :--- | :--- | :--- |
| $N$ | rel. error | error | $\hat{m}$ | $k$ |
| 100 | $5 e-07$ | $3 e-04$ | 20 | 9 |
| 200 | $6 e-07$ | $8 e-04$ | 20 | 9 |
| 300 | $1 e-07$ | $3 e-04$ | 20 | 10 |
| 500 | $2 e-07$ | $5 e-04$ | 20 | 10 |

In the Table, $\hat{m}$ is the estimated bandwidth and $k$ is the number of terms in the Chebyshev expansion. Note the $O(N)$ behavior in terms of cost.

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## Summary

- 'Gapped' systems, like insulators, exhibit strong localization

■ Localization in $P=f(H)$, when strong enough, can lead to fast approximation algorithms
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- Extensions to non-Hermitian case possible (applications??)


## Overview

## 1 The electronic structure problem

2 Density matrices
$3 O(N)$ methods

4 A mathematical foundation for $O(N)$ methods
$5 O(N)$ approximation of functions of sparse matrices

6 A few numerical experiments
7 Some open problems

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An excellent introduction: C. Le Bris, Computational Chemistry from the Perspective of Numerical Analysis, Acta Numerica 14 (2005), 363-444.

## Localization in spectral projectors: small relative gap



Rank-one spectral projector for $H=H^{*}$ tridiagonal. Relative gap $\gamma=10^{-3}$. Note the slow decay and oscillatory behavior of $\left|P_{i j}\right|$.

## Localization in spectral projectors: large relative gap



Rank-one spectral projector for $H=H^{*}$ tridiagonal. Relative gap $\gamma=0.5$.

## Chebyshev approximation

For $H$ with $\sigma(H) \subset[-1,1]$ the Chebyshev polynomials are given by

$$
T_{k+1}(H)=2 H T_{k}(H)-T_{k-1}(H), \quad T_{1}(H)=H, \quad T_{0}(H)=I .
$$

Then $f(H)$ can be represented in a series of the form

$$
f(H)=\sum_{k=0}^{\infty} c_{k} T_{k}(H)
$$

The coefficients of the expansion are given by

$$
c_{k} \approx \frac{2}{M} \sum_{j=1}^{M} f\left(\cos \left(\theta_{j}\right)\right) \cos \left((k-1) \theta_{j}\right)
$$

where $\theta_{j}=\pi\left(j-\frac{1}{2}\right) / M$.

The $N$-independence of the error

The $m$ th truncation error without dropping can be written as

$$
\left\|e_{m}(H)\right\|=\left\|f(H)-\sum_{k=0}^{m} c_{k} T_{k}(H)\right\| .
$$

For $x$ in $[-1,1]$ we have that $\left|T_{k}(x)\right| \leq 1$ for $k=1,2, \ldots$. Then

$$
\left\|e_{m}(H)\right\|=\left\|\sum_{k=m+1}^{\infty} c_{k} T_{k}(H)\right\| \leq \sum_{k=m+1}^{\infty}\left|c_{k}\right|
$$

## A Theorem of Bernstein

The set of Faber polynomials can be used to obtain a uniform approximation to an analytic function $f$ with a sequence of polynomials of bounded degree, i.e.,

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\left|f(z)-\Pi_{N}(z)\right|<c q^{N} \quad(0<q<1)
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for all $z \in F$, where $c$ and $q$ depend on the analytic properties of $f$.

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## Example - Disk

If the region is a disk of radius $\rho$ centered at $z_{0}$, then for any function $f$ analytic on the disk of radius $\rho / q$ centered at $z_{0}$, where $0<q<1$, there exists a polynomial $\Pi_{N}$ of degree at most $N$ and a positive constant $c$ such that

$$
\left|f(z)-\Pi_{N}(z)\right|<c q^{N},
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for all $z \in F$.

